

**IPTRONIK** 

## Manual

# IPEmotion PlugIn CAETEC dataLog



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All specifications are based on the technical status of March 20, 2019. We reserve the right to make any changes required to technically improve the equipment.

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## Contents

1	Forew	vord	12
2	<b>Confi</b> 2.1 2.2	guration Symbols	<b>13</b> 13 13
3	<b>Produ</b> 3.1	User interface 3.2.1 Menu bar 3.2.2 "File" menu and important basic settings for working with the PlugIn 3.2.3 Working with the Ribbon 3.2.4 "Signals" tab 3.2.5 Quick Access Toolbar	<b>14</b> 14 14 14 15 18 18 19 30 33 34 34
4	<b>Settin</b> 4.1 4.2	<b>g up a logger system</b> Choosing a logger-system	<b>35</b> 35 36
		4.2.1       The measurement task tree         4.2.2       The details area         4.2.3       The grid area	36 37 40
	4.3	4.3.1 Column chooser	40 41 42
	4.4 4.5	<ul> <li>Changing the logger system with the <i>change into</i>-command</li> <li>Open / Import / Export the datalog.ccmc and other PlugIn specific files</li> <li>4.5.1 Importing the datalog.ccmc via system import</li> <li>4.5.2 Importing and exporting the datalog.ccmc after system creation</li> <li>4.5.3 Ignore errors and warnings at export</li> <li>4.5.4 Opening the datalog.ccmc via the "Open" dialog</li> <li>4.5.5 Opening the datalog.ccmc via commandline</li> </ul>	44 45 46 47 48 49 50
	4.6	Online communication with the logger4.6.1Communication settings4.6.2Online functions4.6.3Licence information	51 51 53 54 55
	4.7 4.8	Changing a system's default tree elementsSub configurations4.8.1Creating a sub configuration	56 58 59 60
Cł	nange	s and errors excepted.	2

CONTENTS



		4.8.3 4.8.4	4.8.2.1The *.isz file604.8.2.2The *.cfginclude file60Adding new tree elements to an existingg sub configurations60Unlinking tree elements from existing sub configurations60	) )
5	Project 5.1 5.2 5.3 5.4 5.5 5.6	Assigni Tree el Grid a Details	gs62g project parameters62ing a template of project parameters63ements for Project settings64rea for Project settings64area for Project settings64project parameters as variables in CAETEC dataLog PlugIn64	2 3 4 5
6	Signa 6.1	6.1.1 6.1.2 6.1.3 6.1.4	hannels       67         Storage method       68         Adding CAN channels       69         CAN settings       70         6.1.3.1       General       71         6.1.3.2       CAN       72         6.1.3.3       Wake On CAN       72         6.1.3.4       Hardware (Channel number)       75         Virtual CAN settings       80         6.1.4.1       General       80         6.1.4.2       Hardware (Channel number)       81	
	6.2	6.1.5 CAN si 6.2.1 6.2.2 6.2.3 6.2.4	CAN channel Bus statistic86.1.5.1Adding Bus statistics6.1.5.2Bus statistic signalsgnals83Storage method83Importing CAN signals83Import properties84Signal properties866.2.4.1Tree elements for CAN signals6.2.4.2Grid area for CAN signals6.2.4.3Details area for CAN signals	123335337
	6.3	6.2.5 CCP/X 6.3.1 6.3.2	6.2.4.5       Defails died for CAN signals       94         Manual messages / Manual signals       94         6.2.5.1       Adding manual messages and signals       94         6.2.5.2       Tree elementes for manual messages       95         6.2.5.3       Grid area for manual messages       96         6.2.5.4       Details area for manual messages (defining a manual signal)       97         CP signals       98         Storage method       98         Importing CCP/XCP signals       99	4 5 7 8
	6.4	6.3.3 6.3.4	Import properties102Signal properties1026.3.4.1Tree elements for CCP/XCP signals6.3.4.2Grid area for CCP/XCP signals6.3.4.3Details area for CCP/XCP signals1026.3.4.3Details area for CCP/XCP signals104105106107108109109109109100109 <t< td=""><td>2 3 3 5 5</td></t<>	2 3 3 5 5



	6.4.1	Storage method	114
	6.4.2	Importing UDS signals	114
	6.4.3		116
	6.4.4	Signal properties	117
		6.4.4.1 Tree elements for UDS signals	117
		6.4.4.2 Grid area for UDS signals	118
		6.4.4.3 Details area for UDS signals	118
6.5	OBD s	ignals	123
	6.5.1	Storage method	123
	6.5.2	Adding the OBD signals interface	123
	6.5.3		123
	6.5.4	Signal properties	124
		6.5.4.1 Tree elements for OBD signals	124
		6.5.4.2 Grid area for OBD signals	124
		6.5.4.3 Details area for OBD signals	125
6.6	Gatev	ways	132
	6.6.1	Ádding a gateway	132
	6.6.2	Adding an ID filter	132
	6.6.3	Gateway settings	133
		6.6.3.1 Tree elements for Gateways	133
		6.6.3.2 Grid area for Gateways	133
		6.6.3.3 Details area for Gateways	133
	6.6.4	ID filter settings	134
6.7	Runsto		135
0.7	6.7.1	Add Runstate	135
	6.7.2	Tree elements for Runstate	136
	6.7.3	Grid area for Runstate	136
	6.7.4	Details area for Runstate	137
	6.7.5	Export Runstate	137
6.8			138
0.0	6.8.1		138
	6.8.2	Storage method       Adding ETH channels	139
	6.8.3	ETH settings	140
	0.0.0	6.8.3.1 General	140
		6.8.3.2 LAN	141
		6.8.3.3 Settings	141
	6.8.4	ETH Feature interface (FlexRay satellite on ETH)	141
	0.0.4	6.8.4.1 Adding the ETH Feature interface	142
			142
		$\mathbf{O}$	143
4.0		6.8.4.3 Tree elements for a FlexRay satellite	
6.9	ETH sig		144
	6.9.1		144
	6.9.2	Importing ETH signals	144
		6.9.2.1 Importing Fibex files (SOME/IP)	144
		6.9.2.2 Import properties for SOME/IP	145
		6.9.2.3 Importing A2L files (XCPonUDP)	146
		6.9.2.4 IP settings when Importing A2L files (XCPonUDP)	148
	(	6.9.2.5 Import properties for XCPonUDP	148
	6.9.3	Signal properties	149
		6.9.3.1 Signal properties for SOME/IP	149

Changes and errors excepted.



		6.9.3.2 Signal properties for XCPonUDP
6.10	LIN ch	annels
	6.10.1	Storage method
	6.10.2	Adding LIN channels
	6.10.3	LIN settings
		6.10.3.1 General 153
		6.10.3.2 LIN
		6.10.3.3 Wake On LIN
		6.10.3.4 Hardware (Channel number)
	6.10.4	LIN channel Bus statistic
6.11	LIN sig	nals
	6.11.1	Storage method
	6.11.2	Importing LIN signals
	6.11.3	Import properties
	6.11.4	Signal properties
	01111	6.11.4.1 Tree elements for LIN signals
		6.11.4.2 Grid area for LIN signals
		6.11.4.3 Details area for LIN signals
6.12	FloyDa	y channels
0.12	6.12.1	Storage method
	6.12.2	Adding FlexRay channels
	6.12.2	-
	0.12.3	FlexRay settings
		6.12.3.1 General
		6.12.3.2 Wake On FlexRay
	( 10 (	6.12.3.3 Hardware (Channel number)
	6.12.4	FlexRay channel Bus statistic
		6.12.4.1 Adding Bus statistics
(		6.12.4.2 Bus statistic signals
6.13		y signals
	6.13.1	Storage method
	6.13.2	Importing FlexRay signals
		6.13.2.1 Importing Autosar and Fibex files 172
		6.13.2.2 Importing A2L files (XCP on FlexRay) 175
	6.13.3	Import properties
	6.13.4	Signal properties
		6.13.4.1 Tree elements for FlexRay signals
		6.13.4.2 Grid area for FlexRay signals 180
		6.13.4.3 Details area for FlexRay signals
6.14	GPS Si	gnals
	6.14.1	Storage method
	6.14.2	Adding GPS Signals
		6.14.2.1 CAETEC GPS module
		6.14.2.2 Other GPS signals (Assigning GPS signals)
	6.14.3	Signal properties
		6.14.3.1 Tree elements for GPS signals
		6.14.3.2 Grid area for GPS signals
		6.14.3.3 Details area for GPS signals
6.15	Video	devices
0110	6.15.1	Storage method
		Video Interface
	011012	

CONTENTS



	6.15.2.1 Adding the Video Interface	94
	0	94 94
		94 95
		96
		99
	$\mathbf{v}$	99
		99
		00
		00
	6.15.4 Ethernet camera	02
	$\sim$	02
	6.15.4.2 Tree elements for ETH camera	05
	6.15.4.3 Grid area for ETH camera	05
	6.15.4.4 Details area for ETH camera	05
6.16	Video signals	80
		80
	9	08
6.17		211
on	9	211
		211
		12
		12
		12
4 10	$\mathbf{v}$	
6.18		16
	9	16
	•	16
		17
	<b>○</b>	18
	$\sim$	18
	$\sim$	18
6.19	DOUT (Digital output signals)	23
		23
	6.19.2 Adding the DOUT-Interface 2	23
	6.19.3 Signal properties	24
	6.19.3.1 Tree elements for DOUT signals	25
	· · · · · · · · · · · · · · · · · · ·	25
		25
6.20	• • • • • • • • • • • • • • • • • • •	29
	00	29
	· · · · · · · · · · · · · · · · · · ·	30
	<b>v v</b>	33
		33
		33
		33
		37
		41
6.21		46
	9	46
	S	46
	6.21.3 Signal properties	48



		6.21.3.1 Tree elements for Thermo signals
		6.21.3.2 Grid area for Thermo signals
		6.21.3.3 Details area for Thermo signals
	6.22	Internal signals
	0.22	
		6.22.1 Storage method 253
		6.22.2 Accessing internal signals
		6.22.3 Internal signals properties
		6.22.3.1 Tree elements for Internal signals
		6.22.3.2 Grid area for Internal signals
		6.22.3.3 Details area for Internal signals
		6.22.4 Run state
		6.22.5 System info
		6.22.6 Time
	6.23	Formulas
		6.23.1 Storage method
		6.23.2 Adding a formula
		6.23.3 Grid area for formulas
		6.23.4 Details area for formulas
	6.04	
	6.24	
	6.25	Transferring measurement tasks to the logger
_	<b>T</b> . 1	07/
7	Trigge	
	7.1	Adding a trigger
	7.2	Tree elements for triggers
	7.3	Grid area for Triggers
	7.4	Details area for Triggers
	7.5	Standard Triggers
	7.6	00
		88
	7.7	Cyclic Triggers
	7.8	Trigger groups
8	Script	s 287
	8.1	Adding the Scripts-Interface
	8.2	Adding a script
	8.3	Importing a script
	8.4	Tree elements for Scripts
	8.5	Grid area for Scripts (Composing a script)
	0.0	
		8.5.0.1 Edit script code
		8.5.0.2 Prefabricated code blocks
		8.5.0.3 Syntax check
		8.5.0.4 Undo in scripts / Redo in scripts
		8.5.1 Triggers in Scripts
		8.5.2 Signals in Scripts 294
		$\mathbf{\nabla}$
	0 (	
	8.6	Details area for Scripts 295
	8.7	Exporting a script



## **IPTRONIK**

9	<b>Includ</b> 9.1 9.2 9.3 9.4	Adding Tree el Grid ar	the Includes-Interface	<b>297</b> 297 298 298 298
10	Extern 10.1 10.2 10.3 10.4 10.5 10.6	Adding Adding Tree ele Grid ar	atically add external files	<b>300</b> 300 302 302 303 303 303
11	<b>Surve</b> 11.1	illance Display 11.1.1 11.1.2 11.1.3 11.1.4 11.1.5	sAdding a displayThe "Displays" interfaceCAETEC Display-specific settingsopenABK Display-specific settingsGeneral Display settings11.1.5.1Tree elements for a Display11.1.5.2Grid area for a Display11.1.5.3Details area for a Display11.1.5.4Signals for Display11.1.5.5Buttons for Display	<ul> <li>305</li> <li>305</li> <li>307</li> <li>308</li> <li>309</li> <li>310</li> <li>310</li> <li>310</li> <li>311</li> <li>312</li> <li>314</li> <li>315</li> </ul>
	11.2	11.2.1	Setting up the E-mails interface11.2.1.1Adding the E-mails interface11.2.1.2Configure SMTPComposing e-mails11.2.2.1Creating a new e-mail11.2.2.2Grid area for E-mails	<ul> <li>317</li> <li>317</li> <li>317</li> <li>317</li> <li>318</li> <li>318</li> <li>318</li> <li>318</li> <li>319</li> </ul>
	11.3	Log file 11.3.1 11.3.2 11.3.3	messagesAdding the Log file messages interfaceCreate a new Log file messages interfaceComposing Log file messages11.3.3.1Grid area for Log file messages	321 321 321 322 322 322 323
	11.4	Monito 11.4.1 11.4.2 11.4.3	ring Tree elements for Monitoring Booleans 11.4.2.1 Adding Booleans 11.4.2.2 Grid area for Booleans 11.4.2.3 Details area for Booleanss Limit value	325 325 326 326 326 326 326 329 329
			•	329



11.		.4.4 R 1 1 1	1.4.3.3Details area for Limit valuesRange1.4.4.1Adding a Range1.4.4.2Grid area for Ranges1.4.4.3Details area for Ranges	· · · ·	  	333 333 333 334
	11. 11. 11.	.5.1 A .5.2 T .5.3 G	Adding XCP slave ree elements for XCP slave Grid area for XCP slave Details area for XCP slave	· · · ·	· · · · ·	337 337 337 338
	atasets					339
12			ments for Datasets			
12			rea for Datasets			
12						
12						
			Adding project parameters			
			Assigning a template of project parameters			
			Grid area for Project settings			
			Details area for Project settings			
12						
12			Adding the Includes-Interface			
			ree elements for Includes			
			Grid area for Includes			
			Details area for Includes			
12	.6 AT					
	12	2.6.1 T	ree elements for ATFX			352
	12	2.6.2	Grid area for ATFX			352
	12	2.6.3 E	Details area for ATFX			353
			2.6.3.1 ATFX file			
		1	2.6.3.2 ATFX Timelog			355
		1	2.6.3.3 ATFX Signal Group			
	12	2.6.4 V	Vorking with Signal Groups for ATFX			
12		DF 4.0				
			ree elements for MDF 4.0			
	12		Details area for MDF 4.0			
			2.7.3.1 MDF 4.0 File			
			2.7.3.2 MDF 4.0 Timelog			
	10		2.7.3.3 MDF 4.0 Signal Group			
10			Vorking with Signal Groups for MDF 4.0			
12		DF 4.1 2.8.1 F	ile compression in MDF 4.1			
			/ideo attachments in MDF 4.1			
	12		2.8.2.1 Attaching a video			
			2.8.2.2 Details area for video in MDF 4.1			
12	.9 \/e		BLF / Vector ASCII / Vector ASCII compressed			
12			ree elements for bus/trigger tracing			
			Grid area for trigger tracing			
	.2					,.

#### CONTENTS



	12.9.3 Grid area for bus tracing	
	12.9.4 Details area for bus/trigger tracing	
	12.9.4.1 Bus tracing file	377
	12.9.4.2 Trigger trace	379
	12.9.4.3 Bus trace	381
	12.9.4.4 Tracable Bus channel	383
	12.9.5 Bus trace ID Filter	384
12.10	PCAP	386
	12.10.1 Tree elements for PCAP	386
	12.10.2 Grid area for PCAP	387
	12.10.3 Details area for PCAP	387
	12.10.3.1 PCAP file	387
	12.10.3.2 Eth trace	389
12.11	AVI	393
	12.11.1 Including a video signal in the Video Stream	393
	12.11.2 Tree elements for AVI	394
	12.11.3 Grid area for AVI	395
	12.11.4 Details area for AVI	395
	12.11.4.1 AVI File	395
	12.11.4.2 Video	397
	12.11.4.3 Video Stream	399
12.12	WAV	400
	12.12.1 Including an audio signal in the audio Stream	400
	12.12.2 Tree elements for WAV	401
	12.12.3 Grid area for WAV	402
10.10	12.12.4 Details area for WAV	402
12.13	GPX	404
	12.13.1 Assigning GPS signals	
	12.13.2 Tree elements for GPX	404
	12.13.3 Grid area for GPX	405
	12.13.4 Details area for GPX	405
	12.13.4.1 GPX File	405
10.14	12.13.4.2 GPS Tracking	
12.14	CAETEC binary (Classings / Min/Max Values)	409
	12.14.1 Tree elements for CAETEC binary	409
	12.14.2 Details area for CAETEC binary	410
	12.14.3 Adding a classing	411
	12.14.4 Min/Max Values	412
	12.14.4.1 Adding Min/Max Values and selecting signals	412
	12.14.4.2 Tree elements for Min/Max Values	414
	12.14.4.3 Grid area for Min/Max Values	414
10.15	12.14.4.4 Details area for Min/Max Values	415
12.15		418
		418
		419
	12.15.3 Adding a classing	420
10.17		421
12.16		422



13 Data	transfer		423
13.1	Transfe	er events	423
	13.1.1	General Information about transfer events	424
	13.1.2	Trigger events	425
		13.1.2.1 Tree elements for Trigger events	426
		13.1.2.2 Grid area for Trigger events	426
		13.1.2.3 Details area for Trigger events	427
	13.1.3		428
		13.1.3.1 Tree elements for Time events	428
		13.1.3.2 Grid area for Time events	429
		13.1.3.3 Details area for Time events	429
	13.1.4	System events	430
		13.1.4.1 Tree elements for System events	430
		13.1.4.2 Grid area for System events	431
		13.1.4.3 Details area for System events	431
13.2	Transfe	er connections	431
	13.2.1	Data transfer via USB	431
		13.2.1.1 Details area for USB	432
	13.2.2	Data transfer via WIFI	434
		13.2.2.1 Tree elements for WIFI connections	435
		13.2.2.2 Grid area WIFI connections	435
		13.2.2.3 Details area for WIFI	436
	13.2.3	Data transfer via LAN	440
		13.2.3.1 Tree elements for LAN connections	440
		13.2.3.2 Details area for LAN	440
	13.2.4	Data transfer via PPP/UMTS	442
		13.2.4.1 Setting up a PPP/UMTS connection	442
		13.2.4.2 Details area for PPP/UMTS	442
	13.2.5	Setting up a Fileserver	445
		13.2.5.1 Multiple File servers	446
		13.2.5.2 Tree elements for File servers	446
		13.2.5.3 Grid area for File servers	447
		13.2.5.4 Details area for File servers	447
14 Settir	ng up a	time server	449
15 Obto	aining ex	tended support	450





## 1 Foreword



## 2 Configuration

## 2.1 Symbols

Various paragraphs in this manual are marked with special symbols. These symbols have the following meanings:



This symbol highlights important information that, if ignored, may prevent successful use of the program.



This symbol refers to additional information supplementing this manual.

## 2.2 References

References to other sections of this manual are generally placed in brackets and are indicated by an arrow:

 $(\rightarrow 2.1)$  refers to Section 2.1.

When this manual is read in digital form, a mouse-click on such a reference accesses the particular section of the book.



## 3 Product description

#### 3.1 Installation

#### 3.1.1 System requirements

#### Minimum:

Screen resolution: 1080 x 800 pixel Processor: 2 GHz RAM: 2048 MB DirectX 9

#### **Recommended:**

Screen resolution: 1920 x 1200 pixel Processor: 3 GHz Multi-Core RAM: 6144 MB Storage medium type: SSD DirectX 11

#### Supported platforms:

Microsoft Windows 10 (32 Bit and 64 Bit operating systems) Microsoft Windows 8.1 (32 Bit and 64 Bit operating systems) Microsoft Windows 8 (32 Bit and 64 Bit operating systems) Microsoft Windows 7 (32 Bit and 64 Bit operating systems)

#### The following additional software is required:

Microsoft .NET 4.5.1 Framework

#### 3.1.2 Where to get the installation file?

The installation file can be downloaded from https://myipe.ipetronik.com/ or here https://www.ipetronik.com/software/plugins. Once you have logged in with your username and password you will be able to locate the file in the section UP- & DOWNLOADS.

#### 3.1.3 How to know the right version?

The format of the Plugin version is always Vxx.xx.xx (e.g. V15.10.00) and has to match the target system's dataLog firmware-version. To find out which firmware-version your target system is running you can either use the the data logger's web interface or open with a text editor the logger's logfile and look for the firmware version there. For further information please also refer to your data logger's documentation.

Multiple Plugin versions of the CAETEC Plugin for IPEmotion can be installed at the same time. This allows you to work with various data loggers that are running on different firmware versions. Once you have multiple Plugin versions installed, you will always have to ensure that your currently used Plugin version and target system's firmware version match. Please refer to **Switching between Plugin versions** ( $\rightarrow$  3.2.2).

#### 3.1 INSTALLATION



#### 3.1.4 Installation on Windows

Navigate to your download directory and extract the downloaded zip-file. For 32-bit versions of Microsoft Windows choose the following file for installation.

PE Setup IPEmotion PlugIn CAETEC dataLog.exe	30.10.2017 09:21	Anwendung	32.090 KB
For 64-bit versions of Microsoft Windows cho	oose the followir	ng file for installatio	n.
📭 Setup IPEmotion PlugIn CAETEC dataLog (x64).exe	30.10.2017 09:21	Anwendung	25.966 KB

You may be asked to confirm execution of the program. If so, please confirm and type in your Windows user password if asked to do so.

In the next window you may choose the language in which you wish to install the plugin. The language can be changed later on ( $\rightarrow$  3.2.2).

IPETRONIK	ж
IPE	
Welcome to PlugIn CAETEC dataLog	
Please choose your language and press 'Next'	
English	
Next	
IPEmotion PlugIn CAETEC dataLog V15.10.00 Beta Build 13558	

#### 3.1 INSTALLATION



The next window presents the terms of the licence agreement. Check the box I accept the terms of the licence agreement and proceed to the next window by clicking next.

IPETRONIK	×
I. General	1
§ 1 General provisions	
<ol> <li>All legal relations between IPETRONIK GmbH &amp; Co. KG (hereinafter called IPETRONIK) and its customers related to deliveries and/or services of IPETRONIK shall be exclusively based on these terms and conditions of business. General terms and conditions of the customers shall apply only if IPETRONIK has explicitly agreed to them in writing. For the scope of deliveries the mutually agreed written statements shall be decisive.</li> </ol>	
<ol> <li>Unless agreed otherwise by the contracting parties in writing, the General Terms and Conditions of IPETRONIK in force at the time of the customer's statement and accessible for consultation and downloading at <u>www.ipetronik.com/en/terms-conditions</u> shall be applicable exclusively even if not referred to again when concluding similar contracts.</li> <li>In spite of utmost care in preparing this document printing, typing or transmission errors cannot be ruled out. For such errors no warranty can be assumed.</li> </ol>	
§ 2 Subject matter of contract, scope of performance	
✓ I accept the terms of the licence agreement	-
IPEmotion PlugIn CAETEC dataLog V15.10.00 Beta Build 13558 Back Next	

In the next window you select the target folder where the plugin is to be installed. The standard installation path is set as default. Normally you can simply accept it. Click Install to continue and start the installation process. Again you may be asked for confirmation and/or your Windows user or admin password. Please type it in and click OK to continue.

<b>IPTRONIK</b>			ж
Please select the installation director	es Change	Installation folders: Folder where the application is installed to.	
IPEmotion PlugIn CAETEC dataLog V	/15.10.00 Beta Build 13558	Back Install	

Once installation has been comleted successfully you will need to acitvate the Plugin in the Options dialogue in order start working with it. To do so please refer to the section Activating the plugin ( $\rightarrow$ 3.2.2).



After completion of the installation we strongly advice you to acitvate the expert mode and afterwards activate the extended tabs option and change the number of maximum polling lists in the expert settings. For detailed information refer to the sections **Expert mode, Extended tabs** and Maximum polling lists ( $\rightarrow$  3.2.2).

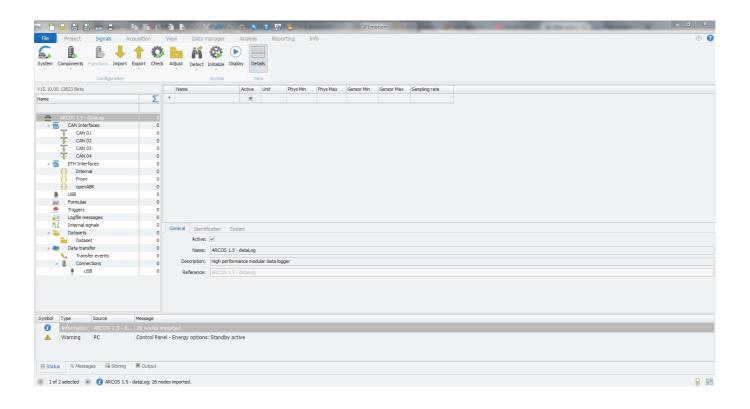


The plugin allows for a customizable user guidance by giving you the option to choose which tree elements you would like to be available in the measurement task tree. For detailed information refer to the section **Customizing tree elements** ( $\rightarrow$  3.2.2).



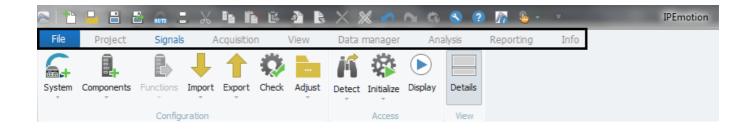
### 3.2 User interface

This section describes the general appearance and funcionality of the CAETEC Plugin for IPEmotion. However it will not describe specifics on how to create a measurement task or on the single elements available to configure your data logger. For information on these topics please refer to Chapter ( $\rightarrow$  6).



#### 3.2.1 Menu bar

The menu bar provides the core funcionality of IPEmotion. However when working with the CAETEC Plugin you will only need to make use of the **"File"** menu and the **"Signals"** tab, as the Plugin offers a closed working environment which includes all funcionality needed in order to work with your data logger inside the "Signals"-tab.





#### 3.2.2 "File" menu and important basic settings for working with the PlugIn

A dropdown menu with basic IPEmotion functionality. Only the item relevant for working with the CAETEC Plugin for IPEmotion will be explained here. For information on items not explained here, please refer to the IPEmotion documentation.

811	) 📙 🗄 🕹	AUTO		i.	ľł	Ê	4	Ę.	$\times$
File									
	New	Re	ecent proj	jects l	ist				
	Open								
	Save								
Ð	Save as								
	App-Export	۲							
- C	Runtime version								
Ō	Compare								
H	Print	•							
Ŋ	View	۲							
	Administration	•							
	Options								
R	About								
	Close								

#### New

Creates a new configuration/project.

#### Open

Opens a previosly saved configuration/project. You can open a range of different filetypes. The **IPEmotion configuration file (\*.iwf)** is a container holding the entire IPEmotion-Project and its settings. The **IPEmotion acquisition configuration file (\*.iac)** holds only the configuration contained in the "Signals" tab.



The \*.isf-filetype and \*.ccmc-filetype can only be opened when working inside the Signals tab of IPEmotion.

#### Save

Saves the current configuration/project.

#### Save as

Changes and errors excepted.



Save the current configuration/project under a new name and/or in a new location. You can choose between two different file-types to save your projects, which will determine the information your saved file will hold. The **IPEmotion configuration file (\*.iwf)** is a container holding the entire IPEmotion-Project and its settings. The **IPEmotion acquisition configuration file (\*.iac)** holds only the configuration contained in the "Signals" tab.

#### Options

Opens a window with options that affect the behaviour of IPEmotion. This manual will only address the options important for working with the CAETEC Plugin for IPEmotion.

#### • Change language

The language can be changed in the options window by choosing the tab **"Appearance"** on the left and then choosing the desired language from the dropdown menu **"Language selection"** on the right.

PlugIns	Appearance View	Skin selection:	IPEmotion V2 v
View       Display tooltips: ♥         Data manager       Font size of the visual elements: M ♥         Import       Transparency of configuration dialogs: ① ♥         Analysis       ① ♥ %         Directories       ① ♥ %         Units       ● Relative         Hotkey       ● Absolute         User displays       Use Windows standard dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not	View		
Usew       Font size of the visual elements:       M *         Jmport       Transparency of configuration dialogs:       0 * %         Export       Use Windows standard dialogs:       Ø         Analysis       Ime channel format:       • Relative         Directories       Ime channel format:       • Relative         Units       • Absolute         Hotkey       User administration         IPEcloud       PlugIns         User displays       Use Windows standard dialogs         At activated flag, the Windows dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not		Display toolting:	
Import Transparency of configuration dialogs: 0 € % Export Use Windows standard dialogs: Directories Time channel format: Absolute Units Hotkey User administration IPEcloud PlugIns User displays User Windows standard dialogs At activated flag, the Windows dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not	Data manager		
Use Windows standard dialogs Use Windows standard dialogs Use Windows standard dialogs User displays User displays User displays User Windows standard dialogs At activated flag, the Windows standard dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not		Font size of the visual elements:	M Ŧ
Use Windows standard dialogs:	Import	Transparency of configuration dialogs:	0 🗘 %
Directories Time channel format:   Relative  Absolute  Units Hotkey User administration IPEdoud PlugIns User displays User Windows standard dialogs At activated flag, the Windows standard dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not		Use Windows standard dialogs:	V
Directories Absolute Units Absolute Hotkey User administration PEcfoud PlugIns User displays Use Windows standard dialogs At activated flag, the Windows standard dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not	Analysis	Time channel format:	Pelative
Hotkey User administration IPEdoud PlugIns User displays User Windows standard dialogs At activated flag, the Windows standard dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not	Directories	The clarife format	
User displays User Windows standard dialogs At activated flag, the Windows standard dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not	Units		
IPEdoud PlugIns User displays Use Windows standard dialogs At activated flag, the Windows standard dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not	Hotkey		
At activated flag, the Windows standard dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not	User administration		
User displays Use Windows standard dialogs At activated flag, the Windows standard dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not	IPEcloud		
Use Windows standard dialogs At activated flag, the Windows standard dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not	PlugIns		
At activated flag, the Windows standard dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not	User displays		
At activated flag, the Windows standard dialogs are used instead of the IPEmotion dialogs. But the Windows dialogs are not			
		At activated flag, the Windows standard dialogs are used in	



#### • Expert mode

The Expert mode can be activated in the options window by choosing the tab **"Basic settings"** on the left and then checking the checkbox for Expert mode. Once you activated the Expert mode, **Expert settings** will be accessible by clicking on the button with the three dots next to the Expert mode checkbox.

Frequently used	Preferred configuration type: <ul> <li>H</li> </ul>	ardware configuration
Basic settings		gnals configuration
Appearance		
/iew	Signal database:	
Data manager	Accurate acquisition chain required:	
Import	Expert mode: 🗹	
Export	Automatic service administration: 🗹	
Analysis		
Directories		
Jnits		
Hotkey		
Jser administration		
PEcloud		
PlugIns		
Jser displays		
	s settings fy basic settings.	

#### • Extended tabs

This Option should be activated. It will provide additional tabs in the Details area for some elements of the Measurement task tree. Extended tabs can be activated by checking the checkbox for **Extended tabs** in Expert settings.

Expert settings ×
General options
Additional warnings: 🗹
Name pattern: "Type"-"Source"-"Inde
Configuration options
Variable configuration: 🗹
Extended tabs: 🗹



#### • Maximum polling lists

Defines the maximum number of polling lists. Multiple polling lists must be supported by the connector. The value should be set to a maximum of 4 polling list. The maximum number of polling lists can be changed by choosing the desired number from the **Max. polling lists** dropdown menu in Expert settings.

Description files import options
View protocols: 🗹
Edit protocol channel scaling:
View diagnostic jobs:
Ignore verbal tables:
Max. polling lists: 4
Use characteristics: for calibration 🔹
Support J1939: 🖌
Logging import:
OK Cancel

#### • Edit protocol channel scaling

This option has to be activated in Expert settings in order for the scaling functionality to be available for protocol channels as well.

Description files import options
View protocols: 🗹
Edit protocol channel scaling: 🗹
View diagnostic jobs:
Ignore verbal tables:
Max. polling lists: 1
Use characteristics: for calibration 🔹
Support J1939: 🗹
Logging import:
OK Cancel



#### • View protocols

Activating this expert setting will allow you to see not only the ECU in the "Measurement task tree", but also the associated dag lists and polling lists.

Description files import options
View protocols: 🔽
Edit protocol channel scaling: 🖌
View diagnostic jobs:
Ignore verbal tables: 🗹
Max. polling lists: 4
Use characteristics: for calibration 🔹
Support J1939: 🗹
Synchronize signals by name:
Logging import:

#### • Ignore verbal tables

It is recommended to activate this option as the PlugIn does not support verbal tables.

If the option to ignore verbal tables is not activated, verbal tables that are included in the configuration will be transformed to a factor/offset scaling at export.

Description files import options
View protocols: 🗹
Edit protocol channel scaling: 🗹
View diagnostic jobs:
Ignore verbal tables: 🗹
Max. polling lists: 4
Use characteristics: for calibration 🔹
Support J1939: 🗹
Synchronize signals by name:
Logging import:



#### • Activating the Plugin

In order to work with the CAETEC Plugin you need to activate it inside IPEmotion. To do so, choose **Pluins** on the left side of the Options window and then tick the checkbox saying *Active* for the CAETEC dataLog Plugin.

requently used	Active		Title		Version	Description		Manufactur
Basic settings	~	6		۲	15.10.00.13558 Beta 🔹		0	
Appearance								
/iew								
Data manager								
mport								
Export								
Analysis								
Directories								
Jnits								
Hotkey								
Jser administration								
PEcloud								
PlugIns								
-								Download
Jser displays								



#### • Switching between Plugin versions

The CAETEC Plugin allows for various versions of the plugin in to be installed at the same time. It offers you the option to switch between different Plugin versions according to the firmware version your dataLog system is running, and therefore allows the use of various dataLog systems with different firmware versions.

In order to switch between Plugin versions choose **PluIns** on the left side of the Options window and then you can choose the desired version in the yellow marked dropdown menu on the right.

Frequently used	Active		Title		Version	Description		Manufacture
Basic settings	~	6		۲	15.10.00.12823 Beta 🔹	CAETEC Datenlogger (ARCO	S and µ 🔞	
Appearance								
View								
Data manager								
Import								
Export								
Analysis								
Directories								
Units								
Hotkey								
User administration								
IPEcloud								
PlugIns	4							
User displays								Download
	The used	ne plugir plugin v	ns to be used.	within th	e list. If a version number	is selected that ends with a '='	character, no a	automatic

#### • Customizing tree elements

The CAETEC Plugin for IPEmotion allows for a customizable user guidance by letting you specifically determine which elements of the Measurement task tree will be available or not. In order to do so, choose **Plugins** on the left side of the Options window and then press the small button with the blue wrench symbol to open the **Plugin-specific settings**.

	Active	Title	Version	Description	Manufact
Basic settings		CAETEC dataLog	🕙 15.10.00.12823 Beta	▼ CAETEC Datenlogger (ARCOS and µ	🔞 CAETEC
Appearance					
View			Plugin-specific settings		
Data manager					
Import					
Export					
Analysis					
Directories					
Units					
Hotkey					
User administration					
IPEcloud					
	4				
PlugIns					
PlugIns User displays					Download

By choosing an element in the "Components" tab of the following window and setting its priority to "**Not used**", as shown below, this element will not be available for the respective Plugin version anymore. If you would like to make available an element which you have previously set to "**Not used**" then you just have to set its priority back to "**Normal**".

pe	Priority
aRCOS 1.0 - dataLog	Normal
ARCOS 1.5 - dataLog	High
📾 μCROS - dataLog	Normal
🚌 μCROS XL - dataLog	Low
TestingLoggerTestCros	Not used
🐻 LIN Interfaces	Normal
🖉 FlexRay Interfaces	Normal
PPP	Normal
XCP slave	Normal
🚝 DIN	Normal
ST DOUT	Normal
ANALOG	Normal
THERMO	Normal
includes	Normal
Displays	Normal
M Emails	Normal
ne Video Interface	Normal
💕 GPS	Normal
CAN	Normal
Bus statistic	Normal
Audio recording	Normal

#### • Create and synchonize external files

It is possible to set up the CAETEC dataLog PlugIn in such a way, that imported signal databases will automatically be added as external file to their respective signal channel. This option is described in detail in the chapter "External files". Please refer to  $(\rightarrow 10.1)$ .



#### • Extended FlexRay namespaces

The CAETEC Plugin for IPEmotion provides the option to work with an extended FlexRay namespace, including base cycle and cycle repetition parameters of signals in the namespace. This may be usefull, if the regular FlexRay namespace creates ambiguos names. In order to do so, choose **PlugIns** on the left side of the Options window and then press the small button with the blue wrench symbol to open the **Plugin-specific settings**.

Frequently used	Active	Title	Version	Description	Manufactur
Basic settings	<b>Z</b>	CAETEC dataLog	15. 10.00. 12823 Beta	<ul> <li>CAETEC Datenlogger (ARCOS and µ</li> </ul>	🔞 CAETEC
Appearance					
View			Plugin-specific settings		
Data manager					
Import					
Export					
Analysis					
Directories					
Units					
Hotkey					
User administration					
IPEcloud					
PlugIns	4				
User displays					Download
uspiays					

In the following window activate the option by marking active the "Extended FlexRay namespace" tickbox in the "Options" tab.

	Error Free Configuration	
Extended FlexRay namespace: eate and synchronize external files:		
Communication		
Primary IP address:	203.0.113.1	
Secondary IP address:	192.168.1.88	
Alternative IP address:		
User name:		
Password:		



#### • Use namespace

The CAETEC Plugin for IPEmotion provides the option to disable namespaces. By default the setting "Use namespace" is activated, which means, that namespaces will be used in your configuration and signalnames or other names must only be unique within their respective namespaces.

If the setting "Use namespace" is deactivated, no namespaces will be used in your configuration and all signalnames and other names need to be unique within the entire configuration.

In order to change this setting, choose **PlugIns** on the left side of the Options window and then press the small button with the blue wrench symbol to open the **Plugin-specific settings**.

	Active	Title	Version	Description	Manufacture
Basic settings		CAETEC dataLog	🔇 15. 10.00. 12823 Beta	CAETEC Datenlogger (ARCOS and µ 🤅	CAETEC
Appearance					
View			Plugin-specific settings		
Data manager					
Import					
Export					
Analysis					
Directories					
Units					
Hotkey					
User administration					
User administration IPEcloud					
	4				
IPEcloud	4				Download

In the following you may activate/deactivate the setting "Use namespace" in the "Options" tab.

eneral		
Export requirements	: Error Free Configuration 👻	
Use namespace	: 🗹	
Extended FlexRay namespace	:	
Auto attach external files	:	
ommunication		
Use deprecated IP range	:	
Primary IP address	: 203.0.113.1	
Secondary IP address	: 192.168.1.88	
Alternate IP address	:	
User name		
Password	:	



#### • Communication settings

In order for online communication via Ethernet between The CAETEC Plugin for IPEmotion and a PC to work, it may be necessary to specify some communication settings. For instructions on how to do so, please refer to  $(\rightarrow 4.6)$ .



#### 3.2.3 Working with the Ribbon

This area contains general functions regarding your configuration.

≥   🏠		RUTO	- X	ie ii	Ê	4	$\times$ 8	≪ ∽	2 4	8	?	h 🕼		IPEmotion
File	Project	Signals	A	cquisitio	n	View	Data i	manager	Ana	alysis		Reporting	Info	)
6			↓				ĸ	*						
System ,	Components ,	Functions	Import T	Export	Check	Adjust	Detect	Initialize	Display	Detail	s			
		Config	uration					Access		View				



The "Ribbon's" functionalities "Components", "Functions", "Import" and "Export" are also accessible by righclicking on the tree element to which you would like to apply one of these options and then choosing the respective option from the context menu.

#### System

A dropdown menu that lets you choose which data logger system you want to configure. You can change the logger system into a different system at any given moment by rightclicking on your current logger system in the measurement task tree and selecting **Change into**.

#### Components

Offers a choice of additional components which are available for the element currently selected in the measurement task tree. You add the desired component by clicking on it. Each activated component will appear in the measurement task tree as a child element to your previously selected element. The same functionality is accessible through right-clicking an element in the measurement task tree and then choosing **Components**.

#### **Functions**

Offers a choice of additional functions which are available for the element currently selected in the measurement task tree. You activate the desired function by clicking on it. The same functionality is accessible through right-clicking an element in the measurement task tree and then choosing **Functions**.

#### Import

Offers a choice of import-options which are available for the element currently selected in the measurement task tree. You choose the desired import-option by clicking on it. The same functionality is accessible through right-clicking an element in the measurement task tree and then choosing **Import**.



#### Export

Offers a choice of export-options which are available for the element currently selected in the measurement task tree. You choose the desired export-option by clicking on it. The same functionality is accessible through right-clicking an element in the measurement task tree and then choosing **Export**.

#### Check

Perform a check on your current configuration's validity. The results will be automatically presented in a pop-up window once the check has finished. In the pop-up window you have the option of rerunning the check by clicking **refresh** and to export the results as a csv-file or html-file. The check function will be automatically performed each time the **datalog.cfg** is exported.

#### Adjust

This functionality is currently not supported by this plugin.

#### Detect

If a logger is connected to your PC, this function detects any connected logger and imports the configuration currently in use on the logger. This gives you the possibility to modify a pre-existing loggerconfiguration without the need of setting it up from scratch.

If there is no valid configuration in use on the connected logger, the plugin will detect all the available interfaces of the logger and adjust the measurement task tree elements accordingly.



If a logger is configured with a user-specific IP or protected with user name and password, it may be necessary, to edit the communication settings of the plugin first. Instruction on these settings can be found here  $(\rightarrow 3.2.2)$ .

#### Initialize

If a logger is connected to your PC, this function exports the configuration currently in use in IPEmotion to the logger. During export the configuration will be checked for validity and give notice if any errors occurr.



If a logger is configured with a user-specific IP or protected with user name and password, it may be necessary, to edit the communication settings of the plugin first. Instruction on these settings can be found here  $(\rightarrow 3.2.2)$ .



#### Reset

If a logger is connected to your PC, this function deploys a basic configuration compatible with your logger model to the logger.



If a logger is configured with a user-specific IP or protected with user name and password, it may be necessary, to edit the communication settings of the plugin first. Instruction on these settings can be found here  $(\rightarrow 3.2.2)$ .

#### Display

This functionality is currently not supported by this plugin.

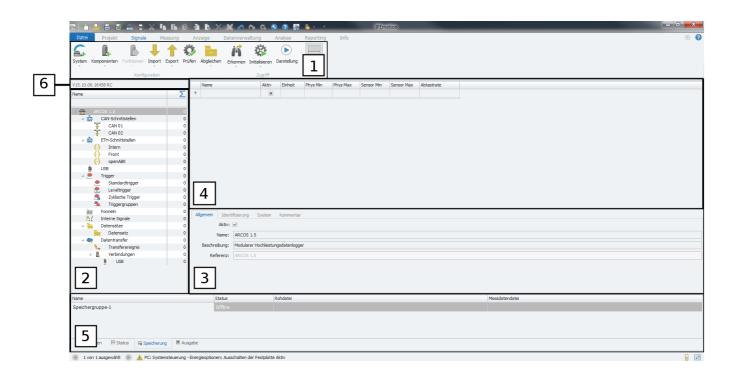
#### Details

Allows you to hide/show the details area of your current configuration.



#### 3.2.4 "Signals" tab

The "Signals" tab, which is located in the menu bar ( $\rightarrow$  3.2.1), contains your main workspace when working with the CAETEC Plugin for IPEmotion. It is divided in various areas which allow you to create measurement tasks and configure your data logger.





#### Ribbon

A strip of icons that can be clicked for quick access to certain functions and tools. (  $\rightarrow$  3.2.3)



#### Measurement task tree

The measurement task tree shows a hierarchical view of the individual configuration sections for the opened measurement task. Specific information on working with the measurement task tree will be given in chapter ( $\rightarrow$  4.2.1).

3	
---	--

#### Details area

This area contains, for the selected section of the measurement task tree, a field and/or tabs that allows you to set the parameter settings for your selected section. Specific information on working with the Details area will be given in chapter ( $\rightarrow$  4.2.2).



#### Grid area

This area contains, for the selected section of the measurement task tree and its child elements, a grid which shows an overview of available measurement channels. Specific information on working with the grid area will be given in chapter  $(\rightarrow 4.2.3)$ .



## 5 Message area

This area contains messages about errors, warnings and information of the current configuration of the measurement task ( $\rightarrow$  3.2.6).



#### Plugin version

The current Plugin version in use is shown in a field located above the measurement task tree. The format of the version is always Vxx.xx.xx and has to match the target system's dataLog firmware-version ( $\rightarrow$  4.3).

#### 3.2.5 Quick Access Toolbar

811	- 🔒 🔒 🖥	RUTO	×	ie fe	Ê	4	X 8	% 🙆	2 4	8 ?	) 💦 🐌	, - <del>-</del>	IPEmotion
File	Project	Signals	A	cquisitior	ı	View	Data i	manager	Ana	alysis	Reportin	g Info	
6.			↓		Ô		ĸ		$\triangleright$				
System	Components	Functions	Import	Export	Check	Adjust	Detect	Initialize	Display	Details			
*	Ť			Ŧ		÷	Ŧ	Ŧ					
		Configu	ration					Access		View			

A customizable toolbar which allows you to quickly access your most frequently used tools. For further information please refer to the IPEmotion documentation.

#### 3.2.6 Message area

This area contains important messages, the status, potential conflicts and errors of the current configuration of the system.

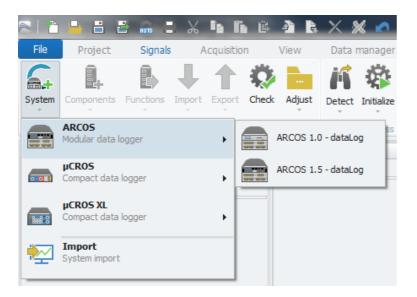


## 4 Setting up a logger system

This section explains the workspace and the steps to set up the right logger system for your project/configuration. It will also explain options to customize the use of your logger system.

## 4.1 Choosing a logger-system

Once you have activated the Plugin ( $\rightarrow$ 3.2.2) choose the desired logger-system. Click the **System button** on the top left in the ribbon and then select your desired system. The system you choose should match your target system (e.g. if your hardware is an AR-COS 1.5 then you should choose the ARCOS 1.5 as the system you wish to configure).



According to your hardware's possible interfaces a preconfigured workspace will be opened inside the Signals tab. This workspace will be explained in more detail in the following.



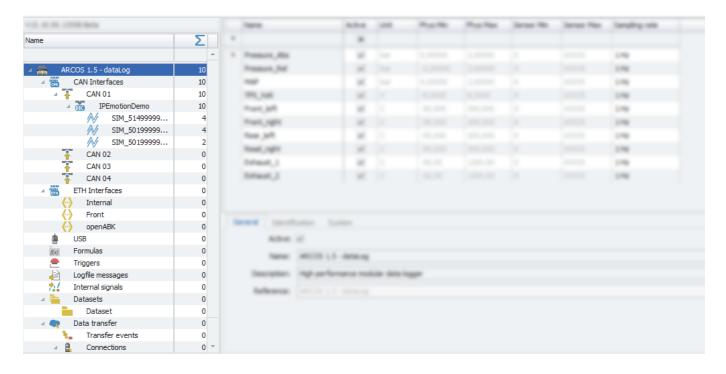
# 4.2 The measurement task workspace

The main parts of the measurement task workspace are the **Measurement task tree** ( $\rightarrow$  4.2.1), **the details area** ( $\rightarrow$  4.2.2) and **the grid area** ( $\rightarrow$  4.2.3). For information on other parts please refer to ( $\rightarrow$  3.2.4).

## 4.2.1 The measurement task tree

The measurement task tree shows a hierarchical view of the individual measurement taskconfiguration pages of the Plugin. Clicking an item in the tree opens the corresponding configuration pages in the details area and the grid area to the right of the tree, where you can perform the desired settings.

Right-clicking an element in the measurement task trees opens a context menu showing options for that element. Depending on the type of element, this context menu gives you the option of adding additional child elements below the clicked element, for example, or lets you remove or disable optional configuration elements.





### 4.2.2 The details area

The details area contains tabs which allow for additional settings for the selected tree element. In this section we will quickly describe the Details settings available for your CAETEC dataLog system, which you will see, once you clicked on your system on top of the measurement task tree. More detailed settings for other tree elements will be handled in the respective sections of this manual.

15. 10. 00. 12730 Beta		Tarm .	4.0.4	100	No. of Concession, Name	10.00	Server He	Server Hen	Langing via
are .	Σ								
		Personal Adv.							178
MOTO LA GRAN		Press, Nd	10						178
<ul> <li>Can traches</li> </ul>	-		14						178
- T CARE DI	-	75,148							178
- X PfosterCere	-	mark (MR	14						178
AV 104,104000		Provid Jught							1.00
N 10,0000.		Name (1981) Name (1981)	14						178
N 10,0000.		Read, right							1.00
1 1000		Exhautt, 1							178
1 100		Driver, J							1.00
A Statement									
O internet									
A Martin									
() and (0)		General Identifi	cation System						
		Active:	~						
as Particles		Name:	ARCOS 1.5 - dataLog						
<ul> <li>Togett</li> </ul>			-						
<ul> <li>Light recognit</li> </ul>		Description:	High performance mod	ular data l	ogger				
1 Internal signals		Reference:	ARCOS 1.5 - dataLog						
- Detects									
-									
<ul> <li>Deta transfer</li> <li>Transfer events</li> </ul>									
· A Constient									

#### • General

This tab allows you to activate or deactivate the entire system by ticking/unticking the checkbox, give a user specific name to your system if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

General Identif	fication System
Active:	
Name:	ARCOS 1.5 - dataLog
Description:	High performance modular data logger
Reference:	ARCOS 1.5 - dataLog



#### Identification

This tab allows for more specific Identification of your system. The **Configuration name** serves as an identifier of your configuration for the user. This is the name of your system that will be visible in the webinterface of your datalogger.

The **Front number** field allows you to enter a target system's unique front number, which will have the effect, that the created datalog.cfg will only work with that specific target system.



In the field "Configuration name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .



If a front number is entered, the configuration will exclusively function for the logger with the corresponding front number. It will not work on any other logger.

General	Identification	System
Con	figuration name:	
	Front number:	

#### • System

This tab allows for system specific settings. Follow-up time defines how long the logger keeps measuring after the last wake-up condition went away. Reserved disk space determines the amount of disk space that is reserved for internal processing (e.g. zip-compression). Shutdown delay sets how long the shutdown of the whole system will be delayed after having ended current measuring. During this time a new measurement can be started by a valid wake-up condition. Shutdown timeout determines the maximum allowed time for a shutdown of the system. If this time is exceeded, a hard shutdown will be forced and all processes, including datatransfers, will be cancelled.

General Identification	System
Follow-up time:	0 s
Reserved disk space:	10 %
Shutdown delay:	0 s
Shutdown timeout:	5 min



#### • Wake on time

The "Wake on time" option allows you to set your logger to wake up on a specific point of time. Whenever this point of time occurs the logger will wake up, if it is not active already. I.e. if you set the mode to hourly at minute "0", the logger will wake up at every full hour. If you set it to hourly and minute "30", the logger will wake up alway at half past the full hour.

If in another case you would like the logger to wake up every monday at 8.30 in the morning, the setting would be **Mode: weekly, Minute: 30, Hour: 8, Day: Monday**, as seen in the figure below.

General	Identification	System	Wake on Time	Comment	Versions
	Mode:	Weekly		Ŧ	
	Minute:	30			
	Hour:	8			
	Day:	1	Monday	Ŧ	
	Month:	January		Ŧ	

#### • Signal check

The "Signal check" function allows to check, whether the logger receives a signal as expected. If a signal is expected but the logger does not receive it, signal check (if it is activated for this signal) will inform the user.

This tab allows you to define a set of global signal settings, which can then later be applied to any signal. That way you can make sure, that all signals which are supposed to be configured in the same way, will actually use the same settings.

The "Signal check" function allows to set one of three modes that define when the logger shoud expect a signal: "Continuous", "Start and stop trigger" and "Stop is inverted start".

It also allows to set the Start-trigger and the Stop-trigger and the timeout.

If any of these parameters gets changed, it will change also for any signal to which is using the global signal check setttings.

In order to make these global settings available for use with signals, the tickbox "Use global settings" needs to be marked active.

General	Identification	System	WakeOnTime	Comment	Versions	Signal check	Bus check
Us	e global settings:	~					
	Mode:	Continuou	S	-			
	Start-trigger:				Selec	t	
	Stop-trigger:				Selec	t	
	Timeout:	30 s					



## 4.2.3 The grid area

The grid area shows all available signals of the selected tree element. It also allows to activate certain signals, to rename them and sort by the different column's parameters. The "column chooser" allows you to customize which columns will be shown in the grid area. For more information on the "column chooser" please refer to ( $\rightarrow$ 4.3.1).

C. B. M. CERRINA		Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
ana l	9								
	•	Pressure_Abs	~	bar	0,00000	2,00000	0	65535	1 Hz
ACTO L1 Arrang		Pressure_Rel	~	bar	-2,00000	2,00000	0	65535	1 Hz
<ul> <li>Can trianfaces</li> </ul>		MAP	~	bar	0,00000	3,00000	0	65535	1 Hz
- T (200-01)		TPS_Volt	~	V	-8,0000	8,0000	0	65535	1 Hz
- X PlouterCere		Front_left	~	С	-50,000	200,000	0	65535	1 Hz
AV 104,104000		Front_right	~			200,000	0	65535	1 Hz
NY INCOME.		Rear_left	~	С	-50,000	200,000	0	65535	1 Hz
		Read_right	~	С	-50,000	200,000	0	65535	1 Hz
T (80.0	2	Exhaust_1	~	С	-50,00	1200,00	0	65535	1 Hz
T (m)n		Exhaust_2	~	С		1200,00	0	65535	1 Hz
A fuel	3	-							
	21	4.0-0	ur.						
E Paradas	1	Tarres.	MICH L3 -deterag						
at tagte recept		Descriptions	ingly performance must	-	-				
5. Enternal agends		indexes.							
- h Intents									
instant (									
- 🗮 Data transfer									
🍆 Transfer events									
· B. Carrachera	10 C								

# 4.3 Plugin version

The current Plugin version in use is shown in a field located above the measurement task tree. The format of the plugin version is always Vxx.xx.xx (Vmajor.minor.hotfix). The plugin version has to match the target system's dataLog firmware-version.

If you have multiple Plugin versions installed, you may switch between versions. For detailed information please refer to Switching between Plugin versions ( $\rightarrow$  3.2.2).



### 4.3.1 Column chooser

The "column chooser" allows you to customize which columns will be visible in the grid area. You can customize your "grid area" in such a way, that every setting you can adjust in the "details area" for a given tree element can be made accessible through the "grid area" of this tree element.

In order to access the "Column chooser" rightclick on any point of the column title bar and choose "Column chooser" from the context menu.

Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate	Bus type	Factor	Offset	Data type	N	
											Ŷ	2	
Pressure_Abs	~	bar	0,00000	2,00000	0	65535	1 Hz	CAN	3,0518E-05				
Pressure_Rel	~	bar		2,00000		65535	1 Hz	CAN	6,10361E-05	-2			
MAP	¥												
TPS_Volt	~	V	-8,0000				1 Hz	CAN	0,000244144				
Front_left	1		-50,000	200,000	0	65535	1 Hz	CAN	0,00381476	-50		Customization	
Front_right	~						1 Hz	CAN	0,00381476			Data type	
Rear_left	~	С	-50,000	200,000	0	65535	1 Hz	CAN	0,00381476	-50		Decimal places	
Read_right	~					65535	1 Hz	CAN	0,00381476			Default value	
Exhaust_1	~	С	-50,00	1200,00	0	65535	1 Hz	CAN	0,0190738	-50		Description	
Exhaust_2	~					65535	1 Hz	CAN	0,0190738			Display Max	
												Display Min	
												Display name	

The resulting window on the right called "Customization" will present you with a selection of the available columns. In order to add an extra column, choose the one you would like to add from the "Customaization" window and drag id to the column bar as shown above.

If you wish to remove a column just drag it to any point outside of the column title bar until you see a big black cross and then release it.

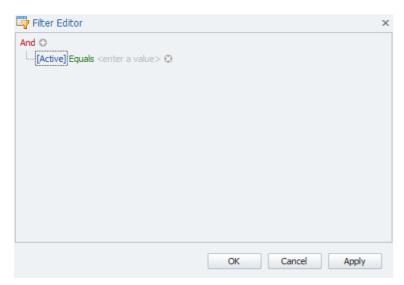


#### 4.3.2 Filter editor

The "Filter editor" allows you to apply customized filter rules to your signals. In order to access the "Filter editor" rightclick on any point of the column title bar and choose "Filter editor" from the context menu.

📴 Filter Editor	×
And O	
① And	
Or Or	
Not And	
ON Not Or	
🖣 Add Condition	
📑 Add Group	
	OK Cancel Apply

Once the "Filter editor" has opened, click on the red "And" in the top left corner. The resulting context menu allows you to choose the method of combining the different filter conditions (And, Or, Not And, Not). It also allows you to add a condition (which can alternatively be achieved by clicking the "+" sign right of the "And") or add a new group of filter conditions.





Once you have added a filter condition, you will now need to specify this condition in order to funciton properly. There are three fields you will need to set.

- The field on the left with **blue letters** defines to which column the filter will apply.
- The field in the middle with green letters sets a parameter for your filter condition.
- The field on the right with grey letters sets a value for the choosen parameter.

📴 Filter Editor	х
And O	
[Active] Does not equal Checked 😳	
[Bus type] Equals CAN	
	OK Cancel Apply

You can combine different filter conditions or groups of filter conditions to obtain the desired filter result. In the example shown above, the filter will select all CAN signals which are not checked "Active".

# 4.4 Changing the logger system with the *change into*-command

A previously set up logger system can still be changed into another one of the same loggerfamily later. To do so, right-click on your system in the measurement task tree, navigate to **change into** and choose the system you would like to change it to.

System Components	Functions Import	Export Cher	ck Adjust	Detect Initializ
	Configuration			Acces
V15.10.03.21025 Beta	=		Name	2
Name		Σ	9	
🔺 🛖 💦 ARCOS 1.5	Compone	ents	E I	
A GR CAN int	eria			
TAD T	N 01 🚡 Change i	nto		ARCOS 1.0
TAD T	N 02 🚯 Function	s		
🔺 🗰 🛛 ETH inte	erfac 👃 Import		•	
Here From From From From From From From From	nt 🚺 📜			
🔶 Inte	ernal 1 Export		<u> </u>	
🔶 ope	enABł 🚳 Use as d	efault		

Interchangeability of logger systems

- ARCOS 1.0  $\leftrightarrow$  ARCOS 1.5
- $\mu CROS \leftrightarrow \mu CROS$  XL (FlexRay; LIN)
- $\mu CROS$  XL (FlexRay)  $\leftrightarrow \mu CROS$  XL (LIN)



If you are trying to change into another logger system and one of your currently used tree elements is not available in the system you are changing into, you will see a **Warning-message** in the Messages area ( $\rightarrow$ 3.2.6) and this tree element will not be migrated.

# 4.5 Open / Import / Export the datalog.ccmc and other PlugIn specific files

### 4.5.1 Importing the datalog.ccmc via system import

When within the "Signals" tab in IPEmotion, you can import an existing configuration via system import. This will create the entire system inside the "Signals" tab.

To do so, click the "System" button in the Ribbon and then click "Import".



In the next window choose the \*.ccmc file of the configuration, you wish to import, and confirm with "Open". This will import the entire system and its configuration which can be modified from here on.

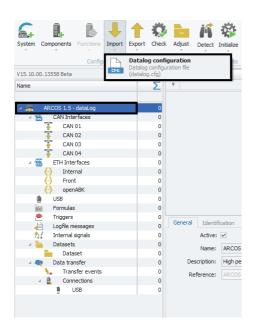
→ × ↑ 📙 « IPI	ETRONIK > IPEmotion > Import >	~	ථ "Import" du	rchsuchen
rganisieren 👻 Neue	r Ordner			· · · ·
Import ^	Name	Änderungsdatum	Тур	Größe
🔥 trunk	📙 Kundendatenbanken	12.03.2019 10:26	Dateiordner	
📤 OneDrive	ARCOS_1.5.ccmc	19.03.2019 10:04	CCMC-Datei	10 KB
Desktop Dokumente Downloads Musik Videos				
<ul> <li>Dokumente</li> <li>Downloads</li> </ul>				

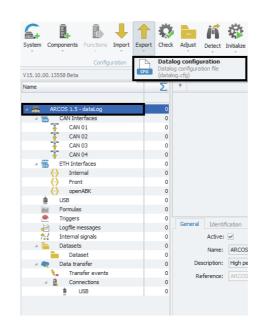
#### 4.5.2 Importing and exporting the datalog.ccmc after system creation

Once you have chosen the system you would like to configure, you will be able to import and/or export the datalog.ccmc. That way you can import a datalog.ccmc previously configured with the plugin and can keep the settings. The export function allows you to export your configuration and then copy it to one or more matching target systems. To do so, just select your system in the measurement task tree and then select either **Import** or **Export** from the Ribbon and choose datalog.ccmc. Alternatively you can right-click on your system in the measurement task tree and select Import or Export from the following context menu.

!

The filename under which the exported .ccmc-file will be save cannot contain any special characters such as ", §, ö and so forth. The spelling of the filename will be checked during export and any special character in the filename will be replaced with an underscore ("\_").



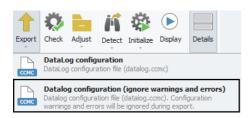


#### 4.5.3 Ignore errors and warnings at export

The CAETEC Plugin for IPEmotion checks any configuration for errors and warnings before exporting the ccmc-container or when using the "Check" function in the Ribbon. If a warning occurs, export will still happen, but the element causing the warning will not be exported.

If an error occurs, the export will be canceled.

However, if you click "Export" in the Ribbon and then choose "Datalog configuration (ignore warnings and errors)", export will happen even if an error or warning occurs. The error/warning will then appear as info-message instead and export will proceed.



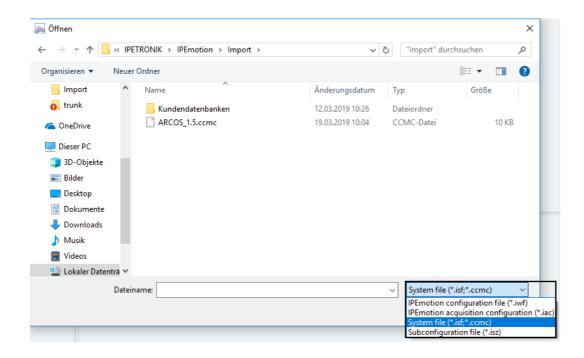
## 4.5.4 Opening the datalog.ccmc via the "Open" dialog

When within the "Signals" tab in IPEmotion, you can open an existing configuration via the "Open" dialog. This will open the entire system inside the "Signals" tab.

To do so, open the "File" menu and then click "Open".



In the next window it is important, that you first choose the "System file (\*.isf, \*.ccmc)" type on the bottom right, before you select the \*.ccmc file, you wish to import, and confirm with "Open". This will open the entire system and its configuration which can be modified from here on.



#### 4.5.5 Opening the datalog.ccmc via commandline

For automatition or working with third party programs it may be usefull, to open the datalog.ccmc from outside of IPEmotion. To do so, you may use the Windows command line (cmd.exe).

Inside the commandline type in the command:

IPEmotion.exe

followed by the path of your \*.ccmc file in double quotes.

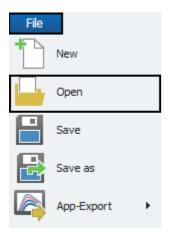
An example for what your commandline prompt should look like:

IPEmotion.exe "D:\tmp\Logger-1.ccmc"

#### 4.5.6 Opening sub configurations

When within the "Signals" tab in IPEmotion, you can open an existing sub configuration via the "Open" dialog. This will open the entire sub configuration inside the "Signals" tab and allows you to make changes to the sub configuration.

To do so, open the "File" menu and then click "Open".



In the next window it is important, that you first choose the "Subconfiguration file (\*.isz)" type on the bottom right, before you select the \*.isz file, you wish to import, and confirm with "Open".

			Х
v ⊙	"Configuration" of	lurchsuchen	9
		= 🕶 🔟	?
nderungsdatum 1	Гур	Größe	
9.03.2019 14:42	SZ-Datei	5 KB	
	Cub and Gameria	- El- (* :)	
~	IPEmotion config IPEmotion acqui System file (*.isf;	guration file (*.i sition configura *.ccmc)	
	~	IPEmotion config IPEmotion acqui System file (*.isf;	Subconfiguration file (*.isz)           IPEmotion configuration file (*.ist)           IPEmotion acquisition configuration           System file (*.isf;*.ccmc)           Subconfiguration file (*.isz)



# 4.6 Online communication with the logger

There are several functions that require online communication between the logger and the pc via Ethernet. This section will explain how to set up the logger for online communication and also the different functions that require online communication.

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# 4.6.1 Communication settings

In order for online communication via Ethernet between The CAETEC Plugin for IPEmotion and a PC to work, it may be necessary to specify some communication settings. In order to do so, choose **Plugins** on the left side of the Options window and then press the small button with the blue wrench symbol to open the **Plugin-specific settings**.



In the "Options" tabsheet of the following window you will find a field called "Communication", containing all the relevant settings for online communication between a logger and a PC.



Options	Components		
General			
	Export requirements:	Error Free Configuration	
Ext	ended FlexRay namespace:		
	Auto attach external files:		
Communi	insting.		
Lommun			
	Use deprecated IP range:		
	Primary IP address:		
	Secondary IP address:	192.168.1.88	
	Alternate IP address:		
	User name:		
	Password:		

#### Use deprecated IP range

If activated, the secondary IP address will be used as primary IP address. This setting affects the following configurations:

- Front channels, ETH channels and openABK channels on ARCOS 1.5
- Internal channels on ARCOS 1.0 and  $\mu cros$



At the moment IPEmotion is not capable of displaying that the primary and secondary IP address have been switched, when the function "Use deprecated IP range" has been acitvated. Nevertheless, if the function has been activated, secondary IP address will function as primary IP address and this should be kept in mind.

## Primary IP address

Primary IP address for communication with a logger. This IP address cannot be changed.

#### Secondary IP address

Secondary IP address for communication with a logger. This IP address cannot be changed.

#### Alternative IP address

If a logger is communicating on a user-specific IP address, type in this address here to ensure correct communication between the logger and the PC.

#### User name and Password

If a logger is protected via user name and password, type them in here to ensure correct communication between the logger and the PC.



# 4.6.2 Online functions

The online functions provided by the plugin can be found in the Ribbon and will be explained in the following.

## Detect

If a logger is connected to your PC, this function detects any connected logger and imports the configuration currently in use on the logger. This gives you the possibility to modify a pre-existing loggerconfiguration without the need of setting it up from scratch.

If there is no valid configuration in use on the connected logger, the plugin will detect all the available interfaces of the logger and adjust the measurement task tree elements accordingly.



If a logger is configured with a user-specific IP or protected with user name and password, it may be necessary, to edit the communication settings of the plugin first. Instruction on these settings can be found here  $(\rightarrow 4.6.1)$ .

## Initialize

If a logger is connected to your PC, this function exports the configuration currently in use in IPEmotion to the logger. During export the configuration will be checked for validity and give notice if any errors occurr.



If a logger is configured with a user-specific IP or protected with user name and password, it may be necessary, to edit the communication settings of the plugin first. Instruction on these settings can be found here  $(\rightarrow 4.6.1)$ .



#### Reset

If a logger is connected to your PC, this function deploys a basic configuration compatible with your logger model to the logger.

If a logger is configured with a user-specific IP or protected with user name and password, it may be necessary, to edit the communication settings of the plugin first. Instruction on these settings can be found here  $(\rightarrow 4.6.1)$ .

## 4.6.3 Licence information

If a logger is connected to the PC, it is possible for the plugin, to access that logger's licence information. Thus you can findout which licence keys are currently installed on your logger and which are still needed for your current configuration to function properly.

To read the licence information out, select your system in the measurement task tree (the topmost element), click the "Functions" button in the Ribbon and then choose "Licence information".



If a logger is configured with a user-specific IP or protected with user name and password, it may be necessary, to edit the communication settings of the plugin first. Instruction on these settings can be found here (to3.2.2).



### 4.6.4 Licence check

If a logger is connectet to the PC, it is possible for the plugin, to check whether all the necessary licences for your current configuration are installed on the logger.

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To perform a licence check, select your system in the measurement task tree (the topmost element), click the "Functions" button in the Ribbon and then choose "Licence check".





If a logger is configured with a user-specific IP or protected with user name and password, it may be necessary, to edit the communication settings of the plugin first. Instruction on these settings can be found here (to3.2.2).



# 4.7 Changing a system's default tree elements

The tree elements available by default for a given system are merely a preference, which can be adjusted via the measurement task tree. If you see, that you usually use 8 instead of 4 CAN busses, you can determine this setting as your default for the currently used system type and the next time you set up a new logger system it will automatically start with your new default settings. To do so, you will first need to add or remove the desired components. (In this case we added another 4 CAN busses in order to get a total of 8).

CAETE(

/15.10.00.13558 Beta			Name	A	ctive	Description
Name	Σ	9				
	*	•	CAN 01		~	CAN interface
ARCOS 1.5 - dataLog	0		CAN 02		~	CAN interface
A CAN Interfaces	0		CAN 03		~	CAN interface
🛉 CAN 01	0		CAN 04		~	CAN interface
CAN 02 CAN 03 CAN 04 CAN 04 CAN 05 CAN 05	0		CAN 05		~	CAN interface
CAN 03	0		CAN 06		~	CAN interface
🚹 CAN 04	0		CAN 07		~	CAN interface
CAN 05	0		CAN 08		~	CAN interface
🚹 CAN 06	0					
CAN 00	0					
ETH Interfaces     Internal	0					
Internal     Front	0	4				
openABK	0	G	ieneral			
USB	0		Active:			
(x) Formulas	0	Active:				
Triggers	0		Name:	CAN Interfaces		
Logfile messages	0		Description:	All grouped CAN	l interfa	aces
Internal signals	0					
A Datasets	0		Reference:	CAN Interfaces		
Dataset	0					
🔺 🗬 🛛 Data transfer	0					
1 Transfer events	0					
A Connections	0 -					



In the next step you will have to right-click on the category of tree elements for which you wish to define your new default settings as shown below. Note: it will not work, if you right-click the single component or the system itself. Make sure to right-click the category, in this case the **CAN Interfaces** and then choose **Use as default**.

(AETE(

15.10.00.135	58 Beta					Name		Active	Description
lame				Σ	٩				
				*	•	CAN 01		~	CAN interface
🛛 🛖 🛛 ARC	OS 1.5 - dataLog			0		CAN 02		~	CAN interface
4	CAN Interfaces	0		0	Ц.	CAN 03		~	CAN interface
Ť	CAN 01	4	Compor	ients 🕨	·   -	CAN 04		~	CAN interface
1	CAN 02	E.	Change	into 🔹 🕨		CAN 05		~	CAN interface
Ť	CAN 03	B-	Function	ns 🕨	·   -	CAN 06		~	CAN interface
+	CAN 04	JL.				CAN 07		~	CAN interface
÷ • •	CAN 05 CAN 06	Å.				CAN 08		~	CAN interface
	CAN 06 CAN 07								
+	CAN 07	8	Use as o	default					
	ETH Interfaces	X	Cut	Ctrl+X					
	Internal	Ep	Сору	Ctrl+C					
ĕ	Front	ľĥ							
Ä	openABK	Ê.			Ge	eneral			
	USB		Delete			Active:	~		
	Formulas	$\square$				Name:	CAN Interfa		
<u>e</u>	Triggers	*	Clean		_	Name:	CAN Interna	ces	
	Logfile messages	2	Copy to	file		Description:	All grouped	CAN interfa	aces
<b>*</b> */	Internal signals	R	Paste fr	om file		Reference:			S 1.5 - dataLog
a 🚞	Datasets		Properti		-1-				
<b>i</b>	Dataset	-	rioperu		_				
	Data transfer			0					
	Transfer event	s		0					



# 4.8 Sub configurations

Sub configurations allow you to set up a partial configuration and export it as a sub configuration, that can then be used as a module in other configurations. This can be especially usefull when handling large fleets of vehicle, loggers or different configurations.

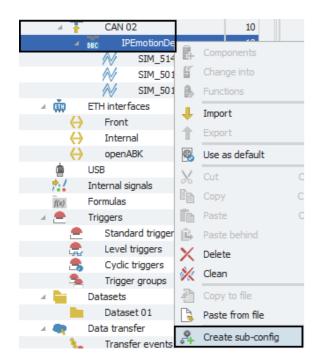
Sub configurations can be created for the following tree elements:

- Databases
  - ECU layer
  - Protocol layer, when no ECU layer is available
- Includes
- Manual messages
- Formulas
- Monitoring
  - Booleans
  - Limit Values
  - Ranges
- Trigger each trigger individually
  - Standard trigger
  - Limit trigger
  - Cyclic trigger
  - Group trigger
- Timelog on Signal group layer
  - Video Stream
  - Signal group
- Display on Signals layer



## 4.8.1 Creating a sub configuration

In order to create a sub configuration, right click on the desired tree element (in this case the "IPEmotionDemo" dbc on CAN 02) and select "Create sub-config".



In the following window you may choose a filepath, where to save the sub configuration and the filename. At creation of the sub configuration, two files with the same name will be created, the \*.isz file and the \*.cfginclude file.

The tree element that has been converted into a sub configuration will be marked with an arrow symbol.



A partial configuration, that has been converted into a sub configuration, will no longer be automatically transferred to the logger at export, although it will still be shown as a sub configuration in the measeurement task tree. In order for any sub configuration to be transferred, the \*.cfginclude file, which has been created at creation of the sub configuration, must be included via the "Includes" function. This will be explained in the following.



## 4.8.2 The \*.isz and the \*.cfginclude files

As mentioned earlier, creating a sub configuration will result in two different files with the same name. The \*.isz file and the \*.cfginclude file. These two files have different functions which will be explained here.

#### 4.8.2.1 The \*.isz file

The \*.isz file ist the partial IPEmotion configuration, which you need in order to modify the existing sub configuration. In order to modify the sub configuration, open the \*.isz file in IPEmotion, make the desired changes and save it. Once the \*.isz file has been modified and saved, the changes will be applied to the linked \*.cfginclude file as well.

For instructions on how to open a sub configuration in IPEmotion please refer to ( $\rightarrow$ 4.5.6).



At the moment it is not possible to save an \*.isz file, that has just been modified, using the "Save as" function. Please use the "Save" function.

## 4.8.2.2 The \*.cfginclude file

The \*.cfginclude file, is the part of the sub configuration which will later be transferred to the logger. It is a regular include file, as described in the chapter "Includes".

This is also the part of your sub configuration which can be included in other configurations using the includes function. That means if you have created a sub configuration and whish to include this sub configuration in one of your configurations, you will need to include the \*.cfginclude file using the "Includes" function.

For instructions on "Includes" please refert to the respective chapter ( $\rightarrow$ 9).

#### 4.8.3 Adding new tree elements to an existingg sub configurations

It is possible to add new tree elements to an existing sub configuration. To do so, open the sub configuration in IPEmotion and then make your changes in the desired tree elemenet. Once the desired tree element is configured properly, you can then righclick on it and select "Create sub-config".

USB USB	😤 Create sub-config
📩 Internal signals	фт -
f(x) Formulas	🖧 Link to sub-config
🛛 🚔 Triggers	😤 Unlink sub-config
🔺 🚔 🛛 Standard triggers	🖏 Properties
🚔 Standard trigge	A Hoperses
🚍 Level triggers	0 Activ

In the following window choose the sub configuration file (\*.isz) on which you are currently working and confirm pressing "Save". This will not result in overwriting the existing sub configuration, but rather will the modification be added to the exisiting sub configuration.





🙈 Speichern unter				×
$\leftarrow \rightarrow \cdot \uparrow$	« IPETRONIK > IPEmotion > Configuration	~	"Configuration"	durchsuchen 🔎
Organisieren 🔻	Neuer Ordner			· · · · · · · · · · · · · · · · · · ·
a OneDrive	^ Name	Änderungsdatum	Тур	Größe
💻 Dieser PC	IPEmotionDemo.isz	19.03.2019 15:37	ISZ-Datei	5 KB
🗊 3D-Objekte				
📰 Bilder				
📃 Desktop				
🚆 Dokumente				
🖊 Downloads				
🁌 Musik				
Videos				
🏰 Lokaler Daten	trä 🗸			
Dateiname:	IPEmotionDemo.isz			~
Dateityp:	(*.isz)			~
∧ Ordner ausblende	n		Speichern	Abbrechen .:

#### 4.8.4 Unlinking tree elements from existing sub configurations

If you have an existing sub configuration and wish, that one of the included tree elements is not part of the sub configuration any longer, this can be achieved via the "Unlink subconfig" function.

In order to do so, open the sub configuration file (\*.isz) in IPEmotion, rightclick on the tree element, that is not supposed to be part of the sub configuration any longer, choose "Unlink sub-config" and then save the sub configuration.

The "Unlink sub-config" function also allows you to revert a tree element, which has previously been converted into a sub configuration. As soon as you apply the "Unlink subconfig" function, the respective tree element will be part of the main configuration again.

🛛 🚔 Triggers	🕺 Unlink sub-config
🔺 🚔 🛛 Standard triggers	Properties
🔩 Standard trigger (	0
🚍 Level triggers	0

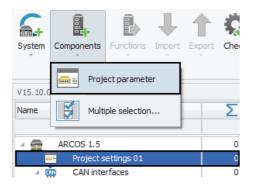


# 5 Project settings

"Project settings" allow you to include project parameters such as company name, serial number, project name etc. in your Configuration. It is also possible to create a set of project settings, specific for a dataset. That way, you can define different project parameters for different datasets. Please refer to the section "Dataset Project settings" ( $\rightarrow$ 12.4).

# 5.1 Adding project parameters

It is possible, to add user-specific project parameters in addition to the default project parameters. To do so, select the "Project settings" element in the measurement task tree, select the "Components" button in the Ribbon and then choose "Project parameter".



The new parameter will appear in the respective "Project settings xx'' Grid area as customizable parameter in the table.

	File name	
	Date	27.06.2018 10:18:39
<i>0</i> .	Project parameter 14	



# 5.2 Assigning a template of project parameters

It is also possible, to assign a template which contains a predefined set of user-specific project parameters. To do so, right-click on the "Project settings" tree element and then choose "Assign template".

V15.10.01.17504 Beta			
Name			Σ
4 🛖 ARCOS 1.5			0
Project setting	â	Companya	0
A m CAN interfaces	4	Components	<b>۰</b> و
T CAN 01	E.	Change into	► D
T CAN 02	8	Functions	► D
🔺 🧰 🛛 ETH interfaces	÷.	Import	D
🔶 Internal	Υ.		0
🔶 Front	T	Export	) ×
🔶 openABK		Assign templat	te 0
USB	65	Use as default	. 0
📥 🖊 🛛 Takanaal atawal		use as delaut	

In the following window you may choose the template file and confirm wit "Open". The file type needs to be .xml.

Pa Öffnen							x
COV VIETRONIK > IPEmotion	► P	rojectTemplate 🕨 EDR	•	€ EDR durchsu	chen		٩
Organisieren 🔻 Neuer Ordner					· · · · · ·		0
🖳 Zuletzt besucht	*	Name		Änderungsdatum	Тур		
🗃 Bibliotheken		projectPar.xml		08.05.2017 17:58	XML-E	)okumen	t
<ul> <li>■ Bilder</li> <li>■ Dokumente</li> <li>→ Musik</li> <li>■ Subversion</li> <li>■ Videos</li> <li>✓ Heimnetzgruppe</li> </ul>	II						
👰 Computer 🍇 Lokaler Datenträger (C:)							
👝 Lokaler Datenträger (K:)	-	•					•
Dateiname: projectPa	ır.xml			✓ projectPar (projectPar (		ml) (prc brechen	5

The CAETEC dataLog PlugIn for IPEmotion currently supports two types of templates, the **"EDR"** type and the **"Feger"** type. Both templates are installed with the plugin in the format "projectPar.xml" and can be found in the plugin's installation directory under "UserData/ProjectTemplate".

If at dataset creation either of these two template types is assigned, the dataset will be treated especially.



# 5.3 Tree elements for Project settings

Including "Project settings" in your configuration will add one new tree element. The tree element is labeled **"Project settings"**.

V15.10.01.17504 Beta	
Name	Σ
ARCOS 1.5	0
Project settings 01	0
A 🧰 CAN interfaces	0

# 5.4 Grid area for Project settings

If the "Project settings" element is selected in the Measurement task tree, the grid area will provide you with a table, that allows you to access all default or previously defined user-specific projet parameters.

	Name	Value
۴		
•	Company name	
	Serial number	
	Manufacturer	
	Project name	
	Project manager name	
	E-mail address project manager	
	User	
	E-mail address user	
	User login	bachl
	Description	
	IPEmotion version	V08.00.01
	File name	
	Date	27.06.2018 10:18:39
	Project parameter 14	



# 5.5 Details area for Project settings

If the "Project settings" element has been selected in the measurement task tree, additional settings are available in the details area.

# General

This tab provides general settings for the selected Project settings file.

General Info	
Active:	
Name:	Project settings 01
Description:	Project settings
Reference:	Project settings 01/ARCOS 1.5

• Name

Give a user-defined Name to the selected formula/signal.

• Description

Give a user-defined description to the selected formula/signal.

• Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

## Info

Tells you the type of template that has been assigned.



# 5.6 Using project parameters as variables in CAETEC dataLog PlugIn

If project settings have been added to your configuration, the Keys of these project settings can be used as variables in some text fields. This can be helpful if the same Parameter (e.g. "VehicleID") should be used in many different contexts. It is then enough, to define a value for that key. Whenever that key is used as a variable in the right context, at export of the datalog.ccmc it will be replaced with the corresponding value.

To use this feature, select the "Project settings" interface in the measurement task tree and navigate to the grid area. Access the column chooser ( $\rightarrow$ 4.3.1) and add the "Key" column to the grid area.

	T HILESS T VIE	Ŷ	
	Name	Value	
9	Key	Ŷ	
	Company name		
	Project name		
	Project manager name		
	E-Mail address project manager		
	User		
	E-Mail address user		
	Description		Customization
	Author		Key
	Department		
	Subject		
	Chassis ID		
•	Vehide ID		
	Description		

This will add a new column with the exact keys, that can be used. Now a corresponding value has to be defined for the key you which to use as variable. Click in the corresponding "Value" field for the desired key (e.g. **"VehicleID"** and type in the Value that shall be used (e.g. "Example Vehicle ID").

	Name	Key	Value
٩			
	Company name	Company	
	Project name	Project	
	Project manager name	AttendantName	
	E-Mail address project manager	AttendantMail	
	User	UserName	
	E-Mail address user	UserMail	
	Description	Description0	
	Author	Author	
	Department	Department	
	Subject	Subject	
	Chassis ID	Vehicle	
I	Vehicle ID	VehideID	Example Vehide ID
	Description	Description 1	

The term "VehicleID" can now be used as a variable in certain text fields and will be replaced with the value "Example Vehicle ID" in the datalog.ccmc.



The syntax for variables is the following:

Variable	Value written in data- log.ccmc
<key></key>	"Value"
<vehicleid></vehicleid>	"Example Vehicle ID"



Wherever it is possible to use project parameters as variables, this maual will point that with an inforamtion box.

# 6 Signal Acquisition

# 6.1 CAN channels

All the CAN channels for your system are located in the tree element "CAN interfaces". There are two types of CAN channels, physical **"CAN"** channels and **"Virtual CAN"** channels.

According to the default settings, the tree element "CAN interfaces" will include a preset number of CAN channels. By clicking the tree element CAN Interfaces you will see all of its channels and signals in the grid area as well as a tab called **General** in the **Details area** which allows you to set a name and description. These settings apply to the entire element "CAN interfaces".

In the following will be described how to add CAN channels and adjust their settings  $(\rightarrow 6.1.3)$ .

	quisition	View Data mana		) 🕐 🌇 🦫 - = Reporting Info	IPEmotion					•
ystem Components Functions Import	1	k Adjust	alize Display De	tais						0
5. 10.00. 13558 Beta		Name	Active		Channel number	Wake On CAN Mode	Baud rate	Normal mode	Timeout	Wake Or
ame	Σ	Υ								
	~ ~	▶ CAN 01	~	CAN interface		1 Disabled	500 kBd		0 s	
ARCOS 1.5 - dataLog		CAN 02	~	CAN interface		2 Disabled	500 kBc		0 s	
ARCOS 1.5 - dataLog A CAN Interfaces	0	CAN 02 CAN 03	~	CAN interface		3 Disabled	500 kBc		0s	
CAN 01	0	CAN 04	·	CAN interface		4 Disabled	500 kBc		0 s	
CAN 02	0	CAN U4	v	CANINENALE		4 Disableu	500 KBC		05	
CAN 03	0									
CAN 04	0									
ETH Interfaces	0									
(··) Internal	0									
Front	0									
openABK	0									
ISB USB	0									
(iv) Formulas	0	4								
Triggers	0									
Logfile messages	0	General								
1 Internal signals	0	Active: 🗸								
🗉 🚞 Datasets	0	Namo	AN Interfaces							
Dataset	0									
🔺 🜒 🛛 Data transfer	0	Description: Al	grouped CAN interf	faces						
	0	Reference: C								
🐛 Transfer events										
<ul> <li>Transfer events</li> <li>Connections</li> <li>USB</li> </ul>	0									



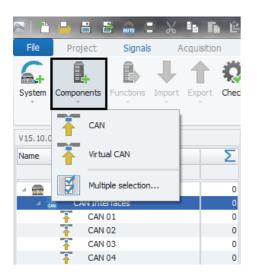
# 6.1.1 Storage method

In order to store all incoming traffic on a CAN channel use a bus tracing method for storage. Please refer to ( $\rightarrow$  12.9).



# 6.1.2 Adding CAN channels

CAN channels can be added by selecting the tree element **"CAN interfaces"**, then clicking the **"Components"** button and finally choosing the desired type of CAN channel you wish to add.



# • CAN

Adds a CAN channel that corresponds to a physical CAN channel of your logger. For instructions on CAN settings refer to  $(\rightarrow 6.1.3)$ .

## • Virtual CAN

Adds a virtual CAN channel. For instructions on Virutal CAN settings refer to  $(\rightarrow 6.1.4)$ .

**Multiple selection** Allows you to add multiple CAN channels of both types at the same time. To do so set the counter for each type to the desired number of channels that you wish to add as marked in the figure below.

IPEm	otion: Componen	ts selection - CAN Inte	rfaces	×
Count	Symbol	Туре	<ul> <li>Description</li> </ul>	
	3 🌲 🋛 🋉	CAN	CAN interface	
	2 🚹	Virtual CAN	Virtual CAN interface	
				OK Cancel



# 6.1.3 CAN settings

By selecting one of the CAN channels in the tree you will be able to define this channel's settings in the details area.

15.10.00.13558 Beta		Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
lame	۶	?							
ARCOS 1.5 - dataLog	0								
CAN Interfaces	0								
T CAN 01	0								
AN 02	0								
👬 CAN 03	0								
👬 CAN 04	0								
🔺 🎬 ETH Interfaces	0								
<ul> <li>Internal</li> </ul>	0								
💮 Front	0								
openABK	0								
i USB	0								
f(x) Formulas	0								
E Triggers	0	Ceneral CAN	Wake Op CAN Harr						
Logfile messages	0			iware					
	0	Active:	<i>s</i>						
	0	Name:	CAN 01						
	-								
	-	Description:	CAN interface						
	-	Reference:	CAN 01/ARCOS 1.5 - d	ataLog					
_	-								
USB	0								
CAN 04 ETH Interfaces internal Front USB USB Formulas Triggers Logfile messages Internal signals		Active: Name: Description:	CAN 01 CAN interface						

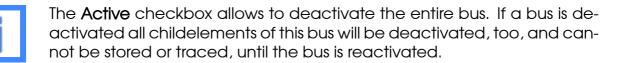


The same settings described in this section as part of the Details area can also be adjusted when selecting the tree element **CAN interfaces** and then directly changing the desired setting in the respective field of the **Grid area**.



## 6.1.3.1 General

This tab allows you to give a user specific name for the selected CAN channel if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



General CAN	Wake On CAN Hardware							
Active:	V							
Name:	e: CAN 01							
Description:	CAN interface							
Reference:	CAN 01/ARCOS 1.5 - dataLog							



# 6.1.3.2 CAN

## Baud rate

The dropdown menu Baud rate allows you to set the Baud rate for the selected CAN channel. The baud rate defines the speed in bits/second at which data can be transmitted through the CAN bus. The speed muss be adapted to the source. Only if all the users on the bus are set at the same rate, is transfer possible.

#### Normal mode

The checkbox Normal mode allows you to determine whether the CAN channel may communicate or is in silent mode. If the checkbox is marked, the channel may communicate, if the checkbox is not marked, the channel is in silent mode.

## CAN FD

This option is not supported by this plugin

#### Data rate

This option is not supported by this plugin

# 6.1.3.3 Wake On CAN

#### Timeout

For Wake on CAN, timeout has a special significance. It defines how long a waking channel must be inactive to be recognized so and therefore allow for the logger to shut down. If timeout is recognized, an entry is made in the log file and an error message with an alert appears on the display, which has to be acknowledged.



## Mode

This dropdwon menu allows you to set the wake-up function for your selected CAN channel.

Wake on CAN type	Characteristics						
Disabled	No start on CAN messages, lowest energy consumption.						
Enabled	Start on a CAN message, with first mes- sages lost; low energy consumption.						
Enabled (no message lost)	Start on CAN message, with no mes- sage lost; slightly higher idle current.						
Keep awake	The logger starts with Clamp 15, but only shuts down if all the awakening condi- tions (Clamp 15 and WakeOnX) are no longer fullfilled.						

## CAN ID - Settings for starting on a specific CAN ID

The CAN ID consists of two fields in the "Wake on CAN" tab of the CAN channel's details area: The **"CAN identifier"** on the left and the **"CAN ID bitmask"** on the right.

CAN ID: std 0 h std 0	d
-----------------------	---

The aim of this setting is to wake the logger with a message having a specific ID (or group of IDs), regardless of what the content of the message is. In order to do so, you can define a **"CAN identifier"** and a **"CAN ID bitmask"** to limit the identifier. Both parameters are used in their binary form. The "CAN ID bitmask" defines (or masks) the bit positions of a message ID that are to be applied. The "CAN identifier" specifies the contents that must exist at these bit positions in order for a start to take place.

Both fields can be defined as **"standard CAN ID"** or **"extended CAN ID"** by clicking the button in the left corner of the field. Both fields can process and show the entered number in its decimal or hexadecimal form. To switch between decimal or hexadecimal just click the button in the right corner of the field as marked in the figure above.



The decimal number is processed in the logger in its binary form and if the number set for the "CAN ID bitmask" = 0, the logger will start on any message.

Example: CAN identifier = 22 (binary = 10110) CAN ID bitmask = 28 (binary = 11100)

In other words, the mask (CAN ID bitmask) specifies that, to start the logger, given values are expected at the positions Bit2, Bit3, Bit4. All other values are irrelevant ("x"). The CAN identifier calls for Bit2 to be "1", Bit3 to be "0" and Bit4 to be "1".

Changes and errors excepted.



#### 6.1 CAN CHANNELS

The following table lists the positions for an 11-bit CAN identifier (in red the masked positions, the numbers signifying the expected values).

Bit10	Bit9	Bit8	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit 1	BitO
X	X	X	X	X	X	1	0	1	Х	X

Example of values of a CAN ID that would start the logger in this configuration:

Bit10	Bit9	Bit8	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit 1	BitO	CAN-ID (dec)
		1	0	0	0	1	0	1	0	1	277
				1	0	1	0	1	1	1	87
1	0	0	0	0	0	1	0	1	0	0	1044
			1	1	1	1	0	1	1	1	247
			1	0	0	1	0	1	1	0	150
						1	0	1	0	0	20
						1	0	1	0	1	21

Values of a CAN ID that would **NOT** start the logger in this configuration (example):

Bit10	Bit9	Bit8	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit 1	BitO	CAN-ID (dec)
		1	0	0	0	1	1	0	0	1	281

### Datafield - Settings for starting on a specific message value of a CAN ID

The Datafield consists of two fields in the "Wake on CAN" tab of the CAN channel's details area: The **"Datafield content"** field, which will contain the **"Datafield content value"** on the left and the **"Datafield bitmask"** on the right.

Datafield: 0 d 0 d

The aim of this setting is to wake the logger with a given content of a message with a particular ID (or a group of IDs).

After defining the ID that is supposed to start the logger, you can follow the above pattern to additionally specify which value within the message of the ID is to be an additional requirement for start. The entire 64-bit message is considered, single bits of which can be defined as start conditions. (In order to specify the values, it is necessary to decode the binary structure of the message. There is no DBC file assistance available here.)

A **"Datafield bitmask"** defines (masks) which bit positions of a message are to be applied. A "1" marks the bit positions to be used. Positions coded "0" are ignored. The "Datafield content value" specifies the contents checked in the mask by the logger. If "Datafield content value" writes "1" (or "0") in the positions of the mask (Datafield bitmask), then the mask positions of the ID must contain the identical values; i.e. "1" (or "0") too, otherwise the logger is not started.

Both fields can process and show the entered number in its binary, decimal or hexadeci-

Changes and errors excepted.



mal form. To switch between binary, decimal or hexadecimal just click the button in the right corner of the field as marked in the figure above.

The decimal number is processed in the logger in binary form and if the number set for the "Datafield bitmask" = 0, the logger will start on any message. When the number entered in the "Datafield bitmask" is considered in binary form,

"1" defines a bit position that is considered in filtering,

"0" means filtering ignored this bit position.

Example:

Wake on CAN trigger raw value = 22 (binary = 10110) Wake on CAN raw value mask = 20 (binary = 10100)

The mask "Datafield bitmask" specifies that, the logger is only started if certain values are found at the positions Bit2 and Bit4. All other values are irrelevant ("x"). "Datafield content value" calls for Bit2 to be "0" and Bit4 to be "1". The following table lists the positions for a 64-bit message (with the masked positions colored red and the numbers signifying the expected values).

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit 1	BitO
X	X	X	1	X	0	Х	X

Message values that would start the logger in this configuration (example):

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit 1	BitO	Message value (dec)
			1	0	0	0	1	17
	1	0	1	1	0	1	1	27
			1	0	0	0	0	16
1	1	1	1	1	0	1	1	251
1	0	0	1	0	0	1	0	146
			1	1	0	0	0	24

Negative example of message values that would NOT start the logger in this configuration:

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit 1	BitO	Message value (dec)
0	0	0	1	1	1	0	0	28

## Settings for starting on a specific signal

The settings described in the previous paragraphs apply to entire messages. This section explains how to apply these settings to a specific signal contained in a message. It describes the procedure for deriving the required WoC parameters from the physical value of a signal. Since a simple formula such as "signal > 30" is not possible, it is necessary to define the start condition at the bit level. The numeric format is important, as well. The order in which the bit positions are counted depends on the numeric format (e.g., Intel



or Motorola). Please bear in mind, when selecting the signal and a particular start value, that the start condition must be met during the entire measurement run. Remember: The start signal is also the stop signal. If the start signal is missing for a set period of time, the logger is stopped. This makes state bits good start signals. Signals such as temperature signals that generally fluctuate, are only suitable providing the definition of the start condition is sufficiently vague. Here vague means that not a specific bit combination switches on the logger, but that a range of bit combinations is possible. When defining filters, be sure to avoid gaps between the significant mask positions (marked), otherwise the covered range of values will also have gaps (see Filter 4), which would shut down the logger. Several filters serve as examples below. The table shows which values start the logger with which filter. In the column for each filter, these values are marked with an "X".

#### Filter 1:

Datafield content value = 16 (binary = 10000) Datafield bitmask = 24 (binary = 11000)

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit 1	BitO
X	X	X	1	0	X	Х	X

#### Filter 2:

Datafield content value = 24 (binary = 11000) Datafield bitmask = 24 (binary = 11000)

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit 1	BitO
X	X	X	1	1	Х	Х	Х

#### Filter 3:

Datafield content value = 16 (binary = 10000) Datafield bitmask = 16 (binary = 10000)

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit 1	BitO
X	X	X	1	X	X	X	X

Filter 4: (negative example)

Datafield content value = 18 (binary = 10010) Datafield bitmask = 18 (binary = 10010)

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit 1	BitO
X	X	X	1	X	X	1	X



Dec. value	Binary value	Filter 1	Filter 2	Filter 3	Filter 4
15	0000001111				
16	0000010000	X		X	
17	0000010001	X		X	
18	0000010010	X		X	X
19	0000010011	X		X	X
20	0000010100	X		X	
21	0000010101	X		X	
22	0000010110	X		X	X
23	0000010111	X		X	X
24	0000011000		X	X	
25	0000011001		X	X	
26	0000011010		X	X	X
27	0000011011		X	X	X
28	0000011100		X	X	
29	0000011101		X	X	
30	0000011110		X	X	X
31	0000011111		X	X	X
32	0000100000				

The following example of a temperature in Intel format illustrates how to derive the filter settings.

#### Example

With the logger operating in the temperature range of approx. 30 - 40 °C, the following signal definition is given:

Deriving Wake on CAN "Datafield bitmask" and Wake on CAN "Datafield content value":

First you use the limit values to derive the raw value and thus the binary value of the operating range.

$$Datafield content value_{30 degree} \frac{value - Offset}{Scale} = \frac{30 - (-10)}{0.1} = 400 = Binary : 110010000$$

$$Data field content value_{40 degree} \frac{value - Offset}{Scale} = \frac{40 - (-10)}{0.1} = 500 = Binary : 111110100$$

The highest bit positions that are identical for both values, without a gap, are the two on the left, which have the value 1. This yields, as mask and filter binary: 1 1000 0000

So the lower bound for the Datafield content value is:

- binary 1 1000 0000
- decimal 384
- physical 28,4°C

Changes and errors excepted.



So the upper bound for the Datafield content value is:

- binary 1 1111 1111
- decimal 511
- physical 41,1°C

Since the value has 9, but the signal 16 Bit, the 7 most significant Bits have to be 0. This is achieved by the Datafield bitmask.

## Filter:

Wake on CAN Datafield content value = 384 (binary = 0000 0001 1000 0000) Wake on CAN Datafield bitmask = 65408 (binary = 1111 1111 1000 0000)

ſ	Bit															
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	0	0	0	0	0	1	1	X	X	X	X	X	X	X

Since, however, the signal lies in the middle of the 64 bit-wide message (bit offset=16), the bit positions to the right of the signal in the message must be filled with "0" (left is equal to Bit0 in the CAN-traffic).

		Bit-C	offset			T_Au	ssen					Don't	care			
Binary	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
Intel:	LSB							MSB								
Datafield content value:	0000	0000	0000	0000	0000	1000	0001	0000	0000	0000	0000	0000	0000	0000	0000	0000
Hex:	0	0	0	0	0	8	1	0	0	0	0	0	0	0	0	0
Datafield bitmask:	0000	0000	0000	0000	0000	1000	1111	1111	0000	0000	0000	0000	0000	0000	0000	0000
Hex:	0	0	0	0	0	8	F	F	0	0	0	0	0	0	0	0

So the Datafield content value is equal to: Datafield content value (hex) = 0xFF800000 **Datafield content value (dec) = 4,286,578,688** 

So the mask is equal to: Datafield bitmask (hex) = 0x1800000 **Datafield bitmask (dec) = 25,165,824** 

Wake on CAN Datafield content value = Wake on CAN Datafield bitmask

## Deriving Wake on CAN "CAN identifier" and "CAN ID bitmask":

The precise ID of the message is to be found – i.e. all the positions of the ID that are not leading zeros are significant. All the significant positions are to be assigned the value of the ID.

This means:

## CAN identifier = Message D = 100

Deriving the significant bit positions of the ID: ID (dec) = 100 => ID (bin) = 1100100 The ID also has 7 significant positions. So the mask must also be 7 bits long. All positions must be assigned "1". "CAN ID bitmask" = 1111111 = 127 (dec)

Changes and errors excepted.



Each node can thus be assigned individual start settings. Remember: During the booting phase, at the node that started the logger, the WoC LED on the front plate of the interface blinks quickly for approximately ten seconds.

Even if WoC (Wake on CAN) is set as start condition the logger starts on clamp 15. So start on clamp 15 has priority over WoC. This is necessary to have a fallback solution in case a start message or start value can no longer be sent.
If the logger was started with clamp 15, it can likewise only be shut down by "pulling" Clamp 15 – based on the principle, the source that starts, also stops – providing there is not simultaneously another wake condition (e.g. WoC) active.

# 6.1.3.4 Hardware (Channel number)

This tab allows you to set a **Channel number** for the selected CAN channel. This channel number has to be unique within the CAN interface.

General	CAN	Wake 0	On CAN	Hardware
	Channel r	number:	1	



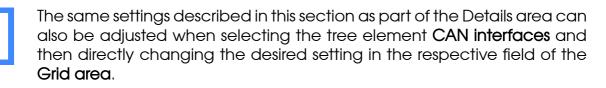
For better orientation and in order to avoid confusion regarding Channelnumbers and -names, a Channels physical number can be found in the logger's **"Web Interface"** and set accordingly.



# 6.1.4 Virtual CAN settings

By selecting one of the Virtual CAN channels in the tree you will be able to define this channel's settings in the details area.

V15.10.00.13558 Beta			Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
Name	Σ	٩								
ARCOS 1.5 - dataLog	0									
CAN Interfaces	0									
CAN 01	0									
CAN 02	0									
CAN 03	0									
	0									
VIRTUAL CAN 05	0									
ETH Interfaces	0									
💮 Internal	0									
	0									
- openABK	0									
USB USB	0									
f(x) Formulas	0	Ge	eneral Hardwa	ro						
👚 Triggers	0	1 00								
Logfile messages	0		Active:	~						
1 Internal signals	0		Name:	VIRTUAL CAN 05						
A 🚞 Datasets	0			and towards to						
Dataset	0		Description:	Virtual CAN interface						
A 🗬 Data transfer	0		Reference:	VIRTUAL CAN 05/ARC	OS 1.5 - da	taLog				
1 Transfer events	0									
Connections	0									
USB	0									



## 6.1.4.1 General

This tab allows you to give a user specific name to your for the selected Virtual CAN channel if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed. The "Active" checkbox allows you to activate or deactivate the selected Virtual CAN channel.

General Hardw	are
Active:	V
Name:	VIRTUAL CAN 05
Description:	Virtual CAN interface
Reference:	VIRTUAL CAN 05/ARCOS 1.5 - dataLog



## 6.1.4.2 Hardware (Channel number)

This tab allows you to set a **Channel number** for the selected Virtual CAN channel. This channel number has to be uniqe within the CAN interface.

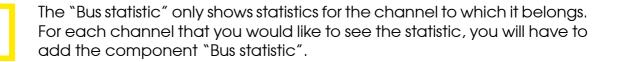
General Hardware	
Channel number: 5	



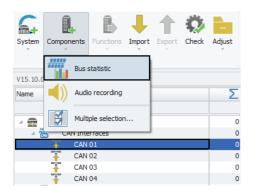
For better orientation and in order to avoid confusion regarding Channelnumbers and -names, a Channels physical number can be found in the logger's **"Web Interface"** and set accordingly.

## 6.1.5 CAN channel Bus statistic

The "Bus statistic" provides a range of statistics and status signals for the respective CAN channel. It contains information on the current state of the Bus, the Busload, as well as on the messages that have been received and errors that ocurred.



**6.1.5.1** Adding Bus statistics Select the channel in the tree for which you would like to add "Bus statistic", then click the "Components" button in the Ribbon and choose "Bus statistic".





**6.1.5.2** Bus statistic signals Once the component "Bus statistic" has been added to your channel, it will appear in the measurement task tree as a child element of this channel and the grid area will give you an overview of the available signals.

The signals included in "Bus statistics" are of the type "Internal signal" and may be adjusted in the same way. For more information on "Internal signals" please refer to ( $\rightarrow$ 6.22).

## Overview of signals

Subtype	Meaning	Unit
Controller state	nan= Channel not available 1= Bus on 2= Bus warning 3= Bus off	-
Busload (%)	Bus load of a CAN/LIN chan- nel	(%)
Number of messages	Number of messages since beginning of measurement	-
Message rate total	Current bus load	(frames/s)
Number of messages with standard ID	Number of messages with standard ID	-
Number of messages with ex- tended ID	Number of messages with ex- tended ID	-
Number of messages with re- mote standard ID	Number of messages with re- mote standard ID	-
Number of messages with re- mote extended ID	Number of messages with re- mote extended ID	-
Number of error frames	Number of error frames	-
Message rate of standard IDs	Messages with standard ID	(frames/s)
Message rate of extended IDs	Messages with extended ID	(frames/s)
Message rate of standard IDs	Messages with remote stan- dard ID	(frames/s)
Message rate of extended IDs	Messages with remote exten- ded ID	(frames/s)
Error frame rate	Average of errors per second	(frames/s)



# 6.2 CAN signals

## 6.2.1 Storage method

In order to store incoming signals on a CAN channel use one of the following signal storage methods.

- ATFX ( $\rightarrow$  12.6)
- MDF 4.0 ( $\rightarrow$  12.7)
- MDF 4.1 ( $\rightarrow$  12.8)

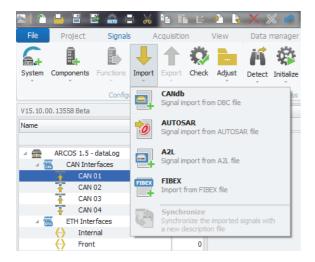
# 6.2.2 Importing CAN signals

This section explains how to import CAN signals. There are three different filetypes which can be used in order to import a single CAN signal or a group of CAN signals:

## CANdb (DBC file), Autosar and Fibex.

The import procedure for all of these filetypes is the same and will be explained using the example of the CANdb import.

To import Signals, select the CAN channel to which you wish to import your signal in the tree, click the **"Import"** button in the ribbon and then choose which filetype the **"description file"**, you wish to use for the import, has. For more information on the "description file" refer to  $(\rightarrow 6.2.4.1)$ .



#### 6.2 CAN SIGNALS

The following window lets you choose which file you wish to import. According to the filetype you have chosen earlier for your import, you will now be able to choose files of the respective filetype. The dropdown menu on the bottom right of the window shows you, which filetypes are available. Choose the file you wish to import and click **"Open"**.

Organisieren 👻 Neue	r Ordner			•	?
🛧 Favoriten 🔶	Name	Änderungsdatum	Тур	Größe	
🧮 Desktop	IPEmotionDemo.DBC	19.02.2017 09:47	DBC-Datei	2 KB	
🐌 Downloads	IPEmotionDemo_Fibex.xml	19.02.2017 09:47	XML-Dokument	27 KB	
📃 Zuletzt besucht 🔤	IPEmotionDemo_J1939.dbc	19.02.2017 09:47	DBC-Datei	9 KB	
E	IPEmotionDemoFD.DBC	19.02.2017 09:47	DBC-Datei	3 KB	
🥽 Bibliotheken	IPEspeed.dbc	19.02.2017 09:47	DBC-Datei	4 KB	
📔 Bilder	IPEspeed_from_V01_02_01.dbc	19.02.2017 09:47	DBC-Datei	4 KB	
Dokumente					
🎝 Musik					
📄 Subversion					
Videos 🗧					
🔞 Heimnetzgruppe					

Once you have opened your file, the **"Importer"** window will appear, that will present you with a range of importing options.

Name	Selection	Sampling rate	Physical range	Description	Project numbe Project versio	
					Protocol: FreeRu	nning 🔺
Pressure Abs		1 Hz	0 bar 2 bar		Protocol	FreeRunning
			-2 bar +2 bar		Signal count	
Pressure_Rel		1 Hz			CAN baud rate	Not specified
MAP		1 Hz	0 bar 3 bar		J1939	
TPS_Volt		1 Hz	-8 V +8 V		Message	
Front_left		1 Hz	-50 C +200 C		Name	SIM_51499999
Front_right		1 Hz	-50 C +200 C	•	CAN ID	std A h
Rear left		1 Hz	-50 C +200 C		Length	
Read right		1 Hz	-50 C +200 C		Sampling rate	1H
Exhaust_1		1 Hz	-50 C +1200 C		Description	
-					Sender name	IPETRONI
Exhaust_2		1 Hz	-50 C +1200 C		Cyclic	~
					Signal	
					Name	Pressure_Ab
					Display identif	
					Byte order	INTE 16-Bit integer un
					Data type	10-bit integer un
porter				•	Bit count	

In this dialog, all signals that can be imported from the description file are displayed. In the left table, all signals, where the "selection" checkboxes are selected, will be marked for import. You can either choose manually, which signals to import, you can use the "Select/Deselect all" button on the bottom left, or you can use a CSV-file to determine which signals are to be imported, by clicking "Select by CSV" on the bottom left.

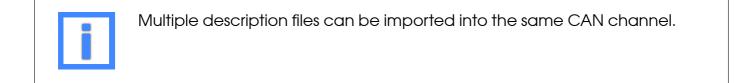
Changes and errors excepted.

## 6.2 CAN SIGNALS



In the right table the metadata, properties of the selected signals, the control unit and the protocol are displayed.

Once you have choosen all the signals you wish to import, click **"OK"** to complete the import procedure.



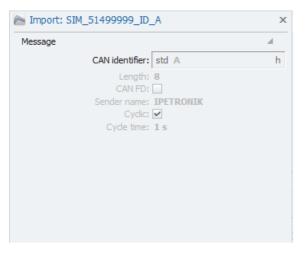


## 6.2.3 Import properties

The "Import properties" of a description file, Message or signal allow you to see certain properties such as the Data format, The CAN identifier, the Bit mask, the start bit, bit count and more. It shows the signal's properties as described by the description file.

General		
	Protocol: FreeRunning	
	File name: IPEmotionDemo.DBC	
	Directory: C:\Users\Public\Docun J1939: 🗌	nents\IP

Example for "Import properties" of a CAN description file



Example for "Import properties" of a CAN Message

Signal			
	Original name:	Pressure_Rel	
	Data format:	INTEL	$\overline{\nabla}$
	Bit count:	16	
	Start bit:	16	
	Bit mask:	FFFF	
	CAN identifier:	std A	h

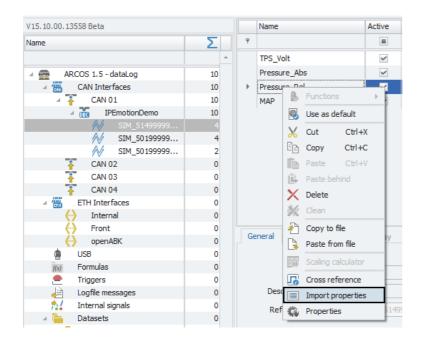
Example for "Import properties" of a CAN signal

#### 6.2 CAN SIGNALS





To access the "Import properties" rightclick on any desired description file, Message or signal and then choose "Import properties" from the resulting context menu.





## 6.2.4 Signal properties

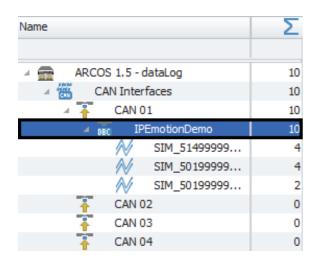
## 6.2.4.1 Tree elements for CAN signals

After having successfully imported the desired signals to your CAN channel, this channel will contain two new layers of child elements in the measurement task tree: The **"Description file"** and the **"Message"**.

## Description file

The "description file" is a database file which contains signal information and can be used to import those signals into a Signal channel in IPEmotion. The filetypes which are supported by the CAETEC Plugin for IPEmotion depend on the type of signal you wish to import.

The symbol in the left part of the tree element shows you the type of "description file" you imported (in this case a "DBC" file), then follows the name of the imported "description file" (in this case "IPEmotionDemo") and on the right is a number indicating how many signals the "description file" contains (in this case 10).

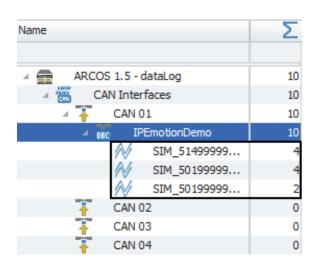




## Message

Each "description file" can contain one or more "Messages" (in this case 3), which then contain the actual signals. A "Message" can be found in the "Measurement task tree" as a child element of the "description file", it belongs to.

Each "Message" can, again, contain one or more signals (in this case the three "Messages" contain 4, 4 and 2 signals), which is indicated by the number on the right of the "Message's" name.



# 6.2.4.2 Grid area for CAN signals

In the "grid area" you will be presented with an overview of your selected CAN channel's signals. Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

## 6.2.4.3 Details area for CAN signals

The Details area shows settings either for the selected tree element ("description file" or "Message") or the selected signal in the grid area. In case a tree element is selected, the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).

In case a signal is selected in the grid area, the details area will contain additional tabs which will be explained in the following.

## General

Please refer to ( $\rightarrow$ 4.2.2).



# Format

This tab contains information and options regarding file format, tasks and Channel type.

General Format	Scaling Display Sig	gnal	
Data type			
Type:	8-Bit integer unsigned	Task: Default	Ŧ
NoValue / DefaultVa	lue		
Value:	+FullScale	<ul> <li>Deactivate NoValue and use Default Value</li> </ul>	
Channel type			
Input:	<b>~</b>	Output:	

## • Data type

This field tells you the type of data (in this case **"8-Bit integer unsigned"**) and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

## • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

# • Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.

## Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

General Format	Scaling Display Signal		
Sensor mode			
Mode:	Status	~	Scaling calculator
Sensor range			
Min:	0 -	Max: 1	Unit: 📃 🔻
Physical range			
Min:	0	Max: 1	Unit:



#### • Sensor Mode

The sensor mode tells the type of signal. It can be of different types such as "Status", "Voltage", "Frequenzy" or others. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.

#### • Sensor Range

Shows the raw value range of the signal.

#### • Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5** "Channel configuration and scaling".

#### Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General Format	Scaling Display Signal
Displaying area	
Min:	0 Max: 1
Formatting	
Decimal places:	Automatic 👻
Name	
Name:	10 ms sync event channel configured

#### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

#### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

#### • Name

Allows you to set a Name to be shown on a display.

## Limit values

This tab allows you to define limit values for a signal and what action to take upon a limit value violation.

General Format Scal	ng Display Limit values	Signal Signal che	ck				
Out of bound or invalid values							
Rejected value: will be dropped							
Valid ranges (Lower/Upper)			Invalid value	s (Physical/Raw)			
1: 🗌 0	0		1:	0	0	d	
2: 0	0		2:	0	0	d	
3: 0	0		3:	0	0	d	

## • Rejected value

Define what happens to a value, that has been rejected because it is out of bound or invalid. By default this value will be dropped. It can also be written as NaN.

## • Valid ranges (Lower/Upper)

Define up to three ranges of valid signal values. Activate a range in order to define its upper/lower value (datatype double). Range 2 can only be activated if range 1 is and range 3 can only be activated if range 2 is.

## Invalid values (Physical/Raw)

Define up to three invalid values. Activate an invalid value in order to define the physical value (datatype double) or raw value (datatype integer). If one of the two has been typed in, the other will be calculated according to the scale/offset settings in the scaling calculator.

Invalid value 2 can only be activated if invalid value 1 is and invalid value 3 can only be activated if invalid value 2 is.

For details on how to use the "Scaling calculator" please refer to the **IPEmotion Do**cumentation - Section 3.4.5 "Channel configuration and scaling".



# Signal

This tab allows you to define signal settings.

General Format Scal	ing Display Signal
Special function:	None •
Internal data type:	Double •
Signalnumber:	
Last value hold:	Until the next reboot 🔹
Timeout:	0 s
Namespace:	'CAN 01'::'SIM_51499999_ID_A'::'10'
	μζ.

## • Internal data type

Assign an internal data type to the signal. Available data types are **"Double"** and **"String"**.

## • Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

#### • Last value hold

Specify, for how long the last value of the signal will be hold.

#### • Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.

#### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.

#### Signal check

This tab allows you to activate "Signal check" for this signal. You may choose whether you wish to apply the global signal check settings to this signal or override the global settings with settings specific for this signal.

Global signal check settings have to be defined first. For information on how to do so and for general information on "Signal check" please refer to ( $\rightarrow$ 4.2.2).

General Format Sca	ling Display Signal	Signal check	Limit values
Use signal check:	¥		
Mode:	Global settings	+	
Start-trigger:			Select
Stop-trigger:			Select
Timeout:	30 s		



## 6.2.5 Manual messages / Manual signals

On CAN and CAN FD channels it is possible to set up a manual signal message which contains manually defined CAN signals. This allows you to define signals independently of a description file. You can use manual messages additionally to a description file or instead of a description file.

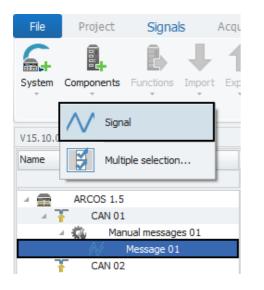
## 6.2.5.1 Adding manual messages and signals

In order to add a manual message to your CAN channel, select the desired channel in the measurement task tree, click the "Components" button in the Ribbon and then select "Manual message".





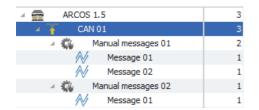
Once the manual message has been added, you can then add one or multiple manual signals to the message. To do so, select the newly created "Message xx" in the measurement task tree, click the "Components" button in the Ribbon and then select "Signal".



## 6.2.5.2 Tree elementes for manual messages

Adding a manual message to your system will add two new layers fo tree elements to the CAN channel. The first layer labeled "Manual messages xx" only serves for grouping together one or more manual messages. As an extra layer underneath you will find the actual manual message labeled "Message xx", which will contain your signals.

As you can see on the figure below, it is possible to have multiple "Manual message xx" layers as well as multiple "Message xx" layers per "Manual message xx". This allows for a more structured possibility of organizing manual signals.



### 6.2.5.3 Grid area for manual messages

In the "grid area" you will be presented with an overview of your selected message's signals. Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

As you can see in the figure below, if the "Manual message xx" layer is selected, the grid area will show the signals of all messages contained within the "Manual message xx". This may lead to multiple signals with the same name in the grid area.

V15.10.03.21609 Beta=			Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
Name	Σ	٩								
		•	Signal 01	~						
4 🛖 ARCOS 1.5	5		Signal 02	~		-32768	32767	-32768	32767	1 Hz
4 T CAN 01	5		Signal 03	~		-32768	32767	-32768	32767	1 Hz
🔺 🦚 🛛 Manual messages 01	4		Signal 01	~		-32768	32767	-32768	32767	1 Hz
Message 01	3									
Message 02	1									
🔺 🖏 🛛 Manual messages 02	1									
Message 01	1									

If you wish to only see the signals of a specific "Message xx'', select the desired "Message xx'' in the measurement task tree.



## 6.2.5.4 Details area for manual messages (defining a manual signal)

The details area provides settings regarding the messages and the signals. As the general functionality of manual signals is that of a regular CAN signal, please refer to the section "Details area for CAN signals" of this manual ( $\rightarrow$ 6.2.4.3).

Here will only be explained the settings that are specific for manual messages and signals.

#### Settings for manual messages

In order to access the settings for manual messages select the desired "Message xx" in the measurement task tree and navigate to the details area. General

Please refer to ( $\rightarrow$ 4.2.2).

#### Bus

This tab provides settings regarding the message itself. Here you determine the CAN ID of the message and its DLC, which determines the data byte volume of the message.

General Bus		
CAN-ID:	std 0 h	
DLC:	8	



## Settings for manual signals (defining a manual signal)

This part will explain how to define a manual signal. In order to access the settings for manual signals select the desired signal in the grid area and navigate to the details area and select the tab "Bits".

For instructions regarding the general signal settings please refer to the section "Details area for CAN signals" of this manual ( $\rightarrow$ 6.2.4.3).

General Format Scali	ng Display Bits Signal Signal check Limit values
Start bit:	0
Bit count:	16
Data format:	Intel 👻

## • Start bit

Define the the first bit of the signal within the datastream.

• Bit count

The bit count defines of how many bits a single sensor value of this signal is composed (it defines the length of the signals in bits).

## • Data format

The data format defines in which order the data bytes are sent.

# 6.3 CCP/XCP signals

#### 6.3.1 Storage method

In order to store incoming signals on a CAN channel use one of the following signal storage methods.

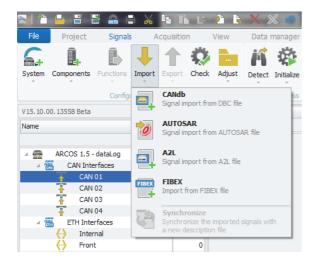
- ATFX ( $\rightarrow$  12.6)
- MDF 4.0 ( $\rightarrow$  12.7)
- MDF 4.1 ( $\rightarrow$  12.8)



## 6.3.2 Importing CCP/XCP signals

This section explains how to import CCP or XCP signals. The filetype associated with these signals is a "A2L file".

To import a CCP/XCP signal, select the CAN channel to which you wish to import your signal in the tree, click the **"Import"** button in the ribbon and then choose the "A2L" filetype for the import.





The following window lets you choose which file you wish to import. According to the filetype you have chosen earlier for your import, you will now only be able to choose files of the "A2L" filetype. Choose the file you wish to import and click **"Open"**.

🔁 Öffnen			A 1000		×
🕞 🖓 📕 « Öffentliche Dok	umente 🕨 IPETRONIK 🕨 IPEmotion 🕨 Im	port 👻	<ul> <li>✓</li> <li>✓</li></ul>	hsuchen	٩
Organisieren 👻 Neuer Ordne	er				
🔶 Favoriten	me	Änderungsdatum	Тур	Größe	
Desktop	IPEmotionDemo.a21	19.02.2017 09:47	A2L-Datei	85	KB
<ul> <li>⅔ Zuletzt besucht</li> <li>➡ Bibliotheken</li> <li>➡ Bilder</li> <li>➡ Dokumente</li> <li>➡ Musik</li> <li>➡ Subversion</li> <li>➡ Videos</li> <li>➡ Heimnetzgruppe</li> </ul>					
			✓ ASAM MCD- Öffnen	2MC (*.a2l)	<b>▼</b> chen

The following window lets you choose whether you want to import a "CCP" signal or a "XCP" signals. Choose the protocol you wish to import and click **"OK"**.

х

Once you have chosen the protocoll and confirmed, the **"Importer"** window will appear, that will present you with a range of importing options.

In this dialog, all signals that can be imported from the description file are displayed. In the left table, all signals, where the "selection" checkboxes are selected, will be marked for import. You can either choose manually, which signals to import, you can use the **"Select/Deselect all"** button on the bottom left, or you can use a CSV-file to determine which signals are to be imported, by clicking **"Select by CSV"** on the bottom left.

In the right table the metadata, properties of the selected signals, the control unit and the protocol are displayed.



Name	Selection	Sampling rate	Physical range	Description	-		
						Protocol: FreeRun	nning 🔺
Duran was Alex		1.1-	Ohan Ohan			Protocol	FreeRunning
_						Signal count	
_							Not specified
MAP		1 Hz	0 bar 3 bar			J1939	
TPS_Volt		1 Hz	-8 V +8 V			Message	*
Front_left		1 Hz	-50 C +200 C			Name	SIM_51499999
Front_right		1 Hz	-50 C +200 C			CAN ID	std A h
Rear left		1 Hz	-50 C +200 C			Length	
-		1 Hz	-50 C +200 C			Sampling rate	1 Hz
						Description	
-							IPETRONIK
Exhaust_2		1 Hz	-50 C +1200 C				<b>*</b>
						-	<u>ــــــــــــــــــــــــــــــــــــ</u>
							Pressure_Abs
							INTEL
						Bit count	16-Bit integer un 16
	Pressure_Abs Pressure_Rel MAP TPS_Volt Front_left	Pressure_Abs     Image: Constraint of the second seco	Pressure_Abs     1 Hz       Pressure_Rel     1 Hz       MAP     1 Hz       TPS_Volt     1 Hz       Front_left     1 Hz       Front_right     1 Hz       Rear_left     1 Hz       Read_right     1 Hz       Exhaust_1     1 Hz	Itz         Obar         2 bar           Pressure_Abs         1 Hz         -2 bar	Image: Market of the second	Pressure_Abs         1Hz         0 bar 2 bar           Pressure_Rel         1Hz         -2 bar +2 bar           MAP         1Hz         0 bar 3 bar           TPS_Volt         1Hz         -8 V +8 V           Front_left         1Hz         -50 C +200 C           Front_right         1Hz         -50 C +200 C           Rear_left         1Hz         -50 C +200 C           Read_right         1Hz         -50 C +200 C           Exhaust_1         1Hz         -50 C +200 C	Image: Non-Section of the section of the se

Once you have choosen all the signals you wish to import, click **"OK"** to complete the import procedure.

Depending on the protocol, a sampling rate or the DAQ list to use, can be assigned to the signals.

In the case of a protocol using DAQ lists (CCP, XCP), you can specify via the column selection dialog, if the signals are configured by the sampling rate or a DAQ list. To achieve this you should open the column selection dialog, via the context menu of the table header, and then drag the desired column ("sampling" or "DAQ list") from the column selection dialog to the table header. The other column is removed automatically.

If in a protocol based on DAQ lists, sampling rates are used for the signal configuration, during import the signals are assigned to the available DAQ list with the most suitable sampling rate.

In case of protocols supporting array signals, you can specify via the "split array" column whether all the signals of the array or just the first to be imported. If this column does not appear it can be moved from the column selection dialog into the table.



Multiple description files can be imported into the same CAN channel.



## 6.3.3 Import properties

The "Import properties" of an "ECU", "Description file", "Polling list", "DAQ list" or signal allow you to see certain properties such as the Data format, the Adress, the Bit mask, the start bit, bit count and more. It shows the properties as described by the description file.

General			
	File name:	IPEmotionDemo.a2l	
	Directory:	C:\Users\Public\Doc	ument.
	Version:	1.0	
	Description file:		
ECU EP	K identification:		
	EPK address:	0	h

Example for Import properties of a CCP/XCP ECU

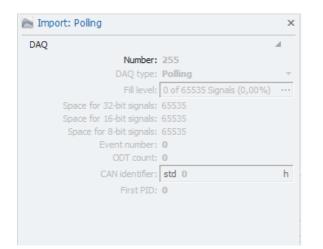
General	4
Protocol: (	
Version: 2	2.1
Data format: I	MOTOROLA
Bytes Only:	
Station ID:	12ED h
Seed & Key file:	
Seed & Key file: ECU	4
ECU	al std 7BC h
ECU CRO:	atd 7BC h std 7BD h

Example for Import properties of a CCP/XCP Description file

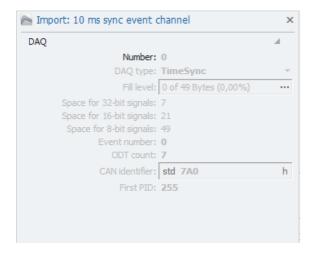
## 6.3 CCP/XCP SIGNALS



# **IPTRONIK**



#### Example for Import properties of a CCP/XCP Polling list



#### Example for signal properties of a CCP/XCP DAQ list



Example for Import properties of a CCP/XCP signal

#### 6.3.4 Signal properties

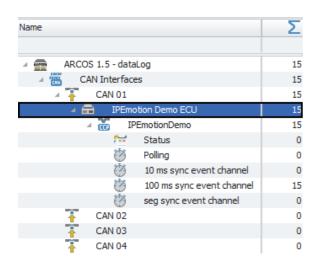
#### 6.3.4.1 Tree elements for CCP/XCP signals

After having successfully imported the desired signals to your CAN channel, this channel will contain three new layers of child elements in the measurement task tree: The **"ECU"**-layer, the **"Description file"**-layer and the **"Message"**-layer.



# ECU

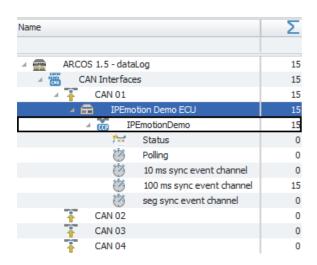
The "ECU" (Electronic control unit) represents the control unit inside the vehicle that the logger communicates with. It allows for an active communication between logger and vehicle, where the logger can not only receive messages but also send messages.



## Description file

The "description file" is a database file which contains signal information and can be used to import those signals into a Signal channel in IPEmotion. The filetype associated with CCP/XCP signals is the **"A2L file"**.

The symbol in the left part of the tree element shows you the type of "database" you imported (CCP or XCP), then follows the name of the imported "description file" (in this case "IPEmotionDemo") and on the right is a number indicating how many signals the "description file" contains (in this case 15).



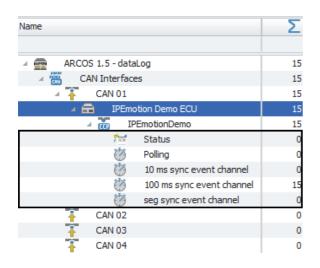


## Signal lists

Each "description file" can contain one or more Signal lists, which then contain the actual signals. A Signal list can be found in the "Measurement task tree" as a child element of the "description file", it belongs to.

Each Signal list can, again, contain one or more signals, which is indicated by the number on the right of the Signal list's name.

CCP/XCP Signal lists group the "description file's" signals in groups with different functionalities. The groups differ in the way that the logger obtains or requests a signal.



## • Status list

The status list contains signals on the ECU status and the status of DAQ lists included in the description file. Each signal list has two entries. **"Configured"** gives information whether the list has been configured, **"started"** gives information whether the respective list has been started and is running or not.

**"Station connected"** tells you whether the respective ECU is connected and **"EPK Versioncheck result"** lets you know whether the "EPK check" has been passed successfully or not.

#### Station connected

Tells you the status of the connection with the respective ECU.

NaN = not started	The ECU has not been started.
0 = failed	The ECU has been started but the connection test has failed.
1 = successful	The ECU has been started and the connection test has been
	passed successfully.

#### EPK Versioncheck result

Tells you about the result of the "EPK check".

NaN = not started	The "EPK check" has not been performed.
0 = failed	The "EPK check" has been performed but not passed.
1 = successful	The "EPK check" has been performed and passed successfully.



#### xxx\_ms\_task\_configured

Tells you whether the respective DAQ list has been configured.

0 = not yet configured	The DAQ list has not yet been configured.
1 = successful	The DAQ list has been configured.

#### xxx\_ms\_task\_started

Tells you whether the respective DAQ list has been started.

0 = not yet started	The DAQ list has not been started. It is inactive.
1 = successful	The DAQ list has been started.

#### • Polling list

Signals contained in a "Polling list", will be actively requested by the logger. That means, for each signal a sampling rate has to be defined, according to which the logger will request the signals which will then be sent to the logger by the ECU.

#### • DAQ list

Signals contained in a "DAQ list" are assigned with a certain time intervall in which the ECU is requested to send these signals. I.e. any signal contained in the DAQ list "100ms sync event channel" will be sent to the logger in an interval of 100ms. This guarantees that there is no unintended delay.

#### 6.3.4.2 Grid area for CCP/XCP signals

In the "grid area" you will be presented with an overview of your selected CAN channel's signals. Also you can find here two important functions, which are the "Column chooser"  $(\rightarrow 4.3.1)$  and the "Filter editor"  $(\rightarrow 4.3.2)$ .

#### 6.3.4.3 Details area for CCP/XCP signals

The Details area shows settings either for the selected tree element ("ECU","description file" or "signal list") or the selected signal in the grid area.

#### • "ECU" selected

In this case the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).

General		
	Active:	V
	Name:	IPEmotion Demo ECU
Des	cription:	
Ref	ference:	IPEmotion Demo ECU/CAN 01/ARCOS 1.5 - dataLog



#### • "description file" selected

In this case the details area will contain the "General" tab ( $\rightarrow$ 4.2.2) plus additional tabs.

## CCP/XCP

This tab contains CCP and XCP specific options.

General CCP Extended	
Resume active:	
Seed & Key:	
EPK check:	
Use optional commands: 🗹	

- Resume active

This option is not supported by the plugin at the moment

- Seed & Key

This field allows you to enter a Seed & Key binary file (\*.skb) which contains the information required to unlock the ECU if necessary.

## EPK check

Checks for differences in the chekcsums of the current configuration and the ECU.

#### - Use optional commands (CCP only)

If marked active, the optional commands defined in the ECU file will be used.

#### Fixed Seed & Key

If no Seed & Key file has been specified, this tab allows you to define fixed Seed & Key settings to be used.

General CCP Fixed Seed & K	Cey EPK Extended
Use fixed value:	
Fixed key value: 0	d
Fixed key length: 1 byte	

#### - Use fixed value

If marked active, a fixed Seed & Key value will be used. The value has to be defined below.



#### - Fixed key value

Define the fixed Seed & Key value. The button on the right allows to switch between decimal, hexadecimal or binary mode.

#### - Fixed key length

The dropdown menu allows you to define the byte length of the fixed Seed & Key value.

## EPK

This tab allows for EPK settings.

General	XCP Fixed Se	eed & Key EPK	Extended
	Checking mode:	EPK check	Ŧ
	GetID Identifier:		
	Action at failure:	Abort acquisition	Ŧ
	Action at failure.	Abor t acquisitio	

### - Checking mode

The dropdown menu allows you to choose the checking mode. It can be either **"EPK"** or **"GetID"**. "GetID" is only available for XCP.

#### - GetID Identifier

Define the identifier for the GetID mode. The identifier is a string that corresponds to the ECU's software version number. It can be found under "EPK identification" by right-clicking on the ECU in the tree and then clicking "Import properties".

#### - Action at failure

Allows you to define what action to take upon an EPK check failure. Regardless of the selected option the logger will always write an EPK check failure logging message.



## Extended

This tab allows for extended settings.



### - Identification second tester

Allows you to activate or deactivate the detection of a second master at the bus.

### - Synchronize DAQ start

Allows you to activate or deactivate the synchronization of the start of all DAQ-lists.

### • "Polling list" or "DAQ list" selected

In this case the details area will additionally contain the **"Trigger tab"**. The "Trigger tab" allows you to set a trigger upon whose activation the signals contained in the list will be requested.

General Trigger				
Mode:	Continuous acquisition 🔻			
Start-trigger:		Select	Remove	
Stop-trigger:		Select	Remove	
Post-trigger duration:	0 s			

#### - Mode

Define whether you wish to continuously acquire data or if you want to start/stop data acquisition via a trigger. There are two modes to control data acquisition via trigger:

Start and stop trigger allows you to set any previously defined trigger as start and/or stop condition.

**Stop is inverted start** will acquire data as long as the start trigger condition is met. Once it is no longer met and a possibly set **Post-trigger duration** has run out, data acquisition will stop.

#### - Start-trigger

Allows you to choose a trigger upon whose activation the list's Signals will be





requested. A trigger has first to be defined. Please refer to ( $\rightarrow$ 7).

- Stop-trigger

Allows you to choose a trigger upon whose activation the list's Signals will stop being requested. A trigger has first to be defined. Please refer to ( $\rightarrow$ 7). If there is no "Stop-trigger" defined the acquisition will be stopped by inverted start condition.

## - Post-trigger duration

You can determine here for how long after a stop request (either by explicit "Stop-trigger" or inverted start condition) the stop will be delayed and data acquisition will continue.

### • Signal selcted

In this case the details area will contain additional tabs which will be explained in the following.

## General

Please refer to ( $\rightarrow$ 4.2.2).

# Format

This tab contains information and options regarding file format, tasks and Channel type.

General Format	Scaling Display Si	gnal
Data type		
Type:	8-Bit integer unsigned	▼ Task: Default ▼
NoValue / DefaultVa	lue	
Value:	+FullScale	<ul> <li>Deactivate NoValue and use Default Value</li> </ul>
Channel type		
Input:	*	Output:

#### - Data type

This field tells you the type of data (in this case **"8-Bit integer unsigned"**) and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

## - NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

## - Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.

Changes and errors excepted.



### Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

General	Format	Scaling	Display	Signal				
Sensor mod	le							
	Mode:	Status					Ŧ	Scaling calculator
Sensor rang	je							
	Min:	0	Ŧ		Max:	1	Ŧ	Unit:
Physical ran	nge							
	Min:	0			Max:	1		Unit:

#### - Sensor Mode

The sensor mode tells the type of signal. It can be of different types such as "Status", "Voltage", "Frequenzy" or others. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.

#### - Sensor Range

Shows the raw value range of the signal.

#### - Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

#### Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General Format	Scaling Display Signal
Displaying area	
Min:	0 Max: 1
Formatting	
Decimal places:	Automatic 🔻
Name	
Name:	10 ms sync event channel configured

#### - Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.



#### - Formatting

The dropdown menu "Decimal places" allows you to set how many decimal numbers of the value will be shown on a display.

### – Name

Allows you to set a Name to be shown on a display.

#### Limit values

This tab allows you to define limit values for a signal and what action to take upon a limit value violation.

General Format Scaling	Display Limit values	Signal Signal che	ck				
Out of bound or invalid values							
Rejected value: will be dropped							
Valid ranges (Lower/Upper)			Invalid value	es (Physical/Raw)			
1: 0	0		1:	0	0	d	
2: 0	0		2:	0	0	d	
3: 0	0		3:	0	0	d	

#### - Rejected value

Define what happens to a value, that has been rejected because it is out of bound or invalid. By default this value will be dropped. It can also be written as NaN.

## - Valid ranges (Lower/Upper)

Define up to three ranges of valid signal values. Activate a range in order to define its upper/lower value (datatype double). Range 2 can only be activated if range 1 is and range 3 can only be activated if range 2 is.

## - Invalid values (Physical/Raw)

Define up to three invalid values. Activate an invalid value in order to define the physical value (datatype double) or raw value (datatype integer). If one of the two has been typed in, the other will be calculated according to the scale/offset settings in the scaling calculator.

Invalid value 2 can only be activated if invalid value 1 is and invalid value 3 can only be activated if invalid value 2 is.

For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.



## Signal

This tab allows you to define signal settings.

General Format Scal	ing Display <mark>Signal</mark>
Signalnumber:	
Last value hold:	Until the next reboot 🔹
Timeout:	0 s
Namespace:	'IPEmotion Demo ECU'

### - Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

### - Last value hold

Specify, for how long the last value of the signal will be hold.

– Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.

#### - Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.

## Signal check

This tab allows you to activate "Signal check" for this signal. You may choose whether you wish to apply the global signal check settings to this signal or override the global settings with settings specific for this signal.

Global signal check settings have to be defined first. For information on how to do so and for general information on "Signal check" please refer to ( $\rightarrow$ 4.2.2).

General Format Sca	ling Display Signal Signal check	Limit values
Use signal check:	$\checkmark$	
Mode:	Global settings 🔹	
Start-trigger:		Select
Stop-trigger:		Select
Timeout:	30 s	



# 6.4 UDS signals

## 6.4.1 Storage method

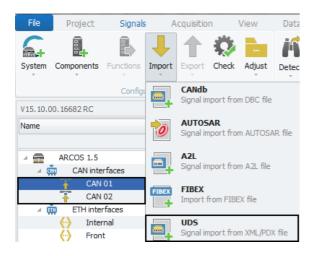
In order to store incoming signals on a CAN channel use one of the following signal storage methods.

- ATFX ( $\rightarrow$  12.6)
- MDF 4.0 ( $\rightarrow$  12.7)
- MDF 4.1 ( $\rightarrow$  12.8)

## 6.4.2 Importing UDS signals

This section explains how to import **UDS signals**. The filetype associated with these signals is a **`XML/PDX file**".

To import a UDS signal, select the CAN channel to which you wish to import your signal in the tree, click the **"Import"** button in the ribbon and then choose the "UDS" filetype for the import.





The following window lets you choose which file you wish to import. According to the filetype you have chosen earlier for your import, you will now only be able to choose files of the "XML/PDX" filetype. Choose the file you wish to import and click **"Open"**.

in Öffnen	And in case of the local division of		×					
🔾 🗸 🗸 Öffentliche Dokumente 🕨	🖉 🖓 « Öffentliche Dokumente 🕨 IPETRONIK 🕨 IPEmotion 🕨 Import  🗸 Import durchsuchen 🔎							
Organisieren 🔻 Neuer Ordner			:= • 🔟 🔞					
☆ Favoriten	Name	Änderungsdatum	Тур					
🧮 Desktop	🗾 IPEmotionDemo.pdx	22.02.2018 19:19	Acrobat Catalog-I					
📕 Downloads	IPEmotionDemo_Fibex.xml	19.02.2017 09:47	XML-Dokument					
📃 Zuletzt besucht	IPEmotionDemo_Fibex_onlyFLX.xml	01.02.2018 14:29	XML-Dokument					
<ul> <li>➢ Bibliotheken</li> <li>➢ Bilder</li> <li>➢ Dokumente</li> <li>J Musik</li> <li>➢ Subversion</li> <li>☑ Videos</li> <li>✓ Heimnetzgruppe</li> </ul>								
Dateiname: IPEmotion	← III Demo.pdx	✓ All supported Öffnen  ·	(*.xml;*.pdx)  Abbrechen					

Next the **"Importer"** window will appear, that will present you with a range of importing options.

Name	Selection	Sampling rate	Physical range	Description	Project versio	
					Control unit co	
Pressure_Abs		1 Hz	0 bar 1,9999694824218		Control unit	<u>م</u>
					Control unit n	IPEmotionDemo
Pressure_Rel		1 Hz	-2 bar +1,99993896484		Epk	
MAP		1 Hz	0 bar 3 bar		EPK address	0 h
TPS_Volt		1 Hz	-8 V +7,999755859375 V		ECU version	IPEmotionDem
Front_left		1 Hz	-50 °C +200,133587786		Protocol: UDS	م
Front_right		1 Hz	-50 °C +200,133587786		Protocol	UD:
Rear_left		1 Hz	-50 °C +200,133587786		Version	
Rear_right		1 Hz	-50 °C +200,133587786		Signal count	1
Exhaust 1		1 Hz	-50 °C +1210,28846153		CAN baud rat	500 kB
Exhaust 2		1 Hz	-50 °C +1210,28846153		Addressing mo	
Exhidust_E		1112	55 0 11215,255 10155		Control unit a	18 ł
					Tester addres	F1
					Tester Tx CA№	std 6F1 k
					Tester Rx CAI	std 618 h
				۱.	Number of mis	

In this dialog, all signals that can be imported from the description file are displayed. In the left table, all signals, where the "selection" checkboxes are selected, will be marked for import. You can either choose manually, which signals to import, you can use the **"Select/Deselect all"** button on the bottom left, or you can use a CSV-file to determine which signals are to be imported, by clicking **"Select by CSV"** on the bottom left.

In the right table the metadata, properties of the selected signals, the control unit and the protocol are displayed.

Changes and errors excepted.



Once you have choosen all the signals you wish to import, click **"OK"** to complete the import procedure.

Multiple description files can be imported into the same CAN channel.

### 6.4.3 Import properties

The "Import properties" of an "ECU", "Description file" or signal allow you to see certain properties such as the Data format, the Adress, the Bit mask, the start bit, bit count and more. It shows the properties as described by the description file.

峇 Import: I	IPEmotionDemo	:	×
General		A	
	Directory:	IPEmotionDemo.pdx C:\Users\Public\Document. IPEmotionDemo	
ECU		A	
	EPK identification:		
	EPK address:	0 h	I

#### Example for Import properties of a UDS ECU

Import: IPEmotionDemo		)
ECU		
Protocol:	UDS	
Tester address:	F1	h
Transmit CAN identifier:	std 6F1	h
Receive CAN identifier:	std 618	h
ECU address:	18	h
Addressing:	0	
Request Delay:	0	
Response Timeout:	500	
Extended Response Timeout:	10000	
Repeat Request Time:	0	
Version:	1	

Example for Import properties of a UDS Description file





Import:	Pressure_Rel		>
Signal			
	Original name:	Pressure_Rel	
	Data format:	INTEL	~
	Bit count:	16	
	Start bit:	16	
	Bit mask:	FFFFFFFFFFFFFF	
	ArrayIndex:	-1	
	Address:	200	h
	Address extension:	0	h

Example for Import properties of a UDS signal

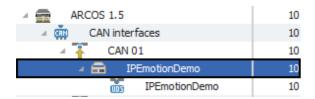
#### 6.4.4 Signal properties

#### 6.4.4.1 Tree elements for UDS signals

After having successfully imported the desired signals to your CAN channel, this channel will contain two new layers of child elements in the measurement task tree: The **"ECU"-layer** and the **"Description file"-layer**.

#### ECU

The "ECU" (Electronic control unit) represents the control unit inside the vehicle that the logger communicates with. It allows for an active communication between logger and vehicle, where the logger can not only receive messages but also send messages.



#### Description file

The "description file" is a database file which contains signal information and can be used to import those signals into a Signal channel in IPEmotion. The filetype associated with UDS signals is the **"UDS file"**.

The symbol in the left part of the tree element shows you the name of the imported "description file" (in this case "IPEmotionDemo") and on the right is a number indicating how many signals the "description file" contains (in this case 10).

4 🚍 ARCOS 1.5	10
CAN interfaces	10
4 🚹 CAN 01	10
🔺 💼 🛛 IPEmotionDemo	10
0 IPEmotionDemo	10



## 6.4.4.2 Grid area for UDS signals

In the "grid area" you will be presented with an overview of your selected CAN channel's signals. Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

## 6.4.4.3 Details area for UDS signals

The Details area allows you to access settings for the selected signal in the grid area. General

Please refer to ( $\rightarrow$ 4.2.2).

# Format

This tab contains information and options regarding file format, tasks and Channel type.

General	Format	Scaling	Display	Trigger	Signal			
Data type	2							
	Type:	16-Bit inte	ger unsigne	d	Ŧ	Task:	Default	*
NoValue /	/ DefaultVal	ue						
	Value:	+FullScale			Ŧ	Deactivate	NoValue and use Default Value	
Channel t	ype							
	Input:	<i>~</i>		Out	out:			

### • Data type

This field tells you the type of data (in this case **"16-Bit integer unsigned"**) and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

## • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

## • Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.



# Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

General	Format	Scaling	Display	Signal			
Sensor m	ode						
	Mode:	Status				~	Scaling calculator
Sensor ra	inge						
	Min:	0	Ŧ		Max: 1	Ŧ	Unit: 🔍 🔻
Physical r	ange						
	Min:	0			Max: 1		Unit:

#### • Sensor Mode

The sensor mode tells the type of signal. It can be of different types such as "Status", "Voltage", "Frequenzy" or others. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.

## • Sensor Range

Shows the raw value range of the signal.

## • Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and** scaling".

## Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General Format	Scaling	Display	Trigger	Signal	
Displaying area					
Min:	-50,00			Max: 1	210,29
Formatting					
Decimal places:	Automatic	Ŧ			
Name					
Name:	Exhaust 2				

## • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.



#### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

## • Name

Allows you to set a Name to be shown on a display.

## Limit values

This tab allows you to define limit values for a signal and what action to take upon a limit value violation.

General Format Scaling Display Limit values Signal Signal check								
Out of bound or invalid values								
Rejected value: will be dropped								
Valid ranges (Lower/Upper)	Valid ranges (Lower/Upper) Invalid values (Physical/Raw)							
1: 0	0	1: 0 0	d					
2: 0	0	2: 0 0	d					
3: 0	0	3: 0 0	d					

#### • Rejected value

Define what happens to a value, that has been rejected because it is out of bound or invalid. By default this value will be dropped. It can also be written as NaN.

## • Valid ranges (Lower/Upper)

Define up to three ranges of valid signal values. Activate a range in order to define its upper/lower value (datatype double). Range 2 can only be activated if range 1 is and range 3 can only be activated if range 2 is.

## • Invalid values (Physical/Raw)

Define up to three invalid values. Activate an invalid value in order to define the physical value (datatype double) or raw value (datatype integer). If one of the two has been typed in, the other will be calculated according to the scale/offset settings in the scaling calculator.

Invalid value 2 can only be activated if invalid value 1 is and invalid value 3 can only be activated if invalid value 2 is.

For details on how to use the "Scaling calculator" please refer to the **IPEmotion Do**cumentation - Section 3.4.5 "Channel configuration and scaling".

# Signal

This tab allows you to define signal settings.

General Format Scal	ing Display Trigger	Signal	
Internal data type:	Double		Ŧ
Signal number:			
Hold last value:	Until the next reboot		<b>*</b>
Timeout:	0 s		
Namespace:	'IPEmotionDemo'::'514'		

### • Internal data type

Assign an internal data type to the signal. Available data types are **"Double"** and **"String"**.

## • Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

### • Last value hold

Specify, for how long the last value of the signal will be hold.

#### • Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.

#### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.

## Signal check

This tab allows you to activate "Signal check" for this signal. You may choose whether you wish to apply the global signal check settings to this signal or override the global settings with settings specific for this signal.

Global signal check settings have to be defined first. For information on how to do so and for general information on "Signal check" please refer to  $(\rightarrow 4.2.2)$ .

eneral Format Sca	ling Display Signal	Signal check	Limit values
Use signal check:	$\checkmark$		
Mode:	Global settings	+	
Start-trigger:			Select
Stop-trigger:			Select
Timeout:	30 s		



# 6.5 OBD signals

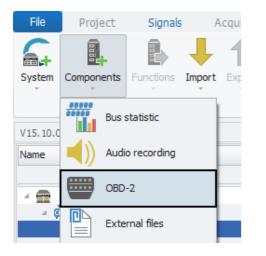
## 6.5.1 Storage method

In order to store all incoming traffic on a CAN channel use a bus tracing method for storage. Please refer to ( $\rightarrow$  12.9).

### 6.5.2 Adding the OBD signals interface

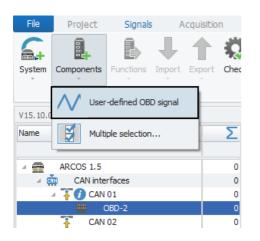
This section explains how to work with OBD (On-Board diagnosis) signals.

In order to work with "OBD signals", you will first need to add the "OBD signals" interface, which will contain all the available "OBD signals". To do so, select a CAN channel in the tree, click the "Components" button in the Ribbon and then choose "OBD-2".



## 6.5.3 User-defined OBD signals

It is possible to define a user-specific "OBD signal". To do so, select the "OBD signals" interface in the measurement task tree, click the "Components" button in the Ribbon and then choose "User-defined OBD signal".

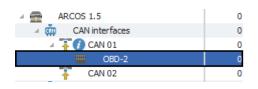




## 6.5.4 Signal properties

#### 6.5.4.1 Tree elements for OBD signals

After having added the "OBD signals" interface, it will appear in the measurement task tree as a ne tree element.



## 6.5.4.2 Grid area for OBD signals

In the "grid area" you will be presented with an overview of all the available "OBD signals". Also you can find here two important functions, which are the **"Column chooser"** ( $\rightarrow$ 4.3.1) and the **"Filter editor"** ( $\rightarrow$ 4.3.2).

	Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
۴								
Ø.	09 01 - Length of vehicle identificatio			0	255	0	255	Event controlled
	09 02 - Vehicle identification number							Event controlled
	002 - DTC that caused required fr			0	65535	0	65535	1 Hz
	003 - Fuel system status 1 & 2			0	65535	0	65535	1 Hz
	004 - Calculated load value		%	0,0	100,0	0	100	1 Hz
	005 - Engine coolant temperature		°C	-40	215	-40	215	1 Hz
	006 - Short term fuel % trim Bank 1		%	-100,0	99,2	-100	99,22	1 Hz
	006 - Short term fuel % trim Bank 3		%	-100,0	99,2	-100	99,22	1 Hz
	007 - Long term fuel % trim Bank 1		%	-100,0	99,2	-100	99,22	1 Hz
	007 - Long term fuel % trim Bank 3		%	-100,0	99,2	-100	99,22	1 Hz
	008 - Short term fuel % trim Bank 2		%	-100,0	99,2	-100	99,22	1 Hz
	008 - Short term fuel % trim Bank 4		%	-100,0	99,2	-100	99,22	1 Hz
	009 - Long term fuel % trim Bank 2		%	-100,0	99,2	-100	99,22	1 Hz
	009 - Long term fuel % trim Bank 4		%	-100,0	99,2	-100	99,22	1 Hz
	00A - Fuel pressure		bar	0,00	7,65	0	7,65	1 Hz



#### 6.5.4.3 Details area for OBD signals

The Details area allows you to access settings either for the "OBD signals" interface or for the selected "OBD signal" in the grid area.

If the interface has been selected in the measurement task tree, the details area will contain two tabs.

#### General

Please refer to ( $\rightarrow$ 4.2.2).

#### **KWP** station

Define the request and respond CAN ID of the addressed ECU.

General KWP station		
Request CAN ID:	std 7E0 h	
Response CAN ID:	std 7E8 h	

Request CAN ID

The Request CAN ID is typically between 7E0h and 7E7h.

#### • Respond CAN ID

The Respond CAN ID is typically between 7E8h and 7EFh.



If a signal has been selected in the Grid area, the details area will contain the following tabs.

#### General

Please refer to ( $\rightarrow$ 4.2.2).

## Format

This tab contains information and options regarding file format, tasks and Channel type.

General For	mat Scaling	Display 1	Trigger Signa	al OBD-2 (P	ID)	
Data type						
т	ype: 8-Bit integ	er unsigned	Ŧ	Task:	Default	~
NoValue / Defa	ultValue					
Va	alue: -FullScale		Ŧ	Deactivate	NoValue and use Default Value	
Channel type						
In	put: 🗹		Output:			

### • Data type

This field tells you the type of data (in this case **"8-bit integer unsigned"**) and allows you to apply special tasks for this formula/signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

#### • NoValue / DefaultValue

This field allows you to define the value that will be shown if a formula/signal value is read as invalid.



# Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

General Fo	rmat Scaling	Display Trigger	Signal OBD-2	(PID)	
Sensor mode					
M	lode: Without un	it		Ŧ	Scaling calculator
Sensor range					
	Min: 0		Max: 255		Unit:
Physical range					
	Min: 0		Max: 255		Unit:

#### • Sensor Mode

The sensor mode tells the type of signal. It can be of different types such as "Status", "Voltage", "Frequenzy" or others. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.

### • Sensor Range

Shows the raw value range of the signal.

• Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

## Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General Format	Scaling Display	Trigger Signal	OBD-2 (PID)
Displaying area			
Min:	-100,0	Max:	99,2
Formatting			
Decimal places: Automatic 🔻			
Name			
Name:	006 - Short term fuel	% trim Bank 1	

• Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

## • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

Changes and errors excepted.



## • Name

Allows you to set a Name to be shown on a display.

# Trigger

This tab provides settings regarding the trigger for the start and stop of data acquisition on this channel.

General Format Sca	ling Display <b>Trigger</b> Signal	OBD-2 (PID)	
Mode:	Continuous acquisition	-	
Start-trigger:		Select	Remove
Stop-trigger:		Select	Remove
Post-trigger duration:	0 s		

## • Mode

Define whether you wish to continuously acquire data or if you want to start/stop data acquisition via a trigger. There are two modes to control data acquisition via trigger:

**Start and stop trigger** allows you to set any previously defined trigger as start and/or stop condition.

**Stop is inverted start** will acquire data as long as the start trigger condition is met. Once it is no longer met and a possibly set **Post-trigger duration** has run out, data acquisition will stop.

## • Start-trigger

Define a trigger, that will start data acquisition.

## • Stop-trigger

Define a trigger, that will stop data acquisition.

## • Post-trigger duration

Post-trigger duration allows you to define, how long after the start trigger was set, data acquisition will stop.

## Limit values

This tab allows you to define limit values for a signal and what action to take upon a limit value violation.

General Format Scal	ng Display Limit values	Signal Signal che	ck			
Out of bound or invalid value	les					
Rejected value:	will be dropped	Ŧ				
Valid ranges (Lower/Upper)			Invalid value	s (Physical/Raw)		
1: 🗌 0	0		1:	0	0	d
2: 0	0		2:	0	0	d
3: 0	0		3:	0	0	d

### • Rejected value

Define what happens to a value, that has been rejected because it is out of bound or invalid. By default this value will be dropped. It can also be written as NaN.

# • Valid ranges (Lower/Upper)

Define up to three ranges of valid signal values. Activate a range in order to define its upper/lower value (datatype double). Range 2 can only be activated if range 1 is and range 3 can only be activated if range 2 is.

## Invalid values (Physical/Raw)

Define up to three invalid values. Activate an invalid value in order to define the physical value (datatype double) or raw value (datatype integer). If one of the two has been typed in, the other will be calculated according to the scale/offset settings in the scaling calculator.

Invalid value 2 can only be activated if invalid value 1 is and invalid value 3 can only be activated if invalid value 2 is.

For details on how to use the "Scaling calculator" please refer to the **IPEmotion Do**cumentation - Section 3.4.5 "Channel configuration and scaling".

# Signal

This tab allows you to define signal settings.

General Format Scali	ng Display Trigger Signal OBD-2 (PID)
Internal data type:	Double -
Signal number:	
Hold last value:	Until the next reboot 🔹
Timeout:	0 s
Namespace:	'OBD-2'

### • Internal data type

Assign an internal data type to the signal. Available data types are **"Double"** and **"String"**.

• Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

• Hold last value

Specify, for how long the last value of the signal will be hold.

• Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.

#### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.

## OBD-2(PID)

This tab allows shows extended OBD-2 specific settings.

General Format Sca	aling Display	Trigger Sig	gnal OBD-2 (PID)	
SID:	1		h	
PID:	6		h	
PID size:	2			
Start bit:	8			
Bit count:	8			

#### Signal check

This tab allows you to activate "Signal check" for this signal. You may choose whether you wish to apply the global signal check settings to this signal or override the global settings with settings specific for this signal.

Global signal check settings have to be defined first. For information on how to do so and for general information on "Signal check" please refer to  $(\rightarrow 4.2.2)$ .

General Format Scal	ing Display Trigger	Signal OBD-2 (P	ID) Signal check	Limit values
Use signal check:	¥			
Mode:	Global settings	-		
Start-trigger:			Select	
Stop-trigger:			Select	
Timeout:	30 s			

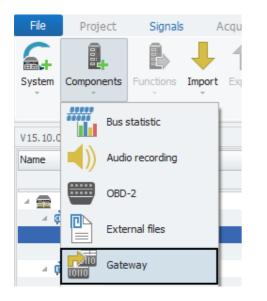


# 6.6 Gateways

The Gateway method makes it possible to take messages received on one CAN channel (source) and output them on another channel (target). Messages are output as soon as they are received with this method, it is neither possible to influence the time of transmission nor to modify the sent data (this can be achieved by means of programing, through a script). Filters can be used to restrict the messages transmitted.

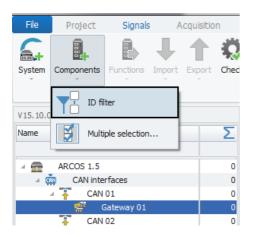
# 6.6.1 Adding a gateway

In order to add a gateway, select the desired source CAN channel in the measurement task tree, click the components button in the Ribbon and then select "Gateway". For instructions regarding the settings of a gateway please refer to  $(\rightarrow 6.6.3)$ .



# 6.6.2 Adding an ID filter

In order to limit the traffic passed through the gateway, one or more ID filter per gateway can be defined. In order to add an ID filter select the desired gateway in the measurement task tree, click the "Components" button in the Ribbon and then select "ID filter". For instruction regarding the settings of an ID filter please refer to  $(\rightarrow 6.6.4)$ .





## 6.6.3 Gateway settings

## 6.6.3.1 Tree elements for Gateways

Each Gateway that has been added to a CAN channel will appear in the measurement task tree as a child element to the respective CAN channel.

Name	Σ
ARCOS 1.5	0
CAN interfaces	0
4 🖡 CAN 01	0
🔛 🖬 Gateway 01	0
Gateway 02	0
	0

# 6.6.3.2 Grid area for Gateways

In the "grid area" you will be presented with an overview of all the previously added ID filters for the selected gateway. You can activate or deactivate an ID filter by ticking/unticking the "Active"-box. Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

P         Image: Constraint of the second secon	Name	Active	Description	
▶ ID filter 01	٩			
	ID filter 01	~		
	ID filter 02	~		

## 6.6.3.3 Details area for Gateways

The details area provides settings regarding the general behaviour of a gateway. General

```
Please refer to (\rightarrow4.2.2).
```

#### Settings

Settings regarding the target CAN channel and filter action.

General Settings		
Default filter action:	Pass all except specified ID or ID rar	nge 🔻
Target:		Select

## • Default filter action

Define whether the gateway should pass or block all traffic except the specified ID or ID range.

Changes and errors excepted.



## • Target

Select the desired target CAN channel.

#### 6.6.4 ID filter settings

All setting regarding the ID filter can be found in the "Filter settings" tab of the details area of the respective ID filter.

	Name		Active	Description
۴				
Þ	ID filte	r 01	~	
	ID filte	r 02	<b>~</b>	
_				
Ge	eneral	Filter settings		
		Mode:	Specific ID	-
		CAN ID:	std O	h
		Stop ID:	std 0	h

#### • Mode

Define whether the filter will affect a specific ID or an ID range.

#### • CAN ID

Define the specific or start ID for the filter. For detailed instructions on the topic CAN ID pleaser refer to ( $\rightarrow$ 6.1.3.3).

## CAN ID

Define the stop ID for the filter if the mode ID range has been selected.



# 6.7 Runstate

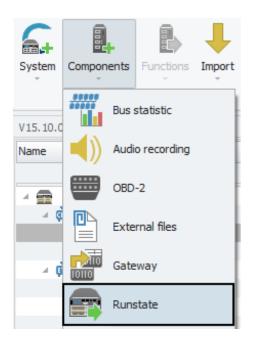
Taking into account the variety of different run states, plus the fact that the ARCOS display is not always used, we have created the possibility of using CAN messages to read out the current logger state and export it into a CANdb file.

For this purpose, the start identifier can be freely selected, while the remaining messages are sequentially put out on the subsequent identifiers.

Moreover, the output rate can be selected, and the content influenced by activating/deactivating individual messages.

# 6.7.1 Add Runstate

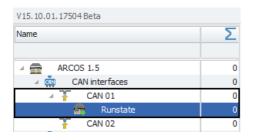
In order to read out the logger state using the "Runstate" functionality, you will first need to add the "Runstate" interface to the CAN channel on which it should be sent. To do so, select the desired CAN channel in the measurement task tree, click the "Components" button in the Ribbon and then choose "Runstate".





# 6.7.2 Tree elements for Runstate

Once the "Runstate" interface has been added to a CAN channel, it will appear in the measurement task tree as a child element to that channel.



## 6.7.3 Grid area for Runstate

In the "Grid area" you will be presented with an overview of the available signal messages. Each signal message has a subject and contains various signals concerning the respective subject. Marking/demarking active a signal message in the grid area will determine, whether the contained information will be read out and saved or discarded at export.

The description field tells you the subject of a signal message and the CAN ID field tells you the CAN ID in hexadecimal of the signal message.

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

	Name	Active	Description	CAN ID
۴				
	Version information	~	Sends version information	0x1
	Measurement time in µs	~	Sends the measurement time in µs	0x2
	Absolute time in µs	~	Sends the absolute time in µs	0x3
	Measurement delay in ms		Sends the current measurement delay in ms	0x4
	Absolute time in s		Sends the absolute time in s	0x4
	Absolute time formatted		Sends the absolute time formatted	0x5
	System state information		Sends the system state information	0x6
	Transfer state information		Sends the transfer state information	0x7



### 6.7.4 Details area for Runstate

The details area for "Runstate" provides runstate settings. General

Please refer to ( $\rightarrow$ 4.2.2).

#### Settings

This tab contains the runstate settings.

General Settings	
First CAN-ID: std 1 h	
Sending rate: 1 Hz	

• First CAN-ID

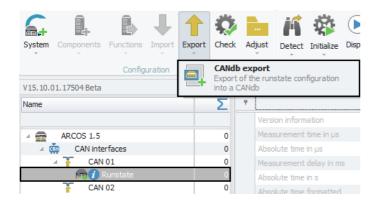
This field defines the CAN identifier for sending of the first signal message. The remaining messages are sequentially put out on the subsequent identifiers.

• Sending rate

Define the output rate for state information.

#### 6.7.5 Export Runstate

In order to make the loggers runstate signals available for further processing or analysis, they may be exported into a CANdb database. To do so, select the "Runstate" interface in the measurement task tree and then click the "Export" button in the Ribbon and choose "CANdb export". Only the signal messages that have previously been marked active in tht grid area will be exported.

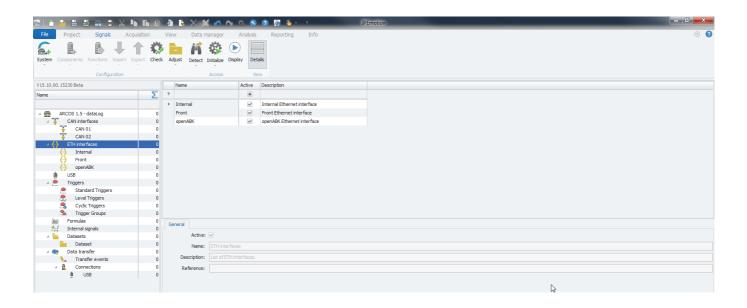




# 6.8 ETH channels

All the ETH channels for your system are located in the tree element "ETH interfaces". According to the default settings, the tree element "ETH interfaces" will include a preset number of ETH channels. By clicking the tree element ETH Interfaces you will see all of its channels and signals in the grid area as well as a tab called **General** in the **Details area** which allows you to set a name and description. These settings apply to the entire element "ETH interfaces".

In the following will be described how to add ETH channels and adjust their settings ( $\rightarrow 6.8.3$ ).



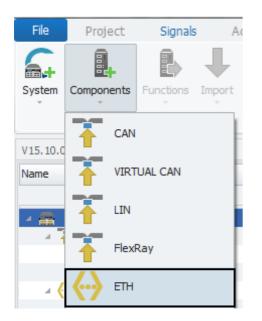
## 6.8.1 Storage method

In order to store all incoming traffic on an ETH channel use "PCAP" as a bus tracing method for storage. Please refer to ( $\rightarrow$  12.10).



# 6.8.2 Adding ETH channels

ETH channels can be added by selecting the tree element **"ETH interfaces"**, then clicking the **"Components"** button and finally choosing the desired type of ETH channel you wish to add.





# 6.8.3 ETH settings

By selecting one of the ETH channels in the tree you will be able to define this channel's settings in the details area.

File	Project	Signals	A	cquisitio	1	View	Data	manager	An	nalysis	Rep	orting	Info			
System	Components	Functions	Import	t Export	Check	 Adjus	t Detect	Initialize	Display	Detai	ils					
		Configu	ration					Access		Viev	v					
V15 10 0	0.15230 Beta					Name				Active Unit Phys Min			Phys Max	Sensor Min	Sensor Max	Sampling rate
	0.13230 Deta				~	9	inc		~		Onic	Filys Mill	Fillys Max	Sensor Min	Sensor Max	Sampling rate
Name					Σ	Ŧ				-						
- <b>B</b>	ARCOS 1.5 -	-		_	0											
- 4	100 M				0											
	T CAN			_	0											
· ,	CAN				0											
	ETH inter     O     Inter			_	0											
	Inter				0											
	open				0											
	💮 ЕТН С				0											
(	USB				0											
	Triggers				0											
		dard Triggers	s		0											
		Triggers			0											
		: Triggers			0											
	🐴 Trigg	er Groups			0	Gene	al LAN	Setting	26							
	(x) Formulas				0	Gene			90							
	🖌 Internal s	-			0		Active	~								
- A 1	-				0		Name	: openA	BK							
Dataset 0				Description		openABK Ethernet interface										
A 🗬 Data transfer 0			-													
Image: Transfer events         0           Image: Connections         0			Reference:			BK/ARCO	S 1.5 - d	ataLog								
		ections ISB			0											

The same settings described in this section as part of the Details area can also be adjusted when selecting the tree element **ETH interfaces** and then directly changing the desired setting in the respective field of the **Grid area**.



# 6.8.3.1 General

This tab allows you to give a user specific name for the selected ETH channel if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

The **Active** checkbox allows to deactivate the entire bus. If a bus is deactivated all childelements of this bus will be deactivated, too, and cannot be stored or traced, until the bus is reactivated.

Front-, Internal- and openABK-buses cannot be deactivated.

General LAN	Settings
Active:	V
Name:	Front
Description:	Front Ethernet interface
Reference:	Front/ARCOS 1.5 - dataLog

# 6.8.3.2 LAN

General LAN Settings	
Get IP address automatically:	$\checkmark$
IP address:	0.0.00
Subnet mask:	255.255.255.0
Standard gateway:	0.0.0.0
DNS server:	0.0.0.0

This tab allows you to set your current ETH channel's LAN settings. Whether it should receive an IP address automatically or not. If you deactivate the setting "Get IP address automatically" and set the IP address manually.



For the tree elements "Open ABK" and "Inernal" the IP settings cannot be adjusted.

## 6.8.3.3 Settings

Changes and errors excepted.



# 6.8 ETH CHANNELS

General LAN Settings	
Channel number	: 3
Used for data transfer	:

This tab allows you to set your current ETH channel's physical channel number and whether it should be used for data transfer.

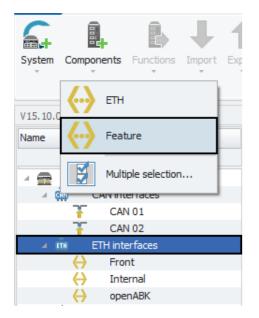
# 6.8.4 ETH Feature interface (FlexRay satellite on ETH)

The "ETH Feature" interface, allows for connection and configuration of a FlexRay satellite via an ETH connection. A FlexRay satellite possesses two FlexRay channels and its functionality is identical to that of the regular FlexRay interface and FlexRay channels.

This section will only explain how to add the "ETH Feature" interface and a FlexRay satellite to your configuration. For details on how to configure a FlexRay channel please refer to  $(\rightarrow 6.12)$  and for FlexRay signals please refer to  $(\rightarrow 6.13)$ .

## 6.8.4.1 Adding the ETH Feature interface

In order to add the "ETH Feature" interface to your configuration, select the ETH interface in the measurement task tree, click the "Components" button in the Ribbon and then choose "Feature".





## 6.8.4.2 Adding a FlexRay satellite

In order to add a FlexRay satellite make sure, that you have added the "ETH Feature" interface to your configuration ( $\rightarrow$ 6.8.4.1). Once the "ETH Feature" interface has been added to your configuration, you will need to select it in the measurement task tree. Then click the "Components" button in the Ribbon and choose "FlexRay" satellite.

6.		
System	Components Functions Import Exp	
V15.10.0	FlexRay Satellite	
Name	Multiple selection	
4 💼	ARCOS 1.5	
► Q	CAN interfaces	
Q	ETH interfaces	
	🔶 Front	
	💮 Internal	
	💮 openABK	
	💮 Feature 01	

### 6.8.4.3 Tree elements for a FlexRay satellite

Each FlexRay satellite comes with two FlexRay channels which will appear as child elements to the FlexRay satellite in the measurement task tree.

🛛 💮 🛛 Feature 01	0
🔺 📻 🛛 FlexRay Satellite 01	C
FlexRay 01	C
FlexRay 02	C



## 6.9 ETH signals

For data acquisition you can import A2L or Fibex databases on the "Front" channel of your "ETH interface" or on any manually added ETH channel. The protocol for importing A2L databases is XCPonUDP and the protocol for importing Fibex databases is SOME/IP.

## 6.9.1 Storage method

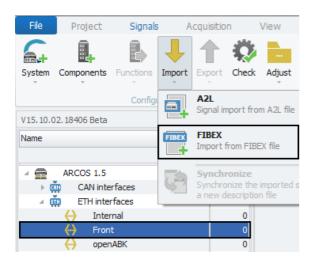
In order to store incoming signals on an ETH channel use one of the following signal storage methods.

- ATFX ( $\rightarrow$  12.6)
- MDF 4.0 ( $\rightarrow$  12.7)
- MDF 4.1 ( $\rightarrow$  12.8)

## 6.9.2 Importing ETH signals

## 6.9.2.1 Importing Fibex files (SOME/IP)

In order to import a Fibex database, select either the "Front" channel or any manually added "ETH xx" channel of your "ETH interface", click the "Import" button in the Ribbon and then choose "Fibex".

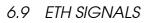


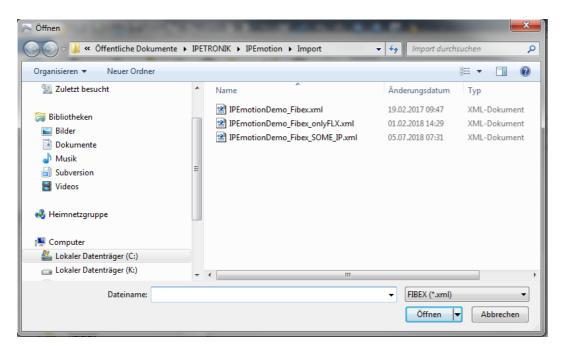
The following window lets you choose which file you wish to import. Choose the file you wish to import and click "Open".

Next the **"Importer"** window will appear, that will present you with a range of importing options.

In this dialog, all signals that can be imported from the description file are displayed. In the left table, all signals, where the "selection" checkboxes are selected, will be marked for import. You can either choose manually, which signals to import, you can use the **"Select/Deselect all"** button on the bottom left, or you can use a CSV-file to determine which signals are to be imported, by clicking **"Select by CSV"** on the bottom left.

# 





Na	ame	Selection	Sampling rate	Message	Physical range	Project versio	
				-	A	Control unit co	2
					0.45	Control unit	*
	ounter	<b>~</b>	1 Hz	ServiceField	0 15	Control unit ni	IPETRONIK
Te	emp1	~	1 Hz	ServiceField	-254 °C +257,8	Protocol: SOME/IP	<u>ـ</u>
Te	emp2	4	1 Hz	ServiceField	-254 °C +257,8	Protocol	SOME/IP
Te	emp3	~	1 Hz	ServiceField	-254 °C +257,8	Version	
Te	emp4	~	1 Hz	ServiceField	-254 °C +257,8	Signal count	
C	ount	~	1 Hz	ExecuteMethod	0 65535	Baud rate	100 MBd
Ti	imeDelta	~	1 Hz	ExecuteMethod	0 s 1193.04647	Transport layer	*
R	atio	~	1 Hz	ExecuteMethod	0 255	Transport laye	
	ime	~	1 Hz	ServiceEvent	0 s 1193046,47	IP address	160,48,199,117
1.1			1 Hz	ServiceEvent	0 d 65535 d	Network mask	255.255.255.128
-	ау	~				Port number	
	ount2	~	1 Hz	ExecuteMethod2	0 65535	Name	ServiceField
Ti	imeDelta2	~	1 Hz	ExecuteMethod2	0 s 1193,04647		
Ra	atio2	~	1 Hz	ExecuteMethod2	0 255 🗸	Message ID	B00D8006 h
					Þ	Length	/

In the right table the metadata, properties of the selected signals, the control unit and the protocol are displayed.

Once you have choosen all the signals you wish to import, click "OK" to complete the import procedure.

#### 6.9.2.2 Import properties for SOME/IP

The "Import properties" of a ECU, Message or signal allow you to see certain properties such as the Data format, EPK identification, the Bit mask, the start bit, bit count and more. It shows the signal's properties as described by the description file.

Example for "Import properties" of a SOME/IP ECU Example for "Import properties" of a SOME/IP protocol layer Example for "Import properties" of a SOME/IP Socket

Changes and errors excepted.



## 6.9 ETH SIGNALS



Import: 1	IPETRONIK		>
General			
	File name:	IPEmotionDemo_Fi	bex_5
	Directory:	C:\Users\Public\Do	cument
	Version:		
	Description file:		
ECU			
	EPK identification:		
	EPK address:	0	h
	El R dudi C55	•	
🛓 Import: 1	IPEmotionDemo_Fi	bex_SOME_IP	>
General			
	Protocol:	SOME/IP	
	Version:		

Example for "Import properties" of a SOME/IP message Example for "Import properties" of a SOME/IP signal

## 6.9.2.3 Importing A2L files (XCPonUDP)

In order to import an A2L database, select either the "Front" channel or any manually added "ETH xx" channel of your "ETH interface", click the "Import" button in the Ribbon and then choose "A2L".



Magnetical Import:	Socket 1		×
Transport la	iyer		
1	Transport layer type: IPv4 address:	UDP 160.48.199.117	Ŧ
	Network mask: Port number:	255.255.255.128 30501	
Import:	ServiceInterface_S	erviceField	×
Message	ServiceInterface_S	erviceField	×
	ServiceInterface_S Message identifier:		× ∡ h
		B00D8006	
	Message identifier: Length: Sender name:	B00D8006 9 IPETRONIK	
	Message identifier: Length:	B00D8006 9 IPETRONIK	× 1 h

The following window lets you choose which file you wish to import. Choose the file you wish to import and click "Open".

Next the **"Importer**" window will appear, that will present you with a range of importing options.

In this dialog, all signals that can be imported from the description file are displayed. In the left table, all signals, where the "selection" checkboxes are selected, will be marked for import. You can either choose manually, which signals to import, you can use the **"Select/Deselect all"** button on the bottom left, or you can use a CSV-file to determine which signals are to be imported, by clicking **"Select by CSV"** on the bottom left.

In the right table the metadata, properties of the selected signals, the control unit and the protocol are displayed.

Once you have choosen all the signals you wish to import, click **"OK"** to complete the import procedure.

	be In via sar sel dra sel au If ir co DA In a "sp be	ppending on the protocol, a sampling rate or the DAQ list to use, can assigned to the signals. the case of a protocol using DAQ lists (CCP, XCP), you can specify the column selection dialog, if the signals are configured by the mpling rate or a DAQ list. To achieve this you should open the column ection dialog, via the context menu of the table header, and then ag the desired column ("sampling" or "DAQ list") from the column ection dialog to the table header. The other column is removed tomatically. In a protocol based on DAQ lists, sampling rates are used for the signal infiguration, during import the signals are assigned to the available infiguration, during import the signals are assigned to the available infiguration, during import in array signals, you can specify via the polit array" column whether all the signals of the array or just the first to imported. If this column does not appear it can be moved from the lumn selection dialog into the table.
--	--	--



**IPETRONIK** 



## 6.9.2.4 IP settings when Importing A2L files (XCPonUDP)

When importing signals to an ETH channel from an A2L file, the PlugIn will automatically set the description file's source IP address (to be found in the import properties of the description file) as the ETH channel's IP address. If DHCP is activated it will be deactivated and the existing IP address will be replaced with the source IP address. Also if DHCP is deactivated but the IP address is set to 0.0.0.0, the existing IP address will be replaced with the source IP address.

However, if DHCP is deactivated and a user specific IP address **other** than 0.0.0.0 is set, this IP address will **not** be replaced.

#### 6.9.2.5 Import properties for XCPonUDP

The "Import properties" for XCPonUDP are identical to XCPonCAN. Please refer to ( $\rightarrow$ 6.3.3).

💛 🗸 🕌 « Öffentliche Dokumente	IPETRONIK      IPEmot	tion Import	- + Import di	ırchsuchen	\$
Organisieren 🔻 Neuer Ordner				•	?
🛠 Favoriten 🔺 Name	×	Änderungsdatum	Тур	Größe	
E Desktop Desktop IPEmoti Downloads Zuletzt besucht Bibliotheken Dokumente Musik Subversion Videos	onDemo.a2l	19.02.2017 09:47	A2L-Datei	85 K	В
neimnetzgruppe					
Dateiname:			- ASAM MC	D-2MC (*.a2l)	-

#### 6.9.3 Signal properties

#### 6.9.3.1 Signal properties for SOME/IP

The signal properties for SOME/IP signals are mainly the same as for Fibex signals on Flexray channels. Please refer to ( $\rightarrow$  6.13.4).

The only difference betwen Fibex signals on ETH and on Flexray is, that importing Fibex signals on ETH will result in one extra layer of tree elements called **"Socket x"**.

The socket layer then contains the signal messages and offers an extra possibility for grouping these messages.

#### 6.9.3.2 Signal properties for XCPonUDP

The signal properties for XCPonUDP signals are the same as for XCP signals on CAN channels. Please refer to ( $\rightarrow$  6.3.4).

### 6.10 LIN CHANNELS





	a column bander barn to move	hu that as				Project		*
	a column header here to group					Project numbe		
	Name	Selection	Sampling rate	Physical range	Description	Project versio		
						Protocol: FreeRu	inning	*
	Pressure Abs		1 Hz	0 bar 2 bar		Protocol	FreeRunn	
	Pressure_Rel		1 Hz	-2 bar +2 bar		Signal count		
	MAP		1 Hz	0 bar 3 bar		CAN baud rate	Not speci	
						J1939 Message		
	TPS_Volt		1 Hz	-8 V +8 V		Name	SIM 51499999	
	Front_left		1 Hz	-50 C +200 C				
	Front_right		1 Hz	-50 C +200 C		F		8
	Rear_left		1 Hz	-50 C +200 C		Length Sampling rate		
	Read_right		1 Hz	-50 C +200 C		Description		
	Exhaust_1		1 Hz	-50 C +1200 C		Sender name	IPETRO	
	Exhaust_2		1 Hz	-50 C +1200 C			~	
						Signal		
						Name	Pressure	Abs
						Display identif		
						Byte order		
						Data type	16-Bit integer u	
h	<b>orter</b> is dialog, all signals that can be i				•	Bit count		
h h	is dialog, all signals that can be i e left table, all signals, where th e right table the properties of th ending on the protocol, a samplir	e "selection ne selected ng rate or t	n" checkboxes ar signals, the con he DAO list to us	e selected, will be marke trol unit and the protocol	are displayed.	Bit count	CP, XCP), you car	1
th th th Se	is dialog, all signals that can be i e left table, all signals, where th e right table the properties of the ending on the protocol, a sampling	e "selection ne selected ng rate or t IPEmotionI	n" checkboxes ar signals, the con he DAO list to us	e selected, will be marke trol unit and the protocol e, can be assigned to the	are displayed.	Bit count	CP, XCP), you car	16
	is dialog, all signals that can be i e left table, all signals, where th e right table the properties of th ending on the protocol, a samplin elect all Select by CSV neral LAN Settings	e "selection ne selected ng rate or t IPEmotion	n" checkboxes ar signals, the con he DAO list to us	e selected, will be marke trol unit and the protocol e, can be assigned to the	are displayed.	Bit count	CP, XCP), you car	16
h	is dialog, all signals that can be i e left table, all signals, where the e right table the properties of the ending on the protocol, a samplin elect all Select by CSV neral LAN Settings Get IP address automatically	e "selection e selected grate or t IPEmotion r: :: 192.16	n" checkboxes ar signals, the con he DAO list to us Demo.DBC - 0 c	e selected, will be marke trol unit and the protocol e, can be assigned to the	are displayed.	Bit count	CP, XCP), you car	10
h	is dialog, all signals that can be i e left table, all signals, where th enght table the properties of th ending on the protocol, a samplin sect all Select by CSV neral LAN Settings Get IP address automatically IP address	e "selection le selected la rate or t IPEmotion r: 192.16 c: 255.25	n" checkboxes ar signals, the com he DAO list to us Demo.DBC - 0 c 58.0.254 55.255.0	e selected, will be marke trol unit and the protocol e, can be assigned to the	are displayed.	Bit count	CP, XCP), you car	16
th th th pe	is dialog, all signals that can be i e left table, all signals, where the eright table the properties of th inding on the protocol, a samplin elect all Select by CSV neral LAN Settings Get IP address automatically IP address Subnet mask	e "selection le selected lg rate or t IPEmotional r: 192.16 r: 255.25 r: 0.0.0.1	n° checkboxes ar signals, the con he DAQ list to us Demo.DBC - 0 c 58.0.254 55.255.0 0	e selected, will be marke trol unit and the protocol e, can be assigned to the	are displayed.	Bit count	CP, XCP), you car	1

## 6.10 LIN channels

To work with "LIN channels", you will first have to add the tree element "LIN interfaces" to your measurement task tree. To do so, select your system in the measurement task tree, click the "Components" button in the ribbon and choose "LIN interfaces" from the resulting dropdown menu.

Once the "LIN interfaces" component has been added it will appear in the measurement task tree as a tree element with one "LIN channel" as a child element.

#### 6.10.1 Storage method

In order to store all incoming traffic on a LIN channel use a bus tracing method for storage. Please refer to ( $\rightarrow$  12.9).



Import: IPEmotionDemo XCP_V1.4	×
· · · · · · · · · · · · · · · · · · ·	
Command-Timeout: 2000	
ReInit Timeout: 5	
Time stamp size: 4	
Time stamp resolution: DAQ_TIMESTAMP_ Time stamp ticks: 1	UNIT *
Time stamp tixed:	
The stanp fixed 💽	
Ethernet	
Target IP address: 192.168.0.2	
Port: 11000	
Hostname:	
MediaType: Auto	T
Source IP address: <b>192.168.0.254</b>	
Image: A mage: A ma	15
💮 Internal	0
🔺 💮 🛛 Front	15
A 📻 IPETRONIK	10
🔺 🚡 🛛 IPEmotionDemo	10
🔺 👧 Socket 1	10
N Service	5
Execut	3
Service	2

## 6.10.2 Adding LIN channels

LIN channels can be added by selecting the tree element **"LIN interfaces"**, then clicking the **"Components"** button and then choosing "LIN channel".

#### LIN

Adds a LIN channel that corresponds to a physical LIN channel of your logger. For instructions on LIN settings refer to ( $\rightarrow$ 6.10.3).

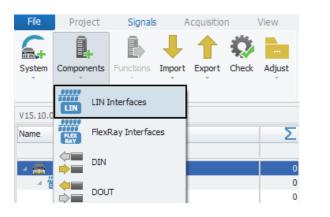
#### Multiple selection

Allows you to add multiple LIN channels of both types at the same time. To do so set the counter for each type to the desired number of channels that you wish to add as marked in the figure below.



**IPETRONIK** 

## 6.10 LIN CHANNELS



V15.10.00.13558 Beta		Name		Active	Description	Channel number	Wake On LIN	Baudrate	Timeout
Name	Σ	9							
		LIN 01		~	LIN interface	1	Disabled	9,6 kBd	0 s
ARCOS 1.5 - dataLog	0								
CAN Interfaces	0								
	0								
	0								
T CAN 03	0								
T CAN 04	0								
🔺 🎬 ETH Interfaces	0								
<ul> <li>Internal</li> </ul>	0								
💮 Front	0								
openABK	0								
usb Usb	0								
(x) Formulas	0								
🚔 Triggers	0	General							
Logfile messages	0	Act	ive: 🗹						
1 Internal signals	0		1 Thi Taba G						
4 🚞 Datasets	0	Na	me: LIN Interface	s					
Dataset	0	Descript	on: All grouped L	N interfac	ces				
4 🌒 Data transfer	0	Deferer	ce: LIN Interface						
1 Transfer events	0	Referen							
A A Connections	0								
USB USB	0								
<ul> <li>LIN Interfaces</li> </ul>	0								
	0								

PEmotion: Components selection - LIN Interfaces		×
Count Symbol Type Description		
B 🗘 📅 LIN LIN interface		
	ОК	Cancel

#### 6.10.3 LIN settings

By selecting one of the LIN channels in the tree you will be able to define this channel's settings in the details area.





	quisition View Check Adjust									
V15.10.0 Name Multiple selection	Σ									
V15.10.00.13558 Beta		Name		Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
Name	Σ ?									
CAN 02 CAN 03 CAN 03 CAN 04 ETH Interfaces Internal OpenABK USB Formulas Triggers Logfile messages Internal signals Datasets		Seneral IIN								
Datasets			Wake On LIN Hardware							
Dataset	0	Active:	×							
1 Transfer events	0	Name:	LIN 01							
A 🗟 Connections	0	Description:	LIN interface							
USB	0	Reference:	LIN 01/ARCOS 1.5 - dataLog							
LIN Interfaces      LIN 01      LIN 02      LIN 03      LIN 04	0 0 0	Kererente.	an expire of the datalog							
👗 LIN 04	0									

The same settings described in this section as part of the Details area can also be adjusted when selecting the tree element LIN interfaces and then directly changing the desired setting in the respective field of the **Grid area**.

#### 6.10.3.1 General

This tab allows you to give a user specific name for the selected LIN channel if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



The **Active** checkbox allows to deactivate the entire bus. If a bus is deactivated all childelements of this bus will be deactivated, too, and cannot be stored or traced, until the bus is reactivated.





General LIN	Wake On LIN Hardware
Active:	V
Name:	LIN 01
Description:	LIN interface
Reference:	LIN 01/ARCOS 1.5 - dataLog

## 6.10.3.2 LIN

eneral LIN Wake O	n LIN Hardware		
Baud rate:	9,6 kBd	<b>T</b>	
LIN version:	2.0		

#### Baud rate

The Baud rate is determined automatically by the logger.

#### LIN version

This field shows you the version of the LIN protocol that is used as described in the "Description file". This field cannot be changed.

## 6.10.3.3 Wake On LIN

Timeout: 0 s Mode: Disabled LIN ID: std 0 h std 0 h
LIN ID: std 0 h std 0 h
Datafield: 0 d

#### Timeout

For Wake On LIN, timeout has a special significance. It defines how long a waking channel must be inactive to be recognized so and therefore allow for the logger to shutdown. If timeout is recognized, an entry is made in the log file and an error message with an alert appears on the display, which has to be acknowledged.

#### Mode

This dropdown menu allows you to set the wake-up function for your selected LIN channel.

Changes and errors excepted.



Wake on LIN type	Characteristics
Disabled	No start on LIN messages, lowest energy
	consumption.
Enabled	Start on a LIN message, with first messa-
	ges lost; low energy consumption.
Enabled (no message lost)	Start on LIN message, with no message
	lost; slightly higher idle current.
Keep awake	The logger starts to other awakenings,
	but only shuts down if all the awakening-
	conditions are no longer fullfilled and if
	the keep awake condition is no longer
	fullfilled.

#### LIN ID - Settings for starting on a specific LIN ID

This functionality is the same for CAN and LIN interfaces and has been described in great detail earlier. Please refer to  $(\rightarrow 6.1.3.3)$ .

#### 6.10.3.4 Hardware (Channel number)

This tab allows you to set a **Channel number** for the selected LIN channel. This channel number has to be unique within the LIN interface.

General LIN Wake Or	LIN Hardware	
Channel number:	1	

i

For better orientation and in order to avoid confusion regarding Channelnumbers and -names, a Channels physical number can be found in the logger's **"Web Interface"** and set accordingly.

#### 6.10.4 LIN channel Bus statistic

The "Bus statistic" provides a range of statistics and status signals for the respective LIN channel. It contains information on the current state of the Bus, the Busload, as well as on the messages that have been received and errors that ocurred.

This functionality is the same for CAN and LIN interfaces and has been described in great detail earlier. Please refer to  $(\rightarrow 6.1.5)$ .



## 6.11 LIN signals

#### 6.11.1 Storage method

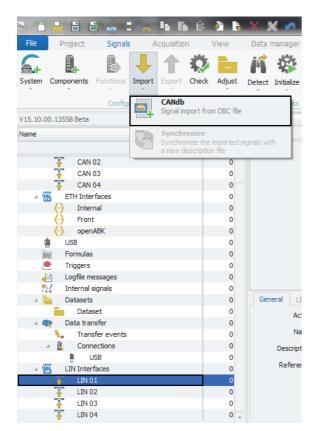
In order to store incoming signals on a LIN channel use one of the following signal storage methods.

- ATFX ( $\rightarrow$  12.6)
- MDF 4.0 ( $\rightarrow$  12.7)
- MDF 4.1 ( $\rightarrow$  12.8)

#### 6.11.2 Importing LIN signals

This section explains how to import LIN signals. The filetype to be used for importing LIN signals is a LINdb (LDF file).

To import signals, select the LIN channel to which you wish to import your signal in the tree, click the **"Import"** button in the ribbon and then choose **"CANdb"** as description file for the import. For more information on the "description file" refer to  $(\rightarrow 6.2.4.1)$ .



#### 6.11 LIN SIGNALS

The following window lets you choose which file you wish to import. The dropdown menu on the bottom right of the window shows you, which filetypes are available. Choose the file you wish to import and click **"Open"**.

Organisieren 🔻 🛛 Neue	r Ordner		-	≡ ▼ 🚺
Zuletzt besucht	Bibliothek "Dokumente"		Anordnen na	ich: Ordner 🔻
Bilder	Name	Änderungsdatum	Тур	Größe
Dokumente	IPEmotionDemo.DBC	19.02.2017 09:47	DBC-Datei	2 KB
🌙 Musik	IPEmotionDemo_Fibex.xml	19.02.2017 09:47	XML-Dokument	27 KB
Subversion ≡	IPEmotionDemo_J1939.dbc	19.02.2017 09:47	DBC-Datei	9 KB
Videos	IPEmotionDemoFD.DBC	19.02.2017 09:47	DBC-Datei	3 KB
	IPEspeed.dbc	19.02.2017 09:47	DBC-Datei	4 KB
🝓 Heimnetzgruppe	IPEspeed_from_V01_02_01.dbc	19.02.2017 09:47	DBC-Datei	4 KB
	WIPER_ROOF_204_172_2008_30a.ldf	11.12.2017 08:15	SQL Server Databa	17 KB
🖳 Computer				
🏭 Lokaler Datenträg				
👝 Lokaler Datenträg 🛫				
Datei			<ul> <li>All supported (*</li> </ul>	

Once you have opened your file, the **"Importer"** window will appear, that will present you with a range of importing options.

a column header here to	group by that column				Project Project numbe	
Name	Sampling rate	Selection	Message	LIN ID	Project versio	
					Protocol: LIN	
RsErr GDO	5 Hz	~	GDO_Frm1		Protocol	
_					Signal count	117
GDO_IntSw1_Psd	5 Hz	~	GDO_Frm1		Version	2,1
GDO_IntSw2_Psd	5 Hz	~	GDO_Frm1		CAN baud rat	19,2 kBd
GDO_IntSw3_Psd	5 Hz	<b>v</b>	GDO_Frm1		Message	-
GDO_LED_On_Rq	5 Hz	1	GDO_Frm1		Name	GDO_Frm1
GDO_General_Flt	5 Hz	~	GDO_Frm1	F.	CAN ID	std 1 h
GDO_Core_Flt	5 Hz	~	GDO_Frm1		Length	2
GDO Security Flt	5 Hz	~	GDO Frm1		Sampling rate	5 Hz
GDO Learn Flt	5 Hz	~	GDO Frm1		Description	
EnvLgtLvl	5 Hz	~	IMIRR Frm1		Sender name Cyclic	<b>v</b>
RsErr_IMIRR	5 Hz	~	IMIRR Frm1		Signal	
AmbLgtSens Flt	5 Hz	~	IMIRR Frm1		Name	RsErr_GDO
GlareLqtSens Flt	5 Hz	~	IMIRR Frm1		Display identif	
Mirr Adzzl	5 Hz	v	IMIRR Frm1		Byte order	
Mirr_Auzzi	5 112	•	IMIRK_FIIII	-	Data type	8-Bit integer unsi
				Þ	Bit count	1

In this dialog, all signals that can be imported from the description file are displayed. In the left table, all signals, where the "selection" checkboxes are selected, will be marked for import. You can either choose manually, which signals to import, you can use the **"Select/Deselect all"** button on the bottom left, or you can use a CSV-file to determine which signals are to be imported, by clicking **"Select by CSV"** on the bottom left.

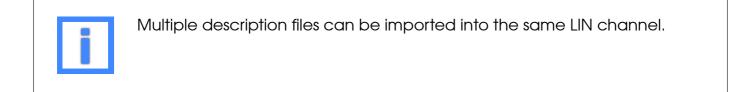






In the right table the properties of the selected signals, the control unit and the protocol are displayed.

Once you have choosen all the signals you wish to import, click **"OK"** to complete the import procedure.

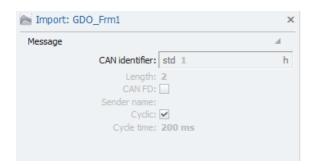


#### 6.11.3 Import properties

The "Import properties" of a description file, Message or signal allow you to see certain properties such as the Data format, the LIN identifier, the Bit mask, the start bit, bit count and more. It shows the signal's properties as described by the description file.



Example for "Import properties" of a LIN description file



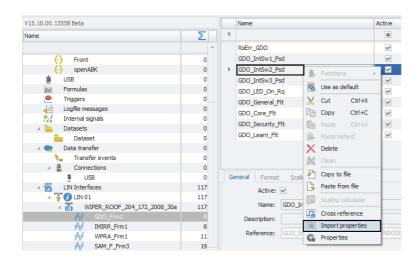
Example for "Import properties" of a LIN Message



Example for "Import properties" of a LIN signal



To access the "Import properties" rightclick on any desired description file, Message or signal and then choose "Import properties" from the resulting context menu.



#### 6.11.4 Signal properties

#### 6.11.4.1 Tree elements for LIN signals

After having successfully imported the desired signals to your LIN channel, this channel will contain two new layers of child elements in the measurement task tree: The **"Description** file" and the **"Message**".

#### Description file

The "description file" is a database file which contains signal information and can be used to import those signals into a Signal channel in IPEmotion. The filetypes which are supported by the CAETEC Plugin for IPEmotion depend on the type of signal you wish to import.

The symbol in the left part of the tree element shows you the type of "description file" you imported (in this case a "LDF" file), then follows the name of the imported "description file" (in this case "WIPER\_ROOF\_...") and on the right is a number indicating how many signals the "description file" contains (in this case 117).

4 🐻 LIN Interfaces	117
4 ∓ 🕖 LIN 01	117
WIPER_ROOF_204_172_2008_30a	117
GDO_Frm1	9
MIRR_Frm1	8
WPRA_Frm1	11
SAM_F_Frm3	19
OHCM_Frm	20
LRSM_Frm1	21
SAM_F_Frm1	20
SAM_F_Frm2	9
🚹 LIN 02	0
🐺 LIN 03	0



#### Message

Each "description file" can contain one or more "Messages", which then contain the actual signals. A "Message" can be found in the "Measurement task tree" as a child element of the "description file", it belongs to.

Each "Message" can, again, contain one or more signals, which is indicated by the number on the right of the "Message's" name.

IIN Interfaces	117
🗍 🏋 🕜 LIN 01	117
WIPER_ROOF_204_172_2008_30a	117
GDO_Frm1	9
MIRR_Frm1	8
WPRA_Frm1	11
SAM_F_Frm3	19
OHCM_Frm	20
LRSM_Frm1	21
SAM_F_Frm1	20
SAM_F_Frm2	9
T LIN 02	0
T LIN 03	0

#### 6.11.4.2 Grid area for LIN signals

In the "grid area" you will be presented with an overview of your selected LIN channel's signals. Also you can find here two important functions, which are the "Column chooser"  $(\rightarrow 4.3.1)$  and the "Filter editor"  $(\rightarrow 4.3.2)$ .



#### 6.11.4.3 Details area for LIN signals

The Details area shows settings either for the selected tree element ("description file" or "Message") or the selected signal in the grid area. In case a tree element is selected, the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).

In case a signal is selected in the grid area, the details area will contain additional tabs which will be explained in the following.

#### General

Please refer to  $(\rightarrow 4.2.2)$ .

#### Format

This tab contains information and options regarding file format, tasks and Channel type.

General <b>Format</b> Scaling Display Sig	inal	
Data type		
Type: 8-Bit integer unsigned	Task: Default	•
NoValue / DefaultValue		
Value: +FullScale	<ul> <li>Deactivate NoValue and use Default Value</li> </ul>	
Channel type		
Input: 🗹	Output:	

#### • Data type

This field tells you the type of data (in this case **"8-Bit integer unsigned"**) and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

#### • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

#### • Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.



## Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

General Format	Scaling Display Signal		
Sensor mode			
Mode:	Status	▼	Scaling calculator
Sensor range			
Min:	0 -	Max: 1 -	Unit: 🔍
Physical range			
Min:	0	Max: 1	Unit:

#### • Sensor Mode

The sensor mode tells the type of signal. It can be of different types such as "Status", "Voltage", "Frequenzy" or others. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.

• Sensor Range

Shows the raw value range of the signal.

#### • Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5** "Channel configuration and scaling".



### Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General Format Scaling Display Signal
Displaying area
Min: 0 Max: 1
Formatting
Decimal places: Automatic 👻
Name
Name: 10 ms sync event channel configured

#### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

#### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

#### • Name

Allows you to set a Name to be shown on a display.

#### Limit values

This tab allows you to define limit values for a signal and what action to take upon a limit value violation.

General Format Scalin	General Format Scaling Display Limit values Signal Signal check				
Out of bound or invalid values					
Rejected value: will be dropped					
Valid ranges (Lower/Upper)		Invalid values (Physical/Raw)			
1: 0	0	1: 0 0	d		
2: 0	0	2: 0 0	d		
3: 0	0	3: 0 0	d		

#### • Rejected value

Define what happens to a value, that has been rejected because it is out of bound or invalid. By default this value will be dropped. It can also be written as NaN.



#### • Valid ranges (Lower/Upper)

Define up to three ranges of valid signal values. Activate a range in order to define its upper/lower value (datatype double). Range 2 can only be activated if range 1 is and range 3 can only be activated if range 2 is.

#### • Invalid values (Physical/Raw)

Define up to three invalid values. Activate an invalid value in order to define the physical value (datatype double) or raw value (datatype integer). If one of the two has been typed in, the other will be calculated according to the scale/offset settings in the scaling calculator.

Invalid value 2 can only be activated if invalid value 1 is and invalid value 3 can only be activated if invalid value 2 is.

For details on how to use the "Scaling calculator" please refer to the **IPEmotion Do**cumentation - Section 3.4.5 "Channel configuration and scaling".

#### Signal

This tab allows you to define signal settings.

neral Format Scal	ng Display Signal	
Special function:	None	Ŧ
Internal data type:	Double	<b>v</b>
Signalnumber:		
Last value hold:	Until the next reboot	•
Timeout:	0 s	
Namespace:	'CAN 01'::'SIM_51499999_	
		63

#### Internal data type

Assign an internal data type to the signal. Available data types are **"Double"** and **"String"**.

• Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

• Last value hold

Specify, for how long the last value of the signal will be hold.

• Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.

#### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.

Changes and errors excepted.



#### Signal check

This tab allows you to activate "Signal check" for this signal. You may choose whether you wish to apply the global signal check settings to this signal or override the global settings with settings specific for this signal.

Global signal check settings have to be defined first. For information on how to do so and for general information on "Signal check" please refer to ( $\rightarrow$ 4.2.2).

General	Format	Scaling	Display	Signal	Signal check	Limit values
1	Use signal d	heck: 🗹				
	N	4ode: Glo	bal settings			
	Start-tri	gger:				Select
	Stop-tri	gger:				Select
	Tim	eout: 30 :	S			



## 6.12 FlexRay channels

To work with "FlexRay channels", you will first have to add the tree element "FlexRay interfaces" to your measurement task tree. To do so, select your system in the measurement task tree, click the "Components" button in the ribbon and choose "FlexRay interfaces" from the resulting dropdown menu.

File	Project	Signals	A	cquisitio	n	View
6.			↓		Ô	
System	Components	Functions	Import	Export	Check	Adjust
V15.10.0	LIN Interfaces					Σ
× 📾						0
″ĕ		т				0

Once the "FlexRay interfaces" component has been added it will appear in the measurement task tree as a tree element with one "FlexRay channel" as a child element.

V15.10.00.13558 Beta		Nam	e	Active	Description	Channel number	Wake On FlexRay	Timeout
Name	Σ	۴						
		Flex	Ray 01	~	FlexRay Interface	1	Disabled	0 s
ARCOS 1.5 - dataLog	0							
CAN Interfaces	0							
	0							
CAN 02	0							
👬 CAN 03	0							
T CAN 04	0							
🔺 🚟 ETH Interfaces	0							
💮 Internal	0							
	0							
openABK	0							
i USB	0							
f(x) Formulas	0							
🚔 Triggers	0	Genera						
Logfile messages	0		Active: 🗹					
nternal signals	0			_				
🔺 🚞 Datasets	0		Name: FlexRay Int	erfaces				
Dataset	0	D	escription: All grouped	FlexRay in	terfaces			
4 🦣 🛛 Data transfer	0		-frances []					
🐛 Transfer events	0	н	eference: FlexRay Int		COS 1.5 - dataLog			
Connections	0							
USB USB	0							
🔺 🙀 🛛 FlexRay Interfaces	0							
FlexRay 01	0							

#### 6.12.1 Storage method

In order to store all incoming traffic on a FlexRay channel use a bus tracing method for storage. Please refer to ( $\rightarrow$  12.9).



### 6.12.2 Adding FlexRay channels

FlexRay channels can be added by selecting the tree element **"FlexRay interfaces"**, then clicking the **"Components"** button and then choosing "FlexRay channel".

### FlexRay

Adds a FlexRay channel that corresponds to a physical FlexRay channel of your logger. For instructions on FlexRay settings refer to  $(\rightarrow 6.12.3)$ .

File	Project	Signals	A	Acquisition		View	
6.			₽	$\mathbf{\uparrow}$			
System ~	Components ,	Functions	Import T	Export	Check	Adjust	
V15.10.0	Flexi	Ray					
Name						Σ	

#### Multiple selection

Allows you to add multiple FlexRay channels of both types at the same time. To do so set the counter for each type to the desired number of channels that you wish to add as marked in the figure below.

峇 IPEm	PEmotion: Components selection - FlexRay Interfaces						
Count	Symbol	Туре	Description				
	β‡ <del>`</del>	FlexRay	FlexRay Interface				
				OK	Cancel		

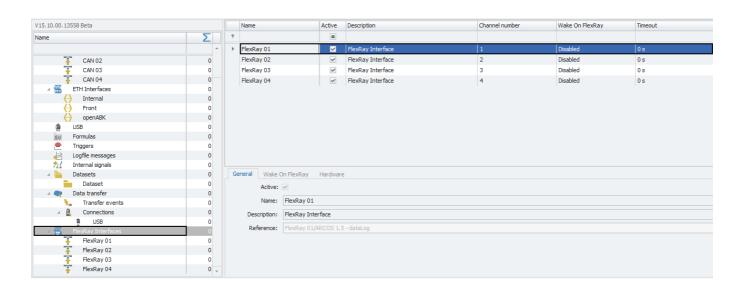
## 6.12.3 FlexRay settings

By selecting the "FlexRay Interfaces" in the tree and the choosing one of the FlexRay channels in the grid area you will be able to define this channel's settings in the details area.

> The same settings described in this section as part of the Details area can also be adjusted when selecting the desired channel in the grid area and then directly changing the desired setting in the respective field of the **Grid area**.



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#### 6.12.3.1 General

This tab allows you to give a user specific name for the selected FlexRay channel if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



The **Active** checkbox allows to deactivate the entire bus. If a bus is deactivated all childelements of this bus will be deactivated, too, and cannot be stored or traced, until the bus is reactivated.

General Wake	On FlexRay Hardware
Active	: 🗹
Name:	FlexRay 01
Description:	FlexRay Interface
Reference:	FlexRay 01/ARCOS 1.5 - dataLog

## 6.12.3.2 Wake On FlexRay



## Timeout

Timeout defines how long a waking channel must be inactive to be recognized so and therefore allow for the logger to shutdown. If timeout is recognized, an entry is made in the log file and an error message with an alert appears on the display, which has to be acknowledged.

### Mode

This dropdown menu allows you to set the wake-up function for your selected FlexRay channel.

Wake on FlexRay type	Characteristics
Disabled	No start on FlexRay messages, lowest
	energy consumption.
Enabled	Start on a FlexRay message, with first
	messages lost; low energy consump-
	tion.
Keep awake	The logger starts to other awakenings,
	but only shuts down if all the awakening-
	conditions are no longer fullfilled and if
	the keep awake condition is no longer
	fullfilled.

## 6.12.3.3 Hardware (Channel number)

This tab allows you to set a **Channel number** for the selected FlexRay channel. This channel number has to be unique within the FlexRay interface.

General Wake On FlexRa	ay Hardware
Channel number:	1

For better orientation and in order to avoid confusion regarding Channelnumbers and -names, a Channels physical number can be found in the logger's **"Web Interface"** and set accordingly.

## 6.12.4 FlexRay channel Bus statistic

The "Bus statistic" for FlexRay provides only one entry on the current status of the FlexRay bus.

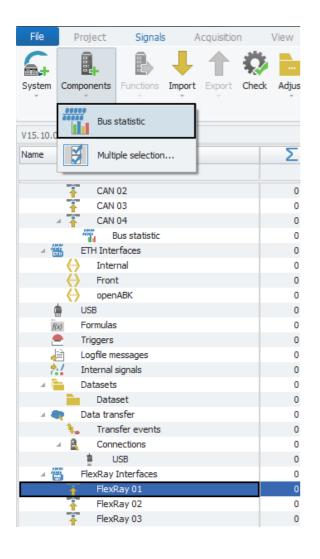




The "Bus statistic" only shows statistics for the channel to which it belongs. For each channel that you would like to see the statistic, you will have to add the component "Bus statistic".

## 6.12.4.1 Adding Bus statistics

Select the channel in the tree for which you would like to add "Bus statistic", then click the "Components" button in the Ribbon and choose "Bus statistic".



## 6.12.4.2 Bus statistic signals

Once the component "Bus statistic" has been added to your channel, it will appear in the measurement task tree as a child element of this channel and the grid area will give you an overview of the available signals.

The signals included in "Bus statistics" are of the type "Internal signal" and may be adjusted in the same way. For more information on "Internal signals" please refer to ( $\rightarrow$ 6.22).





## Overview of signals

Subtype	Meaning	Unit
Controller state	nan= Channel not available 1= Bus on 2= Bus warning 3= Bus off	-



## 6.13 FlexRay signals

#### 6.13.1 Storage method

In order to store incoming signals on a FlexRay channel use one of the following signal storage methods.

- ATFX ( $\rightarrow$  12.6)
- MDF 4.0 ( $\rightarrow$  12.7)
- MDF 4.1 ( $\rightarrow$  12.8)

## 6.13.2 Importing FlexRay signals

This section explains how to import FlexRay signals. There are three different filetypes which can be used in order to import a single FlexRay signal or a group of FlexRay signals:

- Autosar files
- A2L files
- Fibex files

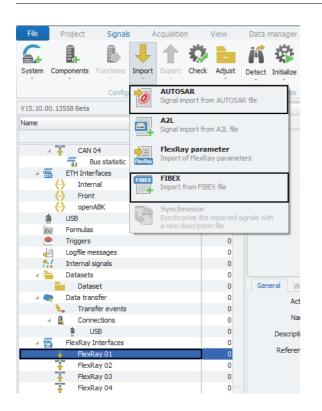
## 6.13.2.1 Importing Autosar and Fibex files

The procedure for both filtetypes is the same and will be exemplary explained in the following via the "Fibex" import.

To import Signals, select the FlexRay channel to which you wish to import your signal in the tree, click the **"Import"** button in the ribbon and then choose **"Autosar"** or **"Fibex"** for the import. For more information on the "description file" refer to ( $\rightarrow$ 6.2.4.1).



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The following window lets you choose which file you wish to import. The dropdown menu on the bottom right of the window shows you, which filetypes are available. Choose the file you wish to import and click **"Open"**.

🦳 Öffnen						x
OO 🗸 🕌 « Öffent	tliche Dokum	ente 🕨 IPETRONIK 🕨 IPEmotion	n 🕨 Import 🔷 👻	✓ Import durchse	ıchen	٩
Organisieren 🔻 Ne	euer Ordner			8	=	0
☆ Favoriten ■ Desktop	Bibl			Anordnen na	ich: Ordner 🔻	
Downloads	Name	*	Änderungsdatum	Тур	Größe	
🖳 Zuletzt besucht	E 🔮 IPE	motionDemo_Fibex.xml	19.02.2017 09:47	XML-Dokument	27 KB	
詞 Bibliotheken						
📔 Bilder						
Dokumente						
🚽 Musik						
Subversion						
Videos						
🔞 Heimnetzgruppe	-					
Da	iteiname:			▼         FIBEX (*.xml)           Öffnen         ▼	Abbreche	• n

Once you have opened your file, the **"Importer"** window will appear, that will present you with a range of importing options.

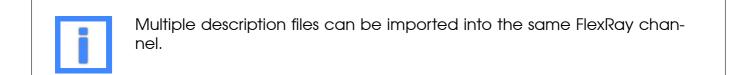
In this dialog, all signals that can be imported from the description file are displayed. In the left table, all signals, where the "selection" checkboxes are selected, will be marked for import. You can either choose manually, which signals to import, you can use the **"Select/Deselect all"** button on the bottom left, or you can use a CSV-file to determine which signals are to be imported, by clicking **"Select by CSV"** on the bottom left.



	a column boadar bara	to group by that column				Project	*
ay	a column neader nere	to group by that column				Project numbe	
	Name	Sampling rate	Selection	Frame	ID	Project versio	
			=			Protocol: FlexRay	*
	Request	200 Hz	~	frmRequest		Protocol	FlexRay
	Response	200 Hz	~	frmResponse		Signal count	6
	Counter			frmSimulationCounter		FlexRay baud	10 MBd
		200 Hz	~			Channel ref	ChannelA 🔻
	CounterCRC	200 Hz	~	frmSimulationCounter		Cold start atte	31
	Sinus	200 Hz	~	frmSimulationSinus		Listen noise	2
	SinusCRC	200 Hz	<b>~</b>	frmSimulationSinus		Macroticks per	3636
						Max without c	1
						Max without c	1
						Network mana	0 bytes
						Number of mir	289
						Start offset co	91
						Pavload lengt	
						Sync node ma	8 WORDS 15
						Action point o	2
						Cas Rx low ma	79
						Dynamic slot i	1
					Þ		1

In the right table the properties of the selected signals, the control unit and the protocol are displayed.

Once you have choosen all the signals you wish to import, click **"OK"** to complete the import procedure.





#### 6.13.2.2 Importing A2L files (XCP on FlexRay)

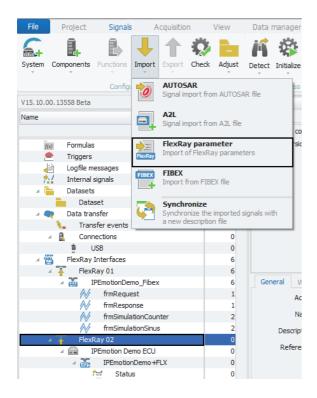
The Import of CCP/XCP databases via A2L files for FlexRay follows the same procedure as the CCP/XCP import via A2L file for CAN. Please refer to ( $\rightarrow$ 6.3.2).

When importing signals from a CCP/XCP database via A2L file, you will need to additionally import the flexray parameters from a Fibex file as described below.

#### Importing FlexRay parameters

When creating a FlexRay XCP measurement task via an A2L file, it is necessary to import the FlexRay parameters via a Fibex file once the A2L file has been imported. Otherwise, the communication between ECU and FlexRay bus cannot be established.

To import FlexRay parameters, select the FlexRay channel to which you wish to import your signal in the tree, click the **"Import"** button in the ribbon and then choose **"FlexRay parameters"** for the import.





The following window lets you choose which Fibex file you wish to import. Choose the file you wish to import and click **"Open"**.

🦱 Öffnen						x		
🔾 🖓 « Öffentliche Dokumente 🕨 IPETRONIK 🕨 IPEmotion 🕨 Import 🧹 🍫 🗍 Import durchsuchen 🖌								
Organisieren 🔻 No	euer Ordne	r		-	≣ ▼ 📶	0		
ጵ Favoriten 📃 Desktop		bliothek "Dokumente"		Anordnen na	ch: Ordner 🔻			
Downloads	Nar	me	Änderungsdatum	Тур	Größe			
🗐 Zuletzt besucht	=	IPEmotionDemo_Fibex.xml	19.02.2017 09:47	XML-Dokument	27 KB			
詞 Bibliotheken								
📔 Bilder								
Dokumente								
J Musik								
Subversion								
Videos								
🔞 Heimnetzgruppe	-							
Di	ateiname:			✓ FIBEX (*.xml)	_	-		
				Öffnen	Abbrecher			

The following window lets you choose the ECU controller with which the FlexRay bus is supposed to communicate. Normally the right controller to choose is called **"XCP Master"**. Select your desired controller and confirm with **"OK"**.

Name	Description	Reference
ctrIPC		ctrIPC
ctrlSimulation		ctrlSimulation
ctrlMonitor		ctrlMonitor
XCP Master		XCP Master

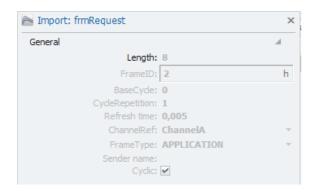


#### 6.13.3 Import properties

The "Import properties" of a description file, Message or signal allow you to see certain properties such as the Data format, the FlexRay identifier, the Bit mask, the start bit, bit count, optional commands and more. It shows the signal's properties as described by the description file.

Import: FlexRay 01	× 🚵 Import: FlexRay 01	
lobal parameter		
Baud rate: 10 MBd		
ChannelRef: ChannelA	Local parameters	-
ColdStartAttempts: 31	AllowHaltDueToClock: 🗹	
ListenNoise: 2	AllowPassiveToActive: 0	
MacroPerCycle: 3636	ClusterDriftDamping: 2	
xWithoutClockCorrectionFatal: 1	DecodingCorrection: 48	
VithoutClockCorrectionPassive: 1	DelayCompensationA: 1	
orkManagementVectorLength: 0	DelayCompensationB: 1	
NumberOfMinislots: 289	ExternOffsetCorrection: 0	
NumberOfStaticSlots: 91	ExternRateCorrection: 0	
OffsetCorrectionStart: 3632	KeySlotId: 64	
PayloadLengthStatic: 8	KeySlotUsedForStartup:	
SyncNodeMax: 15	KeySlotUsedForSync:	
ActionPointOffset: 2	LatestTx: 281	
CasRxLowMax: 79	MacroInitialOffsetA: 5	
DynamicSlotIdlePhase: 1	MacroInitialOffsetB: 5	
Macro tic: 1,375	MicroInitialOffsetA: 6	
Minislot: 5	MicroInitialOffsetB: 6	
MinislotActionPointOffset: 2	MaxPayloadLengthDynamic: 16	
Nit: 7	MicroPerCycle: 200000	
StaticSlot: 24	OffsetCorrectionOut: 126	
SymbolWindow: 0	RateCorrectionOut: 81	
TssTransmitter: 9	SamplesPerMicrotick: 2	
WakeupSymbolRxIdle: 59	SingleSlotEnabled:	
WakeupSymbolicxLow: 50	WakeupChannel: ChannelA	
WakeupSymbolRxWindow: 301	WakeupPattern: 63	
WakeupSymbolRXWindow: 301 WakeupSymbolTxIdle: 180	AcceptedStartupRange: 212	
WakeupSymbolTxLow; 60	ListenTimeout: 400162	
	MaxDrift: 81	
Cyde: 5000	Micro tic: 0,025	
MaxInitializationError: 2,648	MicroPerMacroNom: 20	
SampleClockPeriod: 0,0125	KeySlotUsage: 64	
_		
<b>—</b>	Ψ	

Example for "Import properties" of a FlexRay description file



Example for "Import properties" of a FlexRay Message







Example for "Import properties" of a FlexRay signal

To access the "Import properties" rightclick on any desired description file, Message or signal and then choose "Import properties" from the resulting context menu.

V15.10.00.13558 Beta	Name Activ	
Name	Σ	۹
	*	Request
i USB	0	Response     B. Functions
f(x) Formulas	0	Counter
🚔 Triggers	0	CounterCRC 🚳 Use as default
Logfile messages	0	Sinus 📈 Cut Ctrl+X 🗸
📩 Internal signals	0	SinusCRC
🔺 🚞 Datasets	0	
Dataset	0	Paste Ctrl+V
🔺 🦣 🛛 Data transfer	0	Paste behind
1 Transfer events	0	X Delete
Connections	0	Mr Clean
USB USB	0	
FlexRay Interfaces	6	Copy to file
🛛 👬 FlexRay 01	6	General Format Sca 🔓 Paste from file
IPEmotionDemo_Fibex	6	Active: 🖌 🔯 Scaling calculator
M frmRequest	1	
frmResponse	1	Name: Respo 🌆 Cross reference
frmSimulationCounter	2	Description: Respo Import properties
frmSimulationSinus	2	Properties
FlexRay 02	0	Reference: Respdemoemoemoemo



#### 6.13.4 Signal properties

#### 6.13.4.1 Tree elements for FlexRay signals

The Tree elements available after import for your FlexRay channel depend on the Method you used for importing the signals.

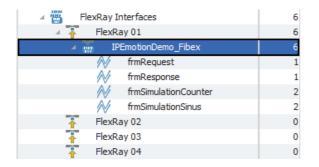
If you imported an A2L file, the resulting tree elements will be equal to a CCP/XCP import on a CAN channel. Please refer to  $(\rightarrow 6.3.4.1)$ .

If you imported a Fibex file to your FlexRay channel, this channel will contain two new layers of child elements in the measurement task tree: The **"Description file"** and the **"Message"**.

#### Description file

The "description file" is the database file which contains signal information and can be used to import those signals into a Signal channel in IPEmotion.

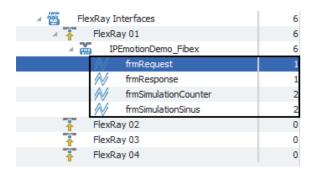
The tree element shows the "description file's" name (in this case "IPEmotionDemo\_Fibex") and, on the right, the number of signals it contains (in this case 6).



#### Message

Each "description file" can contain one or more "Messages", which then contain the actual signals. A "Message" can be found in the "Measurement task tree" as a child element of the "description file", it belongs to.

Each "Message" can, again, contain one or more signals, which is indicated by the number on the right of the "Message's" name.





### 6.13.4.2 Grid area for FlexRay signals

In the "grid area" you will be presented with an overview of your selected FlexRay channel's signals. Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

### 6.13.4.3 Details area for FlexRay signals

The Details area shows settings either for the selected tree element ("description file" or "Message") or the selected signal in the grid area. In case a tree element is selected, the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).

In case a signal is selected in the grid area, the details area will contain additional tabs which will be explained in the following.

#### General

This tab allows you to activate or deactivate the entire signal by ticking/unticking the checkbox, give a user specific name to your signal if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed. The "Sampling rate" allows you to set, how frequently a signal should be requested.

### Format

This tab contains information and options regarding file format, tasks and Channel type.

General	Format Scaling Display Sig	gnal
Data type		
	Type: 16-Bit integer unsigned	▼ Task: Default ▼
NoValue / [	DefaultValue	
	Value: +FullScale	<ul> <li>Deactivate NoValue and use Default Value</li> </ul>
Channel ty	pe	
	Input: 🗹	Output:

#### • Data type

This field tells you the type of data (in this case **"16-Bit integer unsigned"**) and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

#### • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

#### • Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.

Changes and errors excepted.



# Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.



In some cases it may be necessary to activate editing of protocol channel scaling in order to gain full acces to the scaling functionality. For instructions please refer to the point "Edit protocol channel scaling" of the Expert settings ( $\rightarrow$  3.2.2).

General Format	Scaling Display	Signal		
Sensor mode				
Mode:	Status		Ŧ	Scaling calculator
Sensor range				
Min:	0 🔻	Max: 1	Ŧ	Unit: 📃 👻
Physical range				
Min:	0	Max: 1		Unit:

#### • Sensor Mode

The sensor mode tells the type of signal. It can be of different types such as "Status", "Voltage", "Frequenzy" or others. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.

### • Sensor Range

Shows the raw value range of the signal.

### • Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5** "Channel configuration and scaling".



### Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General     Format     Scaling     Display     Signal       Displaying area     Min:     0     Max:     65535       Formatting       Decimal places:     Automatic     ▼       Name
Min:     0     Max:     65535       Formatting       Decimal places:     Automatic
Formatting Decimal places: Automatic
Decimal places: Automatic 🔹
Name
Name: SinusCRC

### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

#### • Name

Allows you to set a Name to be shown on a display.



If the regular FlexRay namespace creates ambiguos names, it may be useful, to work with extended FlexRay namespaces. For instructions please refer to ( $\rightarrow$ 3.2.2).

# Limit values

This tab allows you to define limit values for a signal and what action to take upon a limit value violation.

General	Format Sca	ing Display	Limit values	Signal	Signal che	ck			
Out of bou	und or invalid val	ues							
	Rejected value:	will be dropped	i		-				
Valid range	es (Lower/Upper	)				Invalid value	s (Physical/Raw)		
1:	0		0			1:	0		d
2:	0		0			2:	0	0	d
3:	0		0			3:	0		d

### • Rejected value

Define what happens to a value, that has been rejected because it is out of bound or invalid. By default this value will be dropped. It can also be written as NaN.

# • Valid ranges (Lower/Upper)

Define up to three ranges of valid signal values. Activate a range in order to define its upper/lower value (datatype double). Range 2 can only be activated if range 1 is and range 3 can only be activated if range 2 is.

### Invalid values (Physical/Raw)

Define up to three invalid values. Activate an invalid value in order to define the physical value (datatype double) or raw value (datatype integer). If one of the two has been typed in, the other will be calculated according to the scale/offset settings in the scaling calculator.

Invalid value 2 can only be activated if invalid value 1 is and invalid value 3 can only be activated if invalid value 2 is.

For details on how to use the "Scaling calculator" please refer to the **IPEmotion Do**cumentation - Section 3.4.5 "Channel configuration and scaling".



# Signal

This tab allows you to define signal settings.

General Format Scal	ing Display Signal
Special function:	None 🔻
Internal data type:	Double •
Signalnumber:	
Last value hold:	Until the next reboot 🔹
Timeout:	0 s
Namespace:	'FlexRay 01'::'frmSimulationSinus'::'12'

### • Internal data type

Assign an internal data type to the signal. Available data types are **"Double"** and **"String"**.

### • Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

#### • Last value hold

Specify, for how long the last value of the signal will be hold.

#### • Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.

#### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.



### Signal check

This tab allows you to activate "Signal check" for this signal. You may choose whether you wish to apply the global signal check settings to this signal or override the global settings with settings specific for this signal.

Global signal check settings have to be defined first. For information on how to do so and for general information on "Signal check" please refer to ( $\rightarrow$ 4.2.2).

Use signal check:  Mode: Global settings  Start-trigger: Select
Mode: Global settings
Stop-trigger: Select
Timeout: 30 s



# 6.14 GPS Signals

The GPS module sends a constant stream of values to the logger. Its configuration defines which values from this data stream are to be evaluated and made available for further use.

# 6.14.1 Storage method

In order to store incoming GPS signals you can use the GPX storage method. These signals will then be stored in a separate file only containing your GPS signals.

• GPX (→ 12.13)

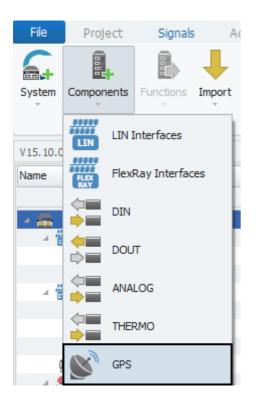
You can also store your GPS signals together with signals from other buses. To do so use one of the following signal storage methods.

- ATFX ( $\rightarrow$  12.6)
- MDF 4.0 ( $\rightarrow$  12.7)
- MDF 4.1 ( $\rightarrow$  12.8)

# 6.14.2 Adding GPS Signals

# 6.14.2.1 CAETEC GPS module

In order to use the CAETEC GPS module, select your system (Arcos 1.x, µcros) in the "Measurement task tree", click the "Components" button in the Ribbon and choose "GPS".



### 6.14.2.2 Other GPS signals (Assigning GPS signals)

If you are not using the CAETEC GPS module, but are receiving GPS signals on your logger GPS tasks have to be manually assigned to the respective signals in order to store those signals in a GPX file.

To assign a GPS task to a signal, select the desired signal in the "Grid area" and then activate it by ticking the "Active" box in the signal's "Details area".

V15.10.00.14946 Beta			Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate	Special function
Name	Σ	٩									
	*		GPS date			0	991231	0	991231	10 Hz	None
N SIM_50 199999	4		GPS altitude		m	-600	9000	-600	9000	10 Hz	None
M SIM_50199999	2		GPS horizontal precision			1	99,9	1	99,9	10 Hz	None
ETH Interfaces	0		GPS estimated horizontal p		m	0	25	0	25	10 Hz	None
💮 Internal	0		GPS track angle		•	-180	180	-180	180	10 Hz	None
- Front	0	+	GPS latitude	~	0	-90	90	-90	90	10 Hz	None
openABK	0		GPS longitude		0	-180	180	-180	180	10 Hz	None
USB	0		GPS satellites number			0	24	0	24	10 Hz	None
Triggers Standard Triggers	0		GPS status			0	2	0	2	10 Hz	None
Standard Triggers	0		GPS time			0	235959	0	235959	10 Hz	None
Cyclic Triggers	0		GPS speed		km/h	0	2400	0	2400	10 Hz	None
Trigger Groups	o										
(ix) Formulas	0	Ge	eneral Format Scaling	Display	Signal						
1 Internal signals	0		Active: 🖌								
🔺 🚞 Datasets	0										
A Dataset	0		Name: GPS latitude								
A B GPX	0		Description: Signal showing	ng GPS inf	ormation						
🍇 GPS Tracking	1		Reference: GPS latitude/		1.5 - data						
🔺 🦣 🛛 Data transfer	0										
1. Transfer events	0		Sampling rate: 10 Hz								
Connections	0										
USB	0										
S GPS	1 -										

Then navigate to the "Format" tab in the signal's "Details area" and use the dropdown menu "Tasks" to assign the desired GPS task.

/15.10.00.16458 RC			Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
lame	Σ	۴								
			GPS date			0	991231	0	991231	10 Hz
ARCOS 1.5	1		GPS altitude		m	-600	9000	-600	9000	10 Hz
A CAN interfaces	0		GPS horizontal precision			1	99,9	1	99,9	10 Hz
	0		GPS estimated horizontal p		m	0	25	0	25	10 Hz
	0		GPS track angle		•	-180	180	-180	180	10 Hz
ETH interfaces	0	•	GPS latitude	~	•	-90	90	-90	90	10 Hz
Internal	0		GPS longitude		•	-180	180	-180	180	10 Hz
💮 Front	0		GPS satellites number			0	24	0	24	10 Hz
openABK	0		GPS status			0	2	0	2	10 Hz
USB	0					-		-		
🔺 🚔 Triggers	0		GPS time			0	235959	0	235959	10 Hz
Standard triggers	0		GPS speed		km/h	0	2400	0	2400	10 Hz
💂 Level triggers	0									
🗂 Cyclic triggers	0									
🛸 Trigger groups	0									
(ix) Formulas	0	Ge	eneral Format Scaling	Display	Signal					
🔺 📩 Internal signals	0									
Run state	0	D	iata type							
⊿ 📴 Datasets	0		Type: 64-Bit floati	ing point		Ŧ	Task: GPS la	atitude in degree	es	~
Dataset	0						Defa	ult		
🔺 🗬 🛛 Data transfer	0	N	loValue / DefaultValue				GPS I	ongitude in degi	ees	
🐛 Transfer events	0		Value: NaN			T De		ongitude in NME		
A 🤮 Connections	0						GPST	atitude in degre atitude in NMEA		-
USB	0	C	hannel type					atitude in NMEA altitude	raw format	
S GPS	1		Input: 🗸				GPS 6			-



Each GPS task can only be assigned to one signal. That means, if you reassign a previously already assigned GPS task to a new signal, make sure to unassign this task from its previously assigned signal.

Using the "Check" function will tell you, whether you have multiply assigned tasks.

### 6.14.3 Signal properties

#### 6.14.3.1 Tree elements for GPS signals

There is one tree element for GPS signals, called "GPS". In the right table of the "Measurement task tree" a number will indicate how many active signals it contains (in this case 2).



### 6.14.3.2 Grid area for GPS signals

In the "Grid area" you will be presented with an overview of the availabe GPS signals. Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

Subtype	Meaning	Unit
GPS date	GPS date UTC yymmdd	-
GPS altitude	Elevation above sea level	(m)
GPS horizontal precision	Horizontal Dilution of Precision	-
GPS estimated horizontal pre-	Estimation of horizontal dilu-	(m)
cision	tion of precision (probability 95%)	
GPS track angle	Inclination of the track	(°)
GPS latitude	Latitude	(°)
GPS longitude	Longitude	(°)
GPS satellites number	Number of received satellites	-
	0 = no connection	
GPS status	1 = connection	-
	2 = Egnos active	
GPS time	GPS time UTC hhmmss	-
GPS speed	Current speed	(km/h)

Overview of GPS signals

#### 6.14.3.3 Details area for GPS signals

The Details area shows settings either for the tree element "GPS" or a selected signal in the grid area. In case the tree element "GPS" is selected, the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).



In case a signal is selected in the grid area, the details area will contain additional tabs which will be explained in the following.

#### General

This tab allows you to activate or deactivate the entire signal by ticking/unticking the checkbox, give a user specific name to your signal if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed. The "Sampling rate" allows you to set, how frequently a signal should be requested.

### Format

This tab contains information and options regarding file format, tasks and Channel type.

General Format Scaling Display	Signal
Data type	
Type: 32-Bit integer unsigned	▼ Task: Default ▼
NoValue / DefaultValue	
Value: -FullScale	Deactivate NoValue and use Default Value
Channel type	
Input: 🗹	Output:

### • Data type

This field tells you the type of data (in this case **"32-Bit integer unsigned"**) and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

#### • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

### • Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.



# Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

In some cases it may be necessary to activate editing of protocol channel scaling in order to gain full acces to the scaling functionality. For instructions please refer to the point **"Edit protocol channel scaling"** of the Expert settings ( $\rightarrow$  3.2.2).

General Format	Scaling Display Sign	al	
Sensor mode			
Mode:	Without unit		Scaling calculator
Sensor range			
Min:	0	Max: 991231	Unit:
Physical range			
Min:	0	Max: 991231	Unit:

#### • Sensor Mode

The sensor mode tells the type of signal. It can be of different types such as "Status", "Voltage", "Frequenzy" or others. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.

#### • Sensor Range

Shows the raw value range of the signal.

### • Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and** scaling".



# Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General Format	Scaling	Display	Signal			
Displaying area						
Min:	0			Max:	235959	
Formatting						
Decimal places:	Automatic	<b>T</b>				
Name						
Name:	GPS time					

#### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

### • Name

Allows you to set a Name to be shown on a display.

### Signal

This tab allows you to define signal settings.

Special function:	None
Signalnumber:	
Last value hold:	Until the next reboot
Namespace:	'GPS'
Origin:	GPS date

### • Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

### • Last value hold

Specify, for how long the last value of the signal will be hold.



#### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.

• Origin

Tells you what is the original signal.

### Signal check

This tab allows you to activate "Signal check" for this signal. You may choose whether you wish to apply the global signal check settings to this signal or override the global settings with settings specific for this signal.

Global signal check settings have to be defined first. For information on how to do so and for general information on "Signal check" please refer to ( $\rightarrow$ 4.2.2).

General Format Sca	aling Display Signal	Signal check	Limit values
Use signal check:	×		
Mode:	Global settings	-	
Start-trigger:			Select
Stop-trigger:			Select
Timeout:	30 s		



# 6.15 Video devices

In order to work with video signals, you will first need to add a video device to your system. There are three different video devices, that you can work with:

- Video Interface  $(\rightarrow 6.15.2)$
- USB camera ( $\rightarrow$ 6.15.3)
- Ethernet camera ( $\rightarrow 6.15.4$ )

### 6.15.1 Storage method

In order to store an incoming signal on a video device use "AVI" as storage method. Please refer to ( $\rightarrow$  12.11).

# 6.15.2 Video Interface

The "Video Interface" provides a set of four analog cameras, which are connected to your logger. It provides five signals, one for each camera and a combination of all four camera signals called "Quad camera". The "Quad camera" provides a single video signal which contains all four original signals at a quarter of their original resolution, and presents a 4 in 1 picture.

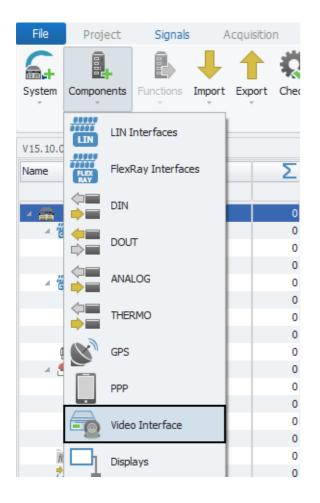
For communication between the cameras and the interface it needs to have its own subnet, in which only the "Video Interface" operates.



The "Video Interface" is a deprecated product and is not bein sold anymore.

# 6.15.2.1 Adding the Video Interface

The "Video Interface" can be added by selecting the system in the "Measurement task tree", then clicking the **"Components"** button and finally choosing "Video Interface"



### 6.15.2.2 Tree elements for the Video Interface

Adding the "Video Interface" to your system will add seven new elements to your "Measurement task tree":

#### • Video Interface xx

This item represents the entire "Video Interface" and all the included child elements.

#### • Cameras

This item is a child element of the "Video Interfaces" element and represents all the included cameras.

### • Camera xx

There are four elements named "Camera xx", they represent the four physical cameras connected to the logger.

### Quad Camera

The "Quad Camera" is a virtual camera, that combines the four signals of the four

Changes and errors excepted.



physical cameras in one single image. The image is divided into four quarters. Each quarter contains one of the physical cameras images.

🔺 🚘 🛛 Video Interface 01	5
🖌 🙆 Cameras	5
📀 Camera 01	1
🔞 Camera 02	1
📀 Camera 03	1
🔞 Camera 04	1
🔞 🛛 Quad Camera	1

#### 6.15.2.3 Grid area for the Video Interface

In the "grid area" you will be presented with an overview of the "Video Interface's" signals. There will be five signals. Signal five is the signal from the "Quad Camera". Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

V15.10.00.14201 Beta				Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
Name	Σ		٩								
		*	•	Video signal 01	~						1 Hz
openABK	0			Video signal 02	~						1 Hz
🛛 🤖 USB	1			Video signal 03	~						1 Hz
🔺 🙆 Camera	1			Video signal 04	~						1 Hz
🔊 USB Video	1			Video signal 05	~						1 Hz
🔺 🚍 Triggers	0										
Standard Triggers	0										
Level Triggers	0										
🚖 Cyclic Triggers S Trigger Groups	0										
	0										
🕅 Formulas	0										
Datasets	0										
Dataset	0										
A Data transfer	0										
t Transfer events	0										
Connections	0			Partial Digities Signal							
USB	0			Actives 14							
Logfile messages	0			Name: Table April 11							
🔺 👼 🛛 Video Interface 01	5										
🛛 🙆 Cameras	5			Description: Tobo age d							
🔞 Camera 01	1			Reference:							
🔞 Camera 02	1										
Camera 03	1										
Camera 04	1										
🔞 🛛 Quad Camera	1										



#### 6.15.2.4 Details area for the Video Interface

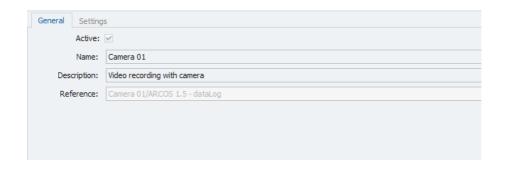
The Details area shows settings either for the tree element "Video Interface xx" or one of its child elements. In case the tree element "Cameras" is selected, the details area will only show the "General" tab. Please refer to  $(\rightarrow 4.2.2)$ .

The "Details area" for video signal will be handled in a separate chapter. Please refer to the Chapter "Video signals" ( $\rightarrow$ 6.16).

In case the "Video Interface" or one of the "Camera" elements is selected in the tree, the "Details area" will contain additional tabs, which will be explained in the following.

#### General

This tab allows you to activate or deactivate the entire tree element by ticking/unticking the checkbox, give a user specific name to tree element if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



### Settings (for Video Interface)

This tab allows you to define the settings for the entire "Video Interface".

Gener	al Settings	
	Channel number:	1
	Network address:	0.0.0.0
	Subnet mask:	255.255.255.0

#### • Channel number

Define the number of the "Video Interface" hardware channel.





For better orientation and in order to avoid confusion regarding Channelnumbers and -names, a Channels physical number can be found in the logger's **"Web Interface"** and set accordingly.

#### • Network address

Define the network adress of the subnet in which your "Video Interface" communicates.

### • Subnet mask

The subnet mask for your "Video Interface". It cannot be changed.

### Settings (for Camera elements)

This tab allows you to define the settings for the entire "Camera" child elements of your "Video Interface".

General Settings		
Channel:	1 *	
Time compensation:	50 ms	
Rotation:	0° •	
Resolution:	Full 🔻	
Mirror:		
Compression rate:	30	

### • Channel

The physical channel, on which the camera operates. It cannot be changed.

#### • Time compensation

Define the compensation of the video capture latency. This value is experience based and can vary.

### • Rotation

Allows you to rotate the video in steps of 90°.

#### • Resolution

Allows you to set the video's resolution to either full or one quarter.

### 6.15 VIDEO DEVICES





#### • Mirror

Checking the box will mirror the image of the video.

# • Compression rate

Allows you to define the compression rate of your video.

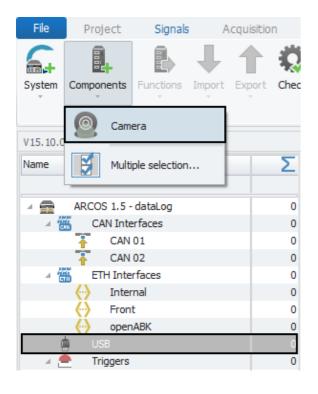


#### 6.15.3 USB camera

The "Camera" component for USB allows you to connect a digital video camera via USB to your logger and control it.

### 6.15.3.1 Adding a USB camera

The "Camera" component for USB can be added by selecting the tree element "USB" in the "Measurement task tree", then clicking the **"Components"** button and finally choosing "Camera"



#### 6.15.3.2 Tree elements for USB camera

Adding the "Camera" component for USB to your system will add two new elements to your "Measurement task tree":



### • Camera

This item represents the camera itself.

#### • USB Video

This item represents the video, that you will receive from the camera.



# 6.15.3.3 Grid area for USB camera

In the "grid area" you will see the video signal coming from your connected USB camera.

V15.10.00.14201 Beta			Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
Name	Σ	۴								
		۶.	Video signal 01	<b>Z</b>						1 Hz
ARCOS 1.5 - dataLog	1									
A CAN Interfaces	0									
T CAN 01	0									
🚹 CAN 02	0									
ETH Interfaces	0									
Internal	0									
💮 Front	0									
💮 openABK	0									
🔺 🚋 USB	1									
🛛 🙆 Camera	1									
🔞 USB Video	1									

#### 6.15.3.4 Details area for USB camera

The Details area shows settings either for the tree element "Camera" or its child element "USB Video". In case the tree element "Camera" is selected, the details area will only show the "General" tab. Please refer to  $(\rightarrow 4.2.2)$ .

The "Details area" for video signal will be handled in a separate chapter. Please refer to the Chapter "Video signals" ( $\rightarrow$ 6.16).

In case the "USB Video" is selected in the tree, the "Details area" will contain additional tabs, which will be explained in the following.

#### General

This tab allows you to activate or deactivate the entire tree element by ticking/unticking the checkbox, give a user specific name to tree element if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.





## Video

This tab allows you to define the settings for the incoming video.

General Video			
Time compensation:	50 ms		
Width:	640		
Height:	480		
Autofocus:	~		
Focus:	0		

#### • Time compensation

Define the compensation of the video capture latency. This value is experience based and can vary.

### • Width

Define the video capture resolution width in pixel.

• Height

Define the video capture resolution height in pixel.

#### • Autofocus

Allows you to enable or disable the the camera's autofocus.

#### • Focus

When "Autofocus" has been disabled, this field allow you to set the focus of the camera.

APPROXIMATE and CALIBRATED devices report the focus metadata in units of diopters (1/meter), so 0.0f represents focusing at infinity, and increasing positive numbers represent focusing closer and closer to the camera device. The focus distance control also uses diopters on these devices.

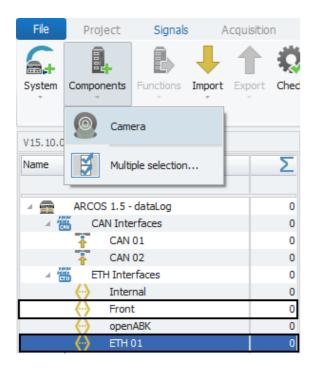


#### 6.15.4 Ethernet camera

The "Camera" component for Ethernet allows you to connect a digital video camera via Ethernet to your logger and control it.

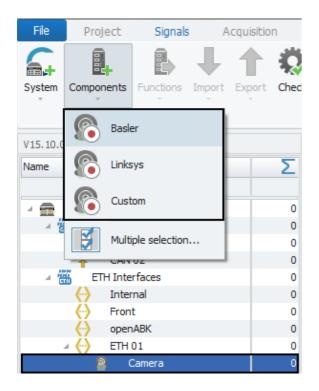
### 6.15.4.1 Adding an ETH camera

The "Camera" component for ETH can be added by selecting the tree element "Front", which is a childelement to the tree element "ETH Interfaces" in the "Measurement task tree" or by selecting any manually added "ETH" channel, then clicking the **"Components"** button and finally choosing "Camera".



In the next step you select the newly created tree element "Camera", then click the **"Components"** button and finally choose the desired camera model.

At the moment the Plugin support two third party cameras, "Basler" and "Linksys". If your camera is not listed, you can simply choose "Custom" and then set the necessary setting manually.







!	Once a new camera for Ethernet has been added, you may encounter problems regarding the cameras IP settings. In order to resolve this problem, DHCP has to be disabled for the tree element "Camera" and IP adresses have to be set for both, the tree element "Camera" and its child element, the cameratype you have previously choosen. The IP addresses must belong to the same subnet, and this subnet must not be used by any other operator of the system.
	To do so, select the tree element that contains your ETH camera navi- gate to the "LAN" tab in the details area, untick the checkbox "Get IP address automatically" and set a new IP address. The first three numbers of your IP address mark the subnet, so they cannot be equal to any other operators IP address, that is not a childe- lement to the currently selected tree element. The last number marks the client inside the subnet. It has to be higher equal or higher than "1" and unique inside its respective subnet.
	Then select your chosen cameratype in the tree (Basler, Linksys or Custom) and navigate to the "Connection" tab in the details area. Here you need to set an IP address that belongs to the same subnet as the one defined in the last step, but, again, with a unique client identifier.



#### 6.15.4.2 Tree elements for ETH camera

Adding the "Camera" component for ETH to your system will add two new elements to your "Measurement task tree".

#### • Camera

This item represents the camera interface.

#### • Basler/Linksys/Custom

This item represents the specific type of camera, that you have connected are configuring.

🔺 🎆 ETH Interfaces	1
💮 Internal	0
Front	0
openABK	0
4 💮 ETH 01	1
🛛 🙆 Camera	1
🏀 Basler	1

# 6.15.4.3 Grid area for ETH camera

In the "grid area" you will see the video signal coming from your connected ETH camera.

V15.10.00.14201 Beta	V15.10.00.14201 Beta		Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
Name	Σ	9								
	-	a.	Video signal 01	<b>~</b>						1 Hz
ARCOS 1.5 - dataLog	1									
CAN Interfaces	0									
	0									
CAN 02	0									
ETH Interfaces	1									
<ul> <li>Internal</li> </ul>	0									
Front	0									
openABK	0									
4 💮 ETH 01	1									
🔺 🙆 Camera	1									
🔞 Basler	1									

#### 6.15.4.4 Details area for ETH camera

The Details area shows settings either for the tree element "Camera" or its child element "Basler/Linksys/Custom". In case the tree element "Camera" is selected, the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).

The "Details area" for video signals will be handled in a separate chapter. Please refer to the Chapter "Video signals" ( $\rightarrow$ 6.16).

In case the childelement "Basler/Linksys/Custom" is selected in the tree, the "Details area" will contain additional tabs, which will be explained in the following.



#### General

This tab allows you to activate or deactivate the entire tree element by ticking/unticking the checkbox, give a user specific name to tree element if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

General Vi	deo Connection
Act	tive: 🗹
Na	me: Basler
Descript	ion: Video recording with Basler Ethernet camera
Referer	ce: Basler/ETH 01/ARCOS 1.5 - dataLog

### Video

This tab allows you to define the settings for the incoming video.

General Video Conne	ction
Time compensation:	50 ms
Width:	640
Height:	480

#### • Time compensation

Define the compensation of the video capture latency. This value is experience based and can vary.

• Width

Define the video capture resolution width in pixel.

### • Height

Define the video capture resolution height in pixel.



# Connection

This tab contains settings according the connection of the camera with the ETH interface.

General Video Conne	ection
IP address:	2.0.0.2
IP port:	80
URL:	

### • IP address

Define the IP address of your camera. It has to belong to the same unique subnet (The first three out of the four numbers define the subnet) as the ETH channel to which it belongs and it needs to have a unique client identifier (the last out of the four number defines the client identifier).

### • IP port

Define the IP port of the video stream.

### • URL

Set the URL on which your cameras stream is to be found. This information should be found in your camera's manual or on the manufacturer's website.

When working with one of the two already supported models (Basler or Linksys) this field will not be accessible, as the URL is already defined. When working with the Custom profile for other cameras you will need to fill in the URL of your camera stream, otherwise the logger will not now where to look for it and will not receive a video signal.



# 6.16 Video signals

The video signals, received from any of the three camera types is are equal in fuctionality. The setting for these signals can be set over the "Details area" for each respective signal and will be explained in the following.

### 6.16.1 Storage method

In order to store a video signal use "AVI" as storage method. Please refer to ( $\rightarrow$  12.11).

### 6.16.2 Settings for video signals

#### General

This tab allows you to activate or deactivate the entire signal by ticking/unticking the checkbox, give a user specific name to your signal if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

General Format	t Display Signal								
Active:	Active: 🗹								
Name:	Video signal 01								
Description:	Video signal								
Reference:	Video signal 01///Basler/ARCOS 1.5 - dataLog								



In the field "Name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .

### Format

Settings in the "Format"-tab do not have any effect on video signals and will therefore not be explained here.





### Display

The only setting in the "Display"-tab relevant for video signals is the "Name" setting. It allows you to set a Name to be shown on a display.

General Format	Display Signal	
Displaying area		
Min:		Max:
Formatting		
Decimal places:	Automatic 👻	
Name		
Name:	Video signal 01	

# Signal

This tab allows you to define signal settings.

General Format Displa	ay Signal
Signalnumber:	
Namespace:	'VIDEO'

#### • Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

#### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.



### Signal check

This tab allows you to activate "Signal check" for this signal. You may choose whether you wish to apply the global signal check settings to this signal or override the global settings with settings specific for this signal.

Global signal check settings have to be defined first. For information on how to do so and for general information on "Signal check" please refer to ( $\rightarrow$ 4.2.2).

General	Format	Scaling	Display	Signal	Signal check	Limit values
	Use signal ch	neck: 🗹				
	м	ode: Glo	oal settings		-	
	Start-trig	ger:				Select
	Stop-trig	ger:				Select
	Time	out: 30	S			



# 6.17 Audio recording

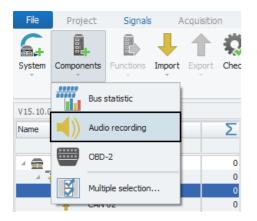
For audio recordings you can connect a microphone to the logger via CAN. The logger will receive the audio signals on one of the CAN channels.

## 6.17.1 Storage method

In order to store an audio recording use "WAV" as storage method. Please refer to ( $\rightarrow$  12.12).

### 6.17.2 Adding an Audio recording

To add an "Audio recording" select the CAN channel to which you wish to add the recording, click the "Components" button in the Ribbon and then choose "Audio recording".



Once the "Audio recording" component has been added, select the newly created tree element "Audio recording" in the respective CAN channel, click the "Components" button in the Ribbon and then choose one of the two available microphones.





#### 6.17.3 Tree elements for Audio recordings

Adding an "Audio recording" to your system will add five new elements to your "Measurement task tree":

### Audio recording

This item represents the entire "Audio recording" and all the included child elements.

### • G.I.N. CASM2T3L / G.I.N. VoCAN

This item represents the microphone which you have connected to the logger. At the moment these are the only supported microphone models.

• Signals

This element contains the incoming audio signal.

#### • LEDs

This element represents the microphone's LEDs. By selecting this item you will be able to give user specific names to the single LEDs in the details area.

#### • Buttons

This element represents the microphone's Buttons. By selecting this item you will be able to give user specific names to the single Buttons in the details area.

Name	- 2
ARCOS 1.5 - dataLog	1
A T CAN interfaces	1
A T CAN 01	1
🔺 ┥ 🔪 Audio recording	1
🛛 🐌 G.i.N. CASM2T3L	1
	1
2 LEDs	0
Buttons	0

### 6.17.3.1 Grid area for Audio recordings

In the "grid area" you will see the incoming audio signal. Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).





V15.10.00.15230 Beta			Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
Name		٩								
	*	•	Audio signal 01	~		-32768	32767	-32768	32767	1 Hz
ARCOS 1.5 - dataLog	1									
A T CAN interfaces 1										
4 👬 CAN 01 1										
🛛 📢 🔪 Audio recording 🛛 1										
🛛 👸 G.i.N. CASM2T3L 1										
√ Signals 1										
EDs 0										
- Buttons	0									

### 6.17.4 Details area for Audio recording

When selecting the audio signal in the grid area, you will be able to access the signal's settings in the details area.

#### General

This tab allows you to activate or deactivate the entire signal by ticking/unticking the checkbox, give a user specific name to your signal if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

The sampling rate allows you to set the frequency in which the logger will receive the signal.

General Format	Scaling Display Signal					
Active:	V					
Name:	Audio signal 01					
Description:	Audio signal					
Reference:	Audio signal 01///Signals/ARCOS 1.5 - dataLog					
Sampling rate:	1 Hz					



In the field "Name" project parameters can be used as variables. For more information please refer to ( $\rightarrow$ 5.6).



# Format

This tab contains information and options regarding file format, tasks and Channel type.

0	General Form	nat Scaling	Display	Signal			
	Data type						
	ту	<b>/pe:</b> 16-Bit integ	ger signed	Ŧ	Task:	Audio mono	•
	NoValue / DefaultValue						
	Va	lue: -FullScale		Ŧ	Deactivate	NoValue and use Default Value	
	Channel type						
	Inj	put: 🗹		Output:			

# • Data type

This field tells you the type of data (in this case **`16-Bit integer unsigned**") and allows you to special tasks for this signal such as "Audio mono".

# • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

# Scaling

The settings in the "Scaling"-tab are not relevant for working with audio recordings.

# Display

The only setting in the "Display"-tab relevant for audio recordings is the "Name" setting. It allows you to set a name to be shown on a display.

General Format	Scaling Display Signal
Displaying area	
Min:	-32768 Max: 32767
Formatting	
Decimal places:	Automatic 👻
Name	
Name:	Audio signal 01

• Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

• Formatting

Changes and errors excepted.



The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

### • Name

Allows you to set a Name to be shown on a display.

# Signal

This tab allows you to define signal settings.

General Format Scaling Display Signal	
Namespace: 'AUDIO'	

### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.



# 6.18 DIN (Digital input signals)

The "DIN" module offers a digital bit-channel, which is directly configured as a digital signal and then acquired. This means they can be used in the logger configuration in the same way as conventional bus signals.

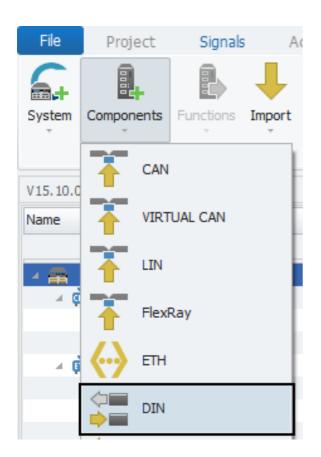
# 6.18.1 Storage method

In order to store incoming signals on a DIN channel use one of the following signal storage methods.

- ATFX ( $\rightarrow$  12.6)
- MDF 4.0 ( $\rightarrow$  12.7)
- MDF 4.1 ( $\rightarrow$  12.8)

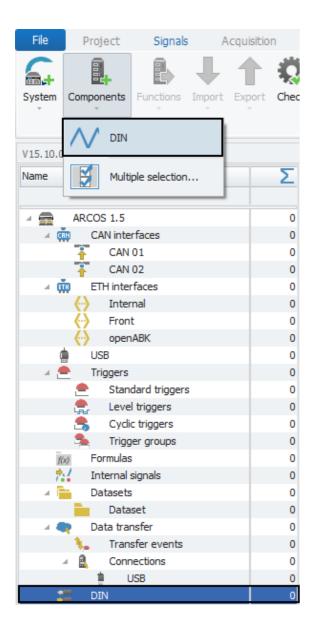
# 6.18.2 Adding the DIN-Interface

In order to work with digital input signals, you will first need to add the "DIN" interface to your system. To do so, select the system in the tree, click the "Components" button in the Ribbon and then choose "DIN".





Once the "DIN" interface has been added to your system, you can then add multiple "DIN" channels, in order to acquire digital signals. To do so, select the "DIN" interface in the tree, click the "Components" button in the Ribbon and then choose "DIN".



In order to acquire digital signals via "DIN" channels, each "DIN" channel needs to be matched with the corresponding digital hardware channels of the logger. To find out the digital hardware channel numbers please consult your loggers webinterface.

Once you know the hardware channel number, navigate to the "Signals" tab in "Details area" of the corresponding "DIN" channel in the grid area and enter the number.

### 6.18.3 Signal properties





Image: Constraint of the sector of		Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max
General       Format       Scaling       Display       Signal         Signal number:	٩							
Signal number:         Hold last value:         Until the next reboot         Timeout:         0 s         Hardware channel:	•	DIN 01	×		0	1	0	1
Signal number:         Hold last value:         Until the next reboot         Timeout:         0 s         Hardware channel:								
Signal number: Hold last value: Until the next reboot Timeout: 0 s Hardware channel: 1								
Signal number: Hold last value: Until the next reboot Timeout: 0 s Hardware channel: 1								
Signal number: Hold last value: Until the next reboot Timeout: 0 s Hardware channel: 1								
Signal number:         Hold last value:         Until the next reboot         Timeout:         0 s         Hardware channel:								
Signal number: Hold last value: Until the next reboot Timeout: 0 s Hardware channel: 1								
Signal number:         Hold last value:         Until the next reboot         Timeout:         0 s         Hardware channel:								
Signal number:         Hold last value:         Until the next reboot         Timeout:         0 s         Hardware channel:								
Signal number:         Hold last value:         Until the next reboot         Timeout:         0 s         Hardware channel:								
Signal number:         Hold last value:         Until the next reboot         Timeout:         0 s         Hardware channel:								
Signal number:         Hold last value:         Until the next reboot         Timeout:         0 s         Hardware channel:								
Signal number:         Hold last value:         Until the next reboot         Timeout:         0 s         Hardware channel:								
Signal number:         Hold last value:         Until the next reboot         Timeout:         0 s         Hardware channel:								
Hold last value: Until the next reboot  Timeout: 0 s Hardware channel: 1	Ger	neral Format Scali	ng Display	Signal				
Timeout: 0 s Hardware channel: 1		Signal number:						
Hardware channel: 1		Hold last value:	Until the next r	eboot	•			
Namespace: 'DIN'		Timeout:	0 s					
						]		

#### 6.18.3.1 Tree elements for DIN signals

After having added the "DIN" interface to your system it will appear as a tree element with the name "DIN".

🔺 🜉 🛛 Data transfer	0
🐛 🛛 Transfer events	0
Zentral Connections	0
USB USB	0
📁 DIN	1

### 6.18.3.2 Grid area for DIN signals

In the "grid area" you will be presented with an overview of the DIN channels which have been added to your system so far. Each DIN channel can only receive one signal and therefore each DIN channel is treated as a signal.

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

### 6.18.3.3 Details area for DIN signals

The Details area shows settings either for the selected tree element "DIN" or the selected "DIN" channel in the grid area. In case the tree element is selected, the details area will



only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).

In case a "DIN" channel is selected in the grid area, the details area will contain additional tabs which will be explained in the following.

#### General

Please refer to ( $\rightarrow$ 4.2.2).

#### Format

This tab contains information and options regarding file format, tasks and Channel type.

General Format	Scaling Display Sig	gnal	
Data type			
Type:	1-Bit	Task: Default	•
NoValue / DefaultVal	ue		
Value:	-FullScale	<ul> <li>Deactivate NoValue and use Default Value</li> </ul>	
Channel type			
Input:	<i>~</i>	Output:	

#### • Data type

This field tells you the type of data (in this case **``1-Bit**") and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

#### • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

#### • Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.

#### Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

#### • Sensor Mode

The sensor mode tells the type of signal. It can be of different types such as "Status",



General	Format Scaling Displa	y Signal		
Sensor ma	de			
	Mode: Status		<b>•</b>	Scaling calculator
Sensor rar	nge			
	Min: 0	Max: 1		Unit:
Physical ra	ange			
	Min: 0	Max: 1		Unit:

"Voltage", "Frequenzy" or others. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.

### • Sensor Range

Shows the raw value range of the signal.

#### • Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5** "Channel configuration and scaling".



### Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General Format	Scaling Display Sign	nal
Displaying area		
Min:	0	Max: 1
Formatting		
Decimal places:	Automatic 👻	
Name		
Name:	DIN 01	

#### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

#### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

### • Name

Allows you to set a Name to be shown on a display.

### Signal

This tab allows you to define signal settings.

Timeout: 0 s Hardware channel: 1		Ŧ	Until the next reboot	Signal number: Hold last value:
Hardware channel: 1			0 s	Timeout:
			1	Hardware channel:
Namespace: 'DIN'			'DIN'	Namespace:

#### • Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

#### • Hold last value

Specify, for how long the last value of the signal will be hold.



#### • Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.

#### • Hardware channel

Assign the corresponding digital hardware channel number from which you would like to acquire data. The hardware channel number can be found out via the log-ger's webinterface.

### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.

#### Signal check

This tab allows you to activate "Signal check" for this signal. You may choose whether you wish to apply the global signal check settings to this signal or override the global settings with settings specific for this signal.

Global signal check settings have to be defined first. For information on how to do so and for general information on "Signal check" please refer to  $(\rightarrow 4.2.2)$ .

General For	nat Scaling	Display	Signal	Signal check	Limit values	
Use si	gnal check: 🗹	]				
	Mode: G	lobal settings		*		
St	art-trigger:				Select	
St	op-trigger:				Select	
	Timeout: 3	0 s				



# 6.19 DOUT (Digital output signals)

The "DOUT" module offers a digital bit-channel on which a calculated digital signal can be put out.

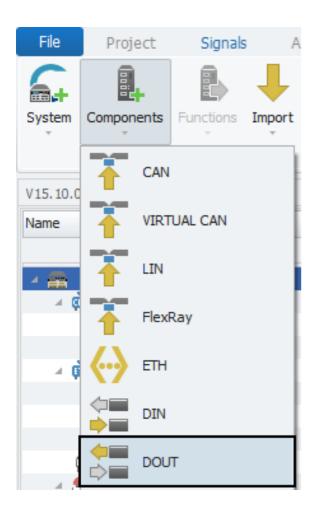
## 6.19.1 Storage method

In order to store outgoing signals on a DOUT channel use one of the following signal storage methods.

- ATFX ( $\rightarrow$  12.6)
- MDF 4.0 ( $\rightarrow$  12.7)
- MDF 4.1 ( $\rightarrow$  12.8)

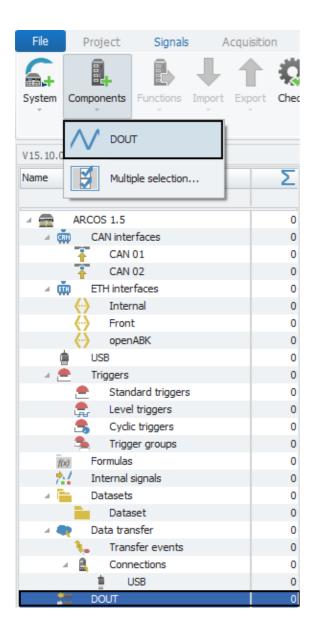
# 6.19.2 Adding the DOUT-Interface

In order to work with digital output signals, you will first need to add the "DOUT" interface to your system. To do so, select the system in the tree, click the "Components" button in the Ribbon and then choose "DOUT".





Once the "DOUT" interface has been added to your system, you can then add multiple "DOUT" channels, in order to put out digital signals. To do so, select the "DOUT" interface in the tree, click the "Components" button in the Ribbon and then choose "DOUT".



In order to put out digital signals via "DOUT" channels, each "DOUT" channel needs to be matched with the corresponding digital hardware channels of the logger. To find out the digital hardware hannel numbers please consult your loggers webinterface.

Once you know the hardware channel number, navigate to the "Signals" tab in "Details area" of the corresponding "DOUT" channel in the grid area and enter the number.

### 6.19.3 Signal properties





	Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max
٩							
Þ	DOUT 01	>		0	1	0	1
Ger	neral Format Scal	ing Display	Calculatio	n Signal			
Ger	neral Format Scal Signal number:		Calculatio	n Signal			
Ger				n Signal			
Ger	Signal number:	Until the next		n Signal			

### 6.19.3.1 Tree elements for DOUT signals

After having added the "DOUT" interface to your system it will appear as a tree element wit the name "DOUT".

🔺 🛶 🛛 Data transfer	0
🐛 Transfer events	0
Connections	0
USB USB	0
5 DOUT	1

### 6.19.3.2 Grid area for DOUT signals

In the "grid area" you will be presented with an overview of the DOUT channels which have been added to your system so far. Each DOUT channel can only receive one signal and therefore each DOUT channel is treated as a signal.

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

### 6.19.3.3 Details area for DOUT signals

The Details area shows settings either for the selected tree element "DOUT" or the selected "DOUT" channel in the grid area. In case the tree element is selected, the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).



In case a "DOUT" channel is selected in the grid area, the details area will contain additional tabs which will be explained in the following.

### General

Please refer to ( $\rightarrow$ 4.2.2).

# Format

This tab contains information and options regarding file format, tasks and Channel type.

General <b>Format</b> Scaling Display Si	gnal
Data type	
Type: 1-Bit	▼ Task: Default ▼
NoValue / DefaultValue	
Value: -FullScale	<ul> <li>Deactivate NoValue and use Default Value</li> </ul>
Channel type	
Input: 🛩	Output:

### • Data type

This field tells you the type of data (in this case **``1-Bit**") and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

### • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

### • Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.

### Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

### • Sensor Mode

The sensor mode tells the type of signal. It can be of different types such as "Status", "Voltage", "Frequenzy" or others. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.



General Format Sca	ing Display Signal			
Sensor mode				
Mode: Statu	S		-	Scaling calculator
Sensor range				
Min: 0		Max: 1		Unit:
Physical range				
Min: 0		Max: 1		Unit:

#### • Sensor Range

Shows the raw value range of the signal.

#### • Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and** scaling".

### Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General Format	Scaling Display Calculation Signal
Displaying area	
Min:	0 Max: 1
Formatting	
Decimal places:	Automatic 👻
Name	
Name:	DOUT 01

#### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

#### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

#### • Name

Allows you to set a Name to be shown on a display.



# Calculation

In this tab you set the formula to calculate the "DOUT" signal. This functionality has been explained in depth in the "Formulas" section. Please refer to  $(\rightarrow 6.23.4)$ .

# Signal

This tab allows you to define signal settings.

General Format Scal	ing Display Calculation Signal
Signal number:	
Hold last value:	Until the next reboot *
Hardware channel:	1
Namespace:	DOUT

### • Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

• Hold last value

Specify, for how long the last value of the signal will be hold.

#### • Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.

#### • Hardware channel

Assign the corresponding digital hardware channel number from which you would like to put out data. The hardware channel number can be found out via the log-ger's webinterface.

#### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.



# 6.20 Analog signals

Your logger is equipped with a number of analog input channels and the "Analog" interface of the plugin allows for direct acquisition of analog signals coming in on these channels. There are three types of analog signals that can be acquired via the "Analog" interface:

- Voltage (→6.20.3.3) Allows you to directly import a raw voltage and, with the help of the "Scaling calculator", to transform it into a signal type of your desire.
- Counter/frequenzy ( $\rightarrow$ 6.20.3.4) Allows you to define a voltage-threshold for the incoming signal and thus transform the raw voltage into a counter or frequenzy.
- Duty cycle ( $\rightarrow$ 6.20.3.5) Allows you to acquire the hightime or the lowtime in percent of a signal.

# 6.20.1 Storage method

In order to store incoming signals on an analog channel use one of the following signal storage methods.

- ATFX ( $\rightarrow$  12.6)
- MDF 4.0 ( $\rightarrow$  12.7)
- MDF 4.1 ( $\rightarrow$  12.8)



# 6.20.2 Adding the Analog Interface

In order to work with incoming analog signals, you will first need to add the "Analog" interface to your system. To do so, select the system in the tree, click the "Components" button in the Ribbon and then choose "Analog".

File	Project	Signals	A
6.			↓
System 	Components	Functions	Import T
V15.10.0		4	
Name		TUAL CAN	-
∡ 🚔			
_	Flex	Ray	
× ¢	ETH	I	
ę		л	
		ALOG	

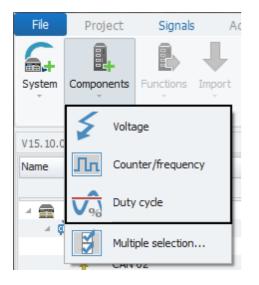


Once the "Analog" interface has been added to your system, you can then add multiple "Analog" channels of three different types (each type will acquire a differeent type of signal).

To do so, select the "Analog" interface in the tree, click the "Components" button in the Ribbon and then choose one of the three types "Voltage" ( $\rightarrow$ 6.20.3.3),

"Counter/frequenzy" ( $\rightarrow$ 6.20.3.4) or "Duty cycle" ( $\rightarrow$ 6.20.3.5).

For specifics on the configuration for each of these signal types please click on the respective links in the preceding paragraph.







In order to acquire signals on analog channels, each analog channel needs to be matched with the corresponding analog hardware channels of the logger. To find out the analog hardware channel numbers please consult your loggers webinterface.

Once you know the hardware channel number, navigate to the "Signals" tab in "Details area" of the corresponding analog channel in the grid area and enter the number.

Na	ame	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max
9							
Ø. AN	NALOG 01	<b>Z</b>	V	-60,000	60,000	-60	60
Gener	ral Format Scal	ing Display	Excitation	Signal			
	Signal number:						
	Hold last value:	Until the next r	reboot	<b>*</b>			
	Timeout:	0 s					
					1		
	Hardware channel:	1					



### 6.20.3 Signal properties

### 6.20.3.1 Tree elements for Analog signals

After having added the "Analog" interface to your system it will appear as a tree element wit the name "Analog".



### 6.20.3.2 Grid area for Analog signals

In the "grid area" you will be presented with an overview of the Analog channels which have been added to your system so far. Each Analog channel can only receive one signal and therefore each Analog channel is treated as a signal.

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

	Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
٩								
•	ANALOG 01	✓	V	-60,000	60,000	-60	60	1 Hz
	·							

### 6.20.3.3 Details area for Analog signals (Voltage)

The Details area shows settings either for the selected tree element "Analog" or the selected "Voltage" channel in the grid area. In case the tree element is selected, the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).

In case a "Voltage" channel is selected in the grid area, the details area will contain additional tabs which will be explained in the following.

#### General

Please refer to ( $\rightarrow$ 4.2.2).



# Format

This tab contains information and options regarding file format, tasks and Channel type.

General	Format	Scaling	Display	Excitation	Signal	
Data type						
	Type:	16-Bit integ	ger signed		▼ Task: Default ▼	
NoValue /	DefaultVa	lue				
	Value:	Null			▼ Deactivate NoValue and use Default Value	
Channel t	ype					
	Input:	~		Output	:	

### • Data type

This field tells you the type of data (in this case **"16-Bit integer signed"**) and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

# • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

### • Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.

### Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

General Forma	Scaling Display	Excitation Signal		
Sensor mode				
Mode	: Voltage		~	Scaling calculator
Sensor range				
Min	-60 🔻	Max: 60	*	Unit: V 👻
Physical range				
Min	: -60,000	Max: 60,000		Unit: V



#### • Sensor Mode

The sensor mode tells the type of signal. It can be of different types such as "Status", "Voltage", "Frequenzy" or others. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.

#### • Sensor Range

Shows the raw value range of the signal.

### • Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5** "Channel configuration and scaling".

### Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General Format	Scaling Display E	excitation Signal	
Displaying area			
Min:	-60,000	Max: 60,000	
Formatting			
Decimal places:	Automatic 👻		
Name			
Name:	ANALOG 01		

#### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

#### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

#### • Name

Allows you to set a Name to be shown on a display.



## Excitation

This tab allows you to provide the analog sensor with excitation if necessary and also to set the voltage of the excitation.

General	Format	Scaling	Display	Excitation	Signal
S	ensor excita	ation:	5 V		

# Signal

This tab allows you to define signal settings.

Signal number: Hold last value: Until the next reboot Timeout: 0 s
Timeout: 0 s
Hardware channel: 1
Namespace: ANALOG'

### • Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

### • Hold last value

Specify, for how long the last value of the signal will be hold.

• Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.

#### • Hardware channel

Assign the corresponding digital hardware channel number from which you would like to put out data. The hardware channel number can be found out via the logger's webinterface.



#### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.

### 6.20.3.4 Details area for Analog signals (Counter/frequenzy)

The Details area shows settings either for the selected tree element "Analog" or the selected "Counter/frequenzy" channel in the grid area. In case the tree element is selected, the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).

In case a "Counter/frequenzy" channel is selected in the grid area, the details area will contain additional tabs which will be explained in the following.

#### General

Please refer to ( $\rightarrow$ 4.2.2).

### Format

This tab contains information and options regarding file format, tasks and Channel type.



#### • Data type

This field tells you the type of data (in this case **"32-Bit integer unsigned"**) and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

#### • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

#### • Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.



### Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

General	Format	Scaling	Display	Input signal	Excitation	Signal	
Sensor m	ode						
	Mode:	Event cour	iter			-	Scaling calculator
Sensor ra	inge						
	Min:	0		Ν	<b>1ax:</b> 429496	7295	Unit:
Physical r	ange						
	Min:	0		N	1ax: 429496	7295	Unit:

### • Sensor Mode

The sensor mode lets you further specify, in which way the signal should be used. There are three options:

Frequenzy Determines the frequency of an analog input.

**Event counter** Determines the occurrence of an event for an analog input. **Event counter with direction** Determines the occurrence of an event for an analog input, including a directional input to count either up or down. This mode requires two analog channels, the prefix of the second channel determines the direction of the event counter.

### • Sensor Range

Shows the raw value range of the signal.

### • Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5** "Channel configuration and scaling".



## Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General     Format     Scaling     Display     Excitation     Signal       Displaying area     Min:     -60,000     Max:     60,000       Formatting       Decimal places:     Automatic     ▼
Min:     -60,000     Max:     60,000       Formatting       Decimal places:     Automatic         Name
Formatting Decimal places: Automatic   Name
Decimal places: Automatic  Name
Name
Name: ANALOG 01

#### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

### • Name

Allows you to set a Name to be shown on a display.

### Input signal

This tab provides settings regarding the Input signal. These settings are crucial for a correct functionality of the Counter/frequenzy mode.

ignal parameters		Prescaler
Threshold on:	3 V	Prescaler: 1
Threshold off:	1 V	
Edge:	Positive edge	
Noise cancelation:	0 s	

• Threshold on

Define the value to detect the input signal as active.

### • Threshold off

Define the value to detect the input signal as inactive.





• Edge

Define the directin for detecting the edges.

• Noise cancellation

Define the noise cancellation delay time.

• Prescaler

Define the prescaler between 1 to 16.

### Excitation

This tab allows you to provide the analog sensor with excitation if necessary and also to set the voltage of the excitation.

General Format Scaling	Display Excitation Signal
Sensor excitation:	5 V

### Signal

This tab allows you to define signal settings.

General Format Scali	ng Display Excitation Signal	
Signal number:		
Hold last value:	Until the next reboot 🔹	
Timeout:	0 s	
Hardware channel:	1	
Namespace:	'ANALOG'	

• Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

• Hold last value

Specify, for how long the last value of the signal will be hold.



#### • Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.

#### • Hardware channel

Assign the corresponding digital hardware channel number from which you would like to put out data. The hardware channel number can be found out via the log-ger's webinterface.

### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.

### 6.20.3.5 Details area for Analog signals (Duty cycle)

The Details area shows settings either for the selected tree element "Analog" or the selected "Duty cycle" channel in the grid area. In case the tree element is selected, the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).

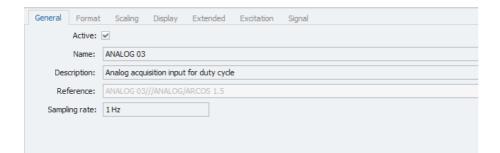
In case a "Duty cycle" channel is selected in the grid area, the details area will contain additional tabs which will be explained in the following.

#### General

Please refer to ( $\rightarrow$ 4.2.2).

### Format

This tab contains information and options regarding file format, tasks and Channel type.



Data type

This field tells you the type of data (in this case **``16-Bit integer unsigned**") and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.



### • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

## • Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.

### Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

General	Format	Scaling	Display	Extended	Excitation	Signal		
Sensor m	ode							
	Mode:	Duty cycle				Ŧ	Scaling cale	culator
Sensor ra	ange							
	Min:	0			Max: 100		Unit: %	
Physical r	ange							
	Min:	0,0			Max: 100,0		Unit: %	

#### • Sensor Mode

The sensor mode tells the type of signal. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.

### • Sensor Range

Shows the raw value range of the signal.

### • Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5** "Channel configuration and scaling".



### Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General Format	Scaling Display	Extended Exc	titation	Signal
Displaying area				
Min:	0,0	Max:	100,0	
Formatting				
Decimal places:	Automatic 🔹			
Name				
Name:	ANALOG 03			

#### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

### • Name

Allows you to set a Name to be shown on a display.

### Extended

This tab provides extended settings regarding the duty cycle mode.

General	Format	Scaling	Display	Extended	Excitation	Signal
Duty cycle mode: High time in percent 🔹						
N	oise cancela	ition: 0 s				

### • Duty cycle mode

Define whether the high time or the low time will be put out in percent.

### Noise cancellation

Define the noise cancellation delay time.



### Excitation

This tab allows you to provide the analog sensor with excitation if necessary and also to set the voltage of the excitation.

General	Format	Scaling	Display	Excitation	Signal	
	Sensor excita	ation:	5 V			

### Signal

This tab allows you to define signal settings.

### • Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

### • Hold last value

Specify, for how long the last value of the signal will be hold.

• Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.

#### • Hardware channel

Assign the corresponding digital hardware channel number from which you would like to put out data. The hardware channel number can be found out via the logger's webinterface.



# • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.



# 6.21 Thermo

The "Thermo" module offers an analog channel, through which a "Thermo" signal can be acquired.

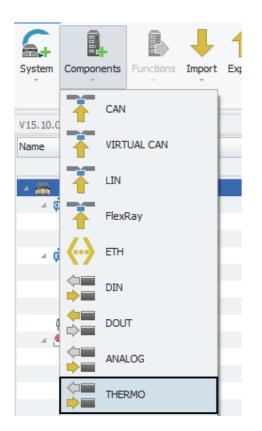
# 6.21.1 Storage method

In order to store incoming signals on a Thermo channel use one of the following signal storage methods.

- ATFX (→ 12.6)
- MDF 4.0 ( $\rightarrow$  12.7)
- MDF 4.1 ( $\rightarrow$  12.8)

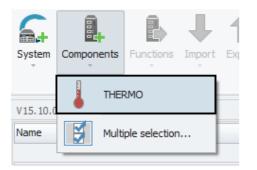
# 6.21.2 Adding the Thermo-Interface

In order to work with "Thermo" signals, you will first need to add the "Thermo" interface to your system. To do so, select the system in the tree, click the "Components" button in the Ribbon and then choose "Thermo".





Once the "Thermo" interface has been added to your system, you can then add multiple "Thermo" channels, in order to acquire digital signals. To do so, select the "Thermo" interface in the tree, click the "Components" button in the Ribbon and then choose "Thermo".





In order to acquire "Thermo" signals via "Thermo" channels, each "Thermo" channel needs to be matched with the corresponding hardware channels of the logger. To find out the hardware channel numbers please consult your loggers webinterface. Once you know the hardware channel number, navigate to the "Signals" tab in "Details area" of the corresponding "Thermo" channel in the grid area and enter the number.

	me	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
9								
THE	ERMO 01	~	°C	-50,00	1200,00	-50	1200	1 Hz
Genera	al Format Scalii	ng Terminal	Display	Signal				
Genera		ng Terminal	Display	Signal				
Genera	Signal number:							
Genera	Signal number: Hold last value:	Until the next		Signal				
Genera	Signal number:	Until the next			]			
Genera	Signal number: Hold last value:	Until the next			] ] ]			



### 6.21.3 Signal properties

### 6.21.3.1 Tree elements for Thermo signals

After having added the "Thermo" interface to your system it will appear as a tree element wit the name "Thermo".



### 6.21.3.2 Grid area for Thermo signals

In the "grid area" you will be presented with an overview of the Thermo channels which have been added to your system so far. Each Thermo channel can only receive one signal and therefore each Thermo channel is treated as a signal.

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

### 6.21.3.3 Details area for Thermo signals

The Details area shows settings either for the selected tree element "Thermo" or the selected "Thermo" channel in the grid area. In case the tree element is selected, the details area will only show the "General" tab. Please refer to  $(\rightarrow 4.2.2)$ .

In case a "Thermo" channel is selected in the grid area, the details area will contain additional tabs which will be explained in the following.

#### General

Please refer to ( $\rightarrow$ 4.2.2).



# Format

This tab contains information and options regarding file format, tasks and Channel type.

General	Format Scaling Ter	minal Display Signal		
Data type	:			
	Type: 16-Bit integer ur	signed 🔻	Task: Default	Ŧ
NoValue /	DefaultValue			
	Value: -FullScale	▼	Deactivate NoValue and use Default Valu	Je
Channel t	ype			
	Input: 🗸	Output:		

### • Data type

This field tells you the type of data (in this case **``16-Bit integer unsigned**") and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

### • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

### • Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.

### Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

General Format	Scaling Terminal Display	Signal		
Sensor mode				
Mode:	Thermo element of type K			Scaling calculator
Sensor range				
Min:	-50	Max: 1200	l	Jnit: C
Physical range				
Min:	-50,00	Max: 1200,00	i	Jnit: C



#### • Sensor Mode

The sensor mode tells the type of signal. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.

### • Sensor Range

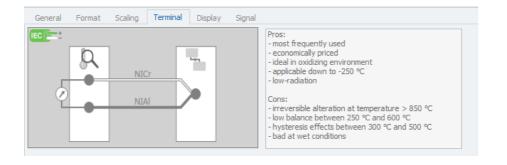
Shows the raw value range of the signal.

### • Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5** "Channel configuration and scaling".

### Terminal

Additional information regarding the kind of thermoelement, that is being used.





# Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

#### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

### • Name

Allows you to set a Name to be shown on a display.

### Signal

This tab allows you to define signal settings.

#### • Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

#### • Hold last value

Specify, for how long the last value of the signal will be hold.



#### • Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.

#### • Hardware channel

Assign the corresponding digital hardware channel number from which you would like to acquire data. The hardware channel number can be found out via the log-ger's webinterface.

#### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.



## 6.22 Internal signals

Internal signals are values that are not fed into the logger from the outside (CAN, GPS...), but are generated within the logger and provide information about internal system states.

Internal signals are largely treated in the same manner as a CAN signal. They can be recorded over time, classed or processed; they can generate alarms or be displayed. Only they can't be directly stored in traces, since the values, with the exception of the bus statistics, are not, as required, in the form of bus messages.

The internal signals are divided into three groups and the details on each group can be found in the respective section:

- Run state ( $\rightarrow$ 6.22.4)
- System info ( $\rightarrow$ 6.22.5)
- Time ( $\rightarrow$ 6.22.6)

#### 6.22.1 Storage method

In order to store internal signals use one of the following signal storage methods.

- ATFX ( $\rightarrow$  12.6)
- MDF 4.0 (→ 12.7)
- MDF 4.1 ( $\rightarrow$  12.8)

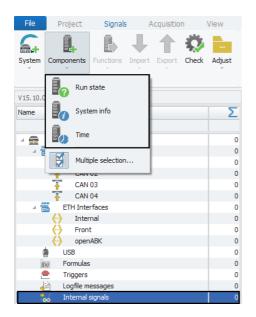


#### 6.22.2 Accessing internal signals

"Internal signals" do not need to be imported, as they are continuosly produced by the logger itself. They only need to be made accessible and can then be activated for to be used liked regular signals in further processing, for example as triggers or in formulas.

To access "Internal signals" select the tree element "Internal signals", click the "Components" button in the Ribbon and then choose, which of the three categories of internal signals you wish to access.

If you wish to acces two or all three categories, you can either access them one by one or through the button **"Multiple selection..."**.





#### 6.22.3 Internal signals properties

#### 6.22.3.1 Tree elements for Internal signals

Each category of "Internal signals" that has been accessed, will appear in the tree as a child element to the tree element "Internal signals" with its respective name. In the right part of the tree it will also show, how many signals have been activated for further processing.

Name	 Σ
🔺 📻 ARCOS 1.5 - dataLog	0
🔺 🚟 CAN Interfaces	0
	0
T CAN 02	0
🚹 CAN 03	0
🚹 CAN 04	0
🔺 🗬 🛛 Data transfer	0
A A Connections	0
📋 USB	0
🐛 Transfer events	0
🔺 🚞 🛛 Datasets	0
Dataset	0
ETH Interfaces	0
Front	0
Internal	0
openABK	0
f(x) Formulas	0
🔺 🐱 Internal signals	0
🗛 Run state	0
Bo System info	0
🗓 Time	0

#### 6.22.3.2 Grid area for Internal signals

In the "Grid area" you will be presented with an overview of the available "Internal signals". Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

#### 6.22.3.3 Details area for Internal signals

The Details area shows settings either for the selected tree element ("Internal signals", "Run state", "System info" or "Time") or the selected signal in the grid area. In case a tree element is selected, the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).

In case a signal is selected in the grid area, the details area will contain additional tabs which will be explained in the following.



#### General

This tab allows you to activate or deactivate the signal by ticking/unticking the checkbox and thus to make it available for internal Recording and further use (e.g. triggers, formulas, display,...)

It also allows you to give a user specific name to your signal if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed. The "Sampling rate" allows you to set, how frequently a signal should be requested.

General Format	Scaling Display Signal
Name:	Main runstate
Description:	Signal showing logger's run state
Reference:	Main runstate////ARCOS 1.5 - dataLog
Sampling rate:	1 Hz

### Format

This tab contains information and options regarding file format, tasks and Channel type.

General Format	Scaling Display Sig	inal	
Data type			
Type:	64-Bit floating point	Task: Default	-
NoValue / DefaultVal	ue		
Value:	NaN	<ul> <li>Deactivate NoValue and use Default Value</li> </ul>	
Channel type			
Input:	×	Output:	

• Data type

This field tells you the type of data (in this case **"64-Bit floating point"**) and allows you to apply special tasks for this signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

#### • NoValue / DefaultValue

This field allows you to define the value that will be shown if a signal value is read as invalid.

#### • Channel type

This field tells you whether you are dealing with a **"Input"** channel or **"Output"** channel.



#### Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

General Format Scali	ng Display Sigr	nal		
Sensor mode				
Mode: Status			Ŧ	Scaling calculator
Sensor range				
Min: 0	~	Max: 1	Ŧ	Unit:
Physical range				
Min: 0		Max: 1		Unit:

#### • Sensor Mode

The sensor mode tells the type of signal. It can be of different types such as "Status", "Voltage", "Frequenzy" or others. It cannot be changed and serves for IPEmotion to know what kind of signal it is dealing with.

• Sensor Range

Shows the raw value range of the signal.

• Physical Range

Allows you to set a range to which you would like to "scale" your signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5** "Channel configuration and scaling".

#### Display

This tab allows you to define what information about the current signal will be shown on a display if one is connected.

General Format	Scaling Display S	ignal	
Displaying area			
Min:	0	Max: 1	
Formatting			
Decimal places:	Automatic 👻		
Name			
Name:	Main runstate		



#### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

#### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

#### • Name

Allows you to set a Name to be shown on a display.

#### Signal

This tab allows you to define signal settings.

General Format Scal	ng Display Signal	
Special function:	None 🔻	
Internal data type:	Double 🔻	
Signalnumber:		
Last value hold:	Until the next reboot 🛛 🔻	
Namespace:	'INTERNAL'	
Origin:	Main runstate	

#### • Internal data type

Assign an internal data type to the signal. Available data types are **"Double"** and **"String"**.

• Signal number

Assign a number to the current signal. This way you will later be able to sort the signals in the grid according to their "Signal numbers".

#### • Last value hold

Specify, for how long the last value of the signal will be hold.

• Timeout

Specify the timeout period for the current signal. If the data source doesn't send data for the specified time period, the value of the signal is set to "NaN (Not a Number)" and will be displayed as "-" in a display.



#### • Namespace

The "Namespace" serves as unique identifier for the signal inside the logger.

#### Signal check

This tab allows to apply the global signal check settings to this signal. In order to do so, global signal check settings have to be defined, please refer to  $(\rightarrow 4.2.2)$ .

The parameters defined by the global signal check settings may be manually overriden for each signal.

This setting does not apply to all internal signals. As of V15.14 it applies to UPS Status signals and as of V17.10 it applies to PPP Status signals.

General Format Sca	ling Display Signal Sign	al check Limit values
Use signal check:	¥	
Mode:	Global settings	<b>T</b>
Start-trigger:		Select
Stop-trigger:		Select
Timeout:	30 s	

#### 6.22.4 Run state

This group of internal signals provides information about the states of external signals and switches, as well as about the wake conditions of the buses that started the logger.

These internal channels can be used as a supplement to the standard logger responses, for example, to start or stop defined methods on signal states. They can also set off warning messages and alarms.

If a bus wake condition is defined, it is output even if this condition was not used to start the current measurement. This makes it possible, during operation, to check when wake conditions are met and trigger methods/messages/alarms.

The following table gives an overview and explanation of "Runs state" signals.

#### 6.22 INTERNAL SIGNALS



Signal	Meaning	Possible Values
Main runstate	Main runstate	0 = off 1 = on
Active wake up condition	Type of wake condition that currently started the logger	1 = A-switch 2 = Cl. 15 3 = WoX
State system switch		0 = off 1 = on
State Clamp 15		0 = off 1 = on
State wake up condition		0 = not met 1 = met
Measuring time delay	Delay between the current logger time and the times- tamp of the data being pro- cessed.	Value in (ms)
Error	Tells you whether an error has occurred in your present con- figuration.	0 = no error 1 = error
Error missing channel		0 = no error 1 = error
Error initialized interface		0 = no error 1 = error
Error missing interface		0 = no error 1 = error
Error persistencefile		0 = no error 1 = error
Dataset size	Tells you the current size of the dataset.	Value in MB
Measuring time delay	Tells you the current measure- ment delay.	Value in ms



#### 6.22.5 System info

These signals provide information on CPU status and allocation of both working memory (mem) and hard drive (disk). Sizes are specified in absolute numbers (in MB or in °C) or as relative values (in %).

This category also contains the loggers frontnumber.

The following table gives an overview and explanation of "System info" signals.

Signal	Meaning	Unit
Total memory	total working memory (RAM)	(MByte)
Free memory	free working memory	(%)
Used memory	used working memory	(%)
Total disk space	total disk space	(MByte)
Free disk space	free disk space	(%)
Used disk space	used disk space	(%)
Total external disk space	total disk space	(MByte)
Free external disk space	free disk space	(%)
Used external disk space	used disk space	(%)
CPU load	processor load	(%)
CPU temperature	processor temperature	(°C)
Frontnumber	Tells you the loggers unique frontnumber	Value



#### 6.22.6 Time

These signals provide information on time and date. They allow you to record a timeline in order to trace the occurrence of events in the logger.

The following table gives an overview and explanation of "Time" signals.

Subtype	Meaning	Unit
Time since beginning of day	Time since 00:00:00 h UTC	(S)
Time sincefirmware start	Time since the firmware was	(s)
	started (values <0 represent values during booting phase)	
Time since START MEAS	Time since measurement has started	(S)
Current date	Current date in the format ddmmyy	Value
Current year	Current year in the format YYYY	Value
Current month	Current month in the format mm	Value
Current day	Current day in the format dd	Value
Current time	Current time in the format hhmmss	Value
Current hour	Current hour in the format hh	(h)
Current minute	Current minute in the format	(min)
	mm	
Current second	Current second in the format	(s)
	SS	(1.10)
Current microseconds	Current microseconds	(µs)



## 6.23 Formulas

A formula is a calculated signal. Apart from the fact of being calculated it has largely the same properties as physical signals and can be modified or used for further processing in the same way. It allows you, to combine already existing signals into a new signal. Therefore the existence of physical signals is requirement in order for formulas to function properly.

All the signals/quantities, that have been individually defined can be further processed in formulas. This also applies to internal signals.

A formula is a one-line term made up of operators and functions that are applied to numbers and signals, which will have a calculated signal as a result. Calculated signals can in turn be used as normal signals in another formula. Not only numbers and signals can serve as function arguments, but also the name of any already defined formula.

The operator priorities used by the formula interpreter are listed in the Table In addition, the interpreter observes the "multiplication/division before addition/subtraction" rule. When uncertain about priorities, you should use brackets.

Bear in mind that signal names and operators, in particular, are case-sensitive. Throughout the signals, whether they be bus, internal or computed, no name may be used twice. The functions can have multiple applications within a formula – with the exception of integration (INT\_STD), differential (DIFF) and moving average (MEAN). So each formula may apply only once the function INT\_STD, DIFF or MEAN.

Operator	Meaning	Priority
AND	Logical and	1
OR	Logical or	1
XOR	Logical, exclusive or	1
<=	Less than or equal to	2
>=	Greater than or equal to	2
<>	Not equal to	2
=	Equal to (comparison)	2
>	Greater than	2
<	Less than	2
+	Addition	3
-	Subtraction	3
*	Multiplication	4
/	Division	4
Λ	Exponentiation $(2^3 =)$ raise	5
	2 to the power of 3")	

#### Special features of moving averages

Unlike the other formulas, the moving average (MEAN) uses not only the current value but also a certain number of previous values. This number is defined by the parameter "Delay depth (values)". The number is theoretically unlimited, but in practice it is limited by the working memory and processing speed.

Assuming the number is =100, then this computes the average over the last 100 samples. At the next sampling instance, the oldest of the 100 values is dropped and the current va-

Changes and errors excepted.

lue is included. At start-up no samples are available for review, so the buffer is still empty. The buffer is filled up with the first valid value and then moves through the sample values. In the event of a signal timeout ("Not a Number", abbreviated NaN, or as a value, also called NoValue), this review is interrupted. As long as the value of the signal is NaN, the moving average is also equal to NoValue (processing a NoValue yields another NoValue). Once the signal goes back to a valid value, the buffer – just like at the start of measurement – is filled with the first valid value, thus resuming processing of a valid average. In a triggered timelog, the moving average is based on the continuous, untriggered value stream. Once the start trigger is activated, the moving average buffer is filled, according to the depth of averaging, with the values gathered prior to the trigger time. This means the moving average at trigger time is computed from values obtained before the start trigger.

#### Special features of "logical" operators

Basic rules for applying the logical operators from are:

- Note upper/lower case: always lowercase logical operators
- Always bracket operands, if you use logical operators. Example: ('signal1') or ('signal2').

The results derived by an operator fundamentally depends on the type of data to which it is applied.

The formula "('signal1') and ('signal2')" applies the logical operator "and" to two channels with rational numbers. In this case, the integer parts of the respective channels are linked bit-wise. So if:

Signal1= 6 (dec) or 110 (bin) Signal2= 3 (dec) or 011 (bin)

Then "('signal1') and ('signal2')" yields the result:

6 and 3 = 2 (dec) or 110 and 011 = 10 (bin)

The formula "('signal1'>5) and ('signal2'>2)" applies the logical operator "and" to the binary intermediate results of two channels with rational numbers. The intermediate results (signal1>5) and (signal2>2) yield binary "0" or "1", depending on the value of the channels. The link "and" merely links these values and can have only "0" or "1" as a result.

#### 6.23.1 Storage method

In order to store calculated signals use one of the following signal storage methods.

- ATFX (→ 12.6)
- MDF 4.0 ( $\rightarrow$  12.7)
- MDF 4.1 (→ 12.8)

Changes and errors excepted.



#### 6.23.2 Adding a formula

To add a new formula select the tree element **"Formulas"**, click on the **"Components"** button in the Ribbon and then choose **"Formula"** 

File	Project	Signals	Acquisiti	on	View
6.			<b> </b> †	Ô	
System	Components	Functions Im	port Export	Check	Adjus
V15.10.0	f(x) Form	nula			
Name	Multi	ple selection		<u></u>	Σ
	~	SIM_501999	99_ID_11		2
	$\sim$	SIM_514999	99_ID_A		4
	🛉 CAN	02			0
	T CAN	03			0
	T CAN	04			0
	🎙 🔹 Data tra	nsfer			0
	4 🚊 🛛 Conr	nections			0
	1 L	JSB			0
	📜 🐛 Tran	sfer events			0
A 🖡	Datasets	;			0
	Data	set			0
▲ @	🖁 🛛 ETH Inte	rfaces			0
	😯 Fron	t			0
	💮 Inter	mal			0
	<ul> <li>oper</li> </ul>	ABK			0
Ť(	🖉 Formulas				0

This will add a generic formula, which in the beginning will have the value "1". Instructions on how to work with that formula and modify it, will be explained in the section "Calculation" ( $\rightarrow$ 6.23.4).

#### 6.23.3 Grid area for formulas

All the formulas, that have been added to your system so far, will be presented in an overview in the grid area. Also you can find here two important functions, which are the **"Column chooser"** ( $\rightarrow$ 4.3.1) and the **"Filter editor"** ( $\rightarrow$ 4.3.2).

	Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate	Bus type	Factor	Offset	Signalnumbe
9												
•	Formula 01	~				-1,797693	1,7976931	1 Hz				
	Formula 02	~		-1,797693	1,797693	-1,797693	1,7976931	1 Hz	NONE		1	
	Formula 03	4		-1,797693	1,797693	-1,797693	1,7976931	1 Hz	NONE		1	0
	Formula 04	~		-1,797693	1,797693	-1,797693	1,7976931	1 Hz	NONE		1	



#### 6.23.4 Details area for formulas

The Details area shows settings either for the tree element "Formulas" or for a single formula/signal which has been selected in the grid area. In case a tree element is selected, the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).

In case a single formula/signal is selected in the grid area, the details area will contain additional tabs which will be explained in the following.

#### General

This tab provides general settings for the selected formula/signal.

General Format	Scaling Display Calculation Signal
Active:	V
Name:	Formula 01
Description:	Define the calculation of a free formula
Reference:	Formula 01////ARCOS 1.5 - dataLog
Sampling rate:	1 Hz

#### Active

Allows you to activate or deactivate the selected formula/signal.

#### Name

Give a user-defined Name to the selected formula/signal.

#### • Description

Give a user-defined description to the selected formula/signal.

#### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



#### • Sampling rate

This field allows you to set the formula/signal's processing rate.

Formulas are executed in cycles. The processing frequency can be defined for each formula. This rate can be set independently of the recording rate. The computation process is applied to the values of the input quantities actually registered at the time of the processing phase. If the processing rate is higher than the signal rate of an input quantity, then the last value of the variable is used again. If the processing rate is lower, then some of the values of the quantity are omitted. (An analogous procedure applies when the recording rate is higher or lower than the processing rate.)
Particularly with such channel processing as min, max, sum or avg, periodic processing means that results are derived for the current sampling instance and not over the entire channel. If, for example, the minimum over an entire channel is required, the minimum/maximum value recording must be used. Processing a timeout value (Not a Number, NaN) also yields a NaN va-
lue.

#### Format

This tab contains information and options regarding file format, tasks and Channel type.

General	Format	Scaling	Display	Calculation	Signal		
Data type							
	Type:	64-Bit floa	ting point		<ul> <li>Task:</li> </ul>	Default	-
NoValue /	DefaultVa	ue					
	Value:	NaN			<ul> <li>Deactivate</li> </ul>	NoValue and use Default Value	
Channel t	ype						
	Input:	<i>~</i>		Output:			

• Data type

This field tells you the type of data (in this case **"64-Bit floating point"**) and allows you to apply special tasks for this formula/signal such as "GPS Longitude", "GPS Latitude", "UTC hour", "Audio mono" and more.

#### • NoValue / DefaultValue

This field allows you to define the value that will be shown if a formula/signal value is read as invalid.



#### Scaling

The fields accessible directly through the tab allow for basic scaling operations to convert analog measurement in engineering units. The **"Scaling calculator"** allows for more refined scaling options with a large range of functions. For details on how to use the "Scaling calculator" please refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.

General	Format	Scaling Display	Calculation Signal		
Sensor mod	le				
	Mode:			-	Scaling calculator
Sensor rang	ge				
	Min:	T	Max:	Ŧ	Unit:
Physical rar	nge				
	Min: -	1,797693134	Max: 1,797693	31348	Unit:

#### • Sensor Mode

The sensor mode tells the type of formula/signal. It can be of different types such as "Status", "Voltage", "Frequenzy" or others. It cannot be changed and serves for IPEmotion to know what kind of formula/signal it is dealing with.

#### • Sensor Range

Shows the raw value range of the formula/signal.

#### • Physical Range

Allows you to set a range to which you would like to "scale" your formula/signal and also define the unit to use. For more refined scaling please use the "Scaling calculator" and refer to the **IPEmotion Documentation - Section 3.4.5 "Channel configuration and scaling"**.



#### Display

This tab allows you to define what information about the current formula/signal will be shown on a display if one is connected.

#### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

#### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.

#### • Name

Allows you to set a Name to be shown on a display.

#### Calculation

This tab provides the main functionality for working with formulas. Here you can define the functions and operators of your formula and what numbers and/or signals they should be applied to.

The operator priorities used by the formula interpreter are listed in the Table In addition, the interpreter observes the "multiplication/division before addition/subtraction" rule. When uncertain about priorities, you should use brackets.

Bear in mind that signal names and operators, in particular, are case-sensitive. Throughout the signals, whether they be bus, internal or computed, no name may be used twice. The functions can have multiple applications within a formula – with the exception of integration (INT\_STD), differential (DIFF) and moving average (MEAN). So each formula may apply only once the function INT\_STD, DIFF or MEAN.



Operator	Meaning	Priority
AND	Logical and	1
OR	Logical or	1
XOR	Logical, exclusive or	1
<=	Less than or equal to	2
>=	Greater than or equal to	2
<>	Not equal to	2
=	Equal to (comparison)	2
>	Greater than	2
<	Less than	2
+	Addition	3
-	Subtraction	3
*	Multiplication	4
/	Division	4
Λ	Exponentiation $(2^3 =)$ raise	5
	2 to the power of 3")	

General Format Scali	ng Display Calculation Signal	
Formula:	1	
Value persistence:	Until the next reboot 🛛 🔻	f(x)
MEAN Depth:	0	
PREV Depth:	1	
	1	

#### • Formula

This field allows you to manually enter a formula.

#### • Formula editor

Although there is the possibility to manually define formulas, most of the time it will be more convenient to define formulas using the *`Formula editor″*.

General Format Scal	ing Display Calculation Signal
Formula:	'TPS_Volt' + 'Rear_left'
Value persistence:	Until the next reboot
Moving Average buffer size:	0
Delay buffer size:	0

The "Formula editor" provides an overview of your current formula (the upper table), as well as the possible "Operands" (left table) and "Operators" (right table) and a short description for each item in the lower table.



You can add items to your formula either by doubleclicking on them or per drag and drop.

If you wish to delete an item from the formula, you can simply mark it with the mouse and than delete it.

If you are uncertain about the operator priorities please refer to the table above.

When confirming a formula that has been defined in the "Formula editor" by clicking **OK**, the editor will automatically validate the formula's correctness. If the formula is not correct, that will result in an error message.

Operand	Description	Reference	Source	Port	Active		Operator	Description	
Operand	Description	Reference	Source	Port			Operator	Description	
						<u> </u>			
Formula 01	Define the calculation of a free formula.		Formula 01		~		(	Begin of bracket block	
Main run state	Signal showing the run state of the logger		Main run st				)	End of bracket block	
Active wake-up condition	Signal showing the run state of the logger	Active wak	Active wak	ARCOS 1.5			+	Addition	
State system switch	Signal showing the run state of the logger		State syste				-	Subtraction	
State clamp 15	Signal showing the run state of the logger		State dam				*	Multiplication	
State wake-up condition	Signal showing the run state of the logger		State wake				^	Potentiation	
Measuring time delay	Signal showing the run state of the logger	Measuring	Measuring	ARCOS 1.5			1	Division	
Error	Signal showing the run state of the logger	Error////AR	Error/Run s	ARCOS 1.5			MOD	Modulo operator	
Error missing channel	Signal showing the run state of the logger	Error missin	Error missin	ARCOS 1.5			ABS()	Absolute value	
Error initialized interface	Signal showing the run state of the logger	Error initiali	Error initiali	ARCOS 1.5			SIGN()	Calculation of sign	
Error missing interface	Signal showing the run state of the logger	Error missin	Error missin	ARCOS 1.5			PREV()	Previous value	
Error persistence file	Signal showing the run state of the logger	Error persis	Error persis	ARCOS 1.5			=	Equality	
Dataset size	Signal showing the run state of the logger	Dataset siz	Dataset siz	ARCOS 1.5			<>	Inequality	
Dataset size (external)	Signal showing the run state of the logger	Dataset siz	Dataset siz	ARCOS 1.5			<	Less comparison	
GPS date	Signal showing GPS information	GPS date//	GPS date/G	ARCOS 1.5			<=	Comparison to less or equal	
GPS altitude	Signal showing GPS information	GPS altitud	GPS altitud	ARCOS 1.5			>	Greater comparison	
GPS horizontal precision	Signal showing GPS information	GPS horizo	GPS horizo	ARCOS 1.5			>=	Comparison to greater or equal	
GPS estimated horizontal precision	Signal showing GPS information	GPS estima	GPS estima	ARCOS 1.5			AND	Logical And operator	
GPS track angle	Signal showing GPS information	GPS track a	GPS track a	ARCOS 1.5			OR	Logical Or operator	
GPS latitude	Signal showing GPS information	GPS latitud	GPS latitud	ARCOS 1.5	~		XOR	Logical Exclusive-Or operator	
GPS longitude	Signal showing GPS information	GPS longitu	GPS longitu	ARCOS 1.5			SHL	Shift left	
GPS satellites number	Signal showing GPS information	GPS satellit	GPS satellit	ARCOS 1.5			SHR	Shift right	
GPS status	Signal showing GPS information	GPS status	GPS status	ARCOS 1.5			SIN()	Sine function	
GPS time	Signal showing GPS information	GPS time///	GPS time/G	ARCOS 1.5			cos()	Cosine function	

#### • Value persistence

Defines the persistence of the signal, so that the value of the signal is sustained even beyond logger restart.

#### • Moving average buffer size

Defines buffer size of the MEAN() filter.

• Delay buffer size

Defines the size of the delay() buffer.

#### Signal

This tab allows you to define formula/signal settings.

#### • Signal number

Assign a number to the current formula/signal. This way you will later be able to sort the formulas/signals in the grid according to their "Signal numbers".



#### 6.23 FORMULAS

General Format Scali	ing Display Signal
Special function:	None 👻
Internal data type:	Double +
Signalnumber:	
Last value hold:	Until the next reboot 🔹
Namespace:	'INTERNAL'
Origin:	Main runstate

#### • Namespace

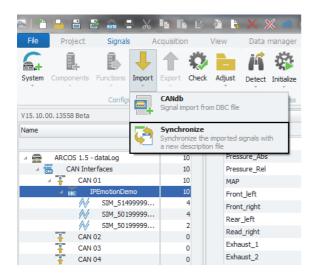
The "Namespace" serves as unique identifier for the formula/signal inside the logger.



## 6.24 Synchronizing signals

This option allows you to synchronize the signals of a already imported description file with a newer or older version of the same description file.

To do so, select the CAN channel or description file you wish to synchronize in the measurement task tree, click "Import" in the ribbon and then choose **"Synchronize"**.



In the resulting window you will be shown which is the file preivously used under "Previous file" and you will be able to choose a new file with which you would like to synchronize. To do so, click in the field for the new file and then click the button with the three dots as shown in the following figure.

Previous file	New file			0,00381476	
IPEmotionDemo.DBC		RONIK (IPEmotion ) In		0,0190738	-50
			Select 1	the file, which should rep	lace the file on the left

In the resulting window you will be able to choose the file with which you would like to synchronize and confirm by clicking "Open".



) 🔾 🕞 🥵 Öffentlic	he Dokumente 🕨 IPETRONIK 🕨 IPEmotion	<ul> <li>Import</li> </ul>	• 🍫 Import du	urchsuchen	
Organisieren 🔻 Neue	er Ordner				0
📃 Zuletzt besucht 🔺	Name	Änderungsdatum	Тур	Größe	
-	IPEmotionDemo.DBC	19.02.2017 09:47	DBC-Datei	2 K	В
Bibliotheken	IPEmotionDemo_J1939.dbc	19.02.2017 09:47	DBC-Datei	9 K	в
Bilder	IPEmotionDemoFD.DBC	19.02.2017 09:47	DBC-Datei	3 K	В
Musik	IPEspeed.dbc	19.02.2017 09:47	DBC-Datei	4 K	В
Musik     Subversion     Videos     Heimnetzgruppe	IPEspeed_from_V01_02_01.dbc	19.02.2017 09:47	DBC-Datei	4 K	В
Computer					
🚢 Lokaler Datenträg					
👝 Lokaler Datenträg					
Date	name:		▼ *.DBC		•

Before you complete the synchronization process, you may adjust two settings on how to handle differences between the two description files.

Fi	le replacements	-		х
	Previous file	New file		
Þ	IPEmotionDemo.DBC	IPEmotionDemo.DBC		
S	Show differences: 📃 Missing signal h	andling: Keep 🔻 OK Car	ncel	

#### • Show differences

If marked active and there are differences between the current configuration and the new description file, a dialog with all these differences will be displayed before the synchronization is be performed. Properties, that cannot be edited, will not be taken into account in this comparison.

#### • Missing signal handling

This dropdown menu allows you to specify how signals, that are no longer available in the new description file, should be handled.

To complete the synchronization process click "OK".



## 6.25 Transferring measurement tasks to the logger



# 7 Triggers

Triggers define a certain event or condition in a way, that they can trigger an action. They possess two distinguishing features compared to formulas:

- They are not a signal but an **event**
- A trigger alway has to be a **truth condition** and therefore can only have to possible values: true or false

Other than that, they are similar to formulas and can mainly be treated in the same way:

A trigger allows you, to combine already existing signals. Therefore the existence of physical signals is requirement in order for triggers to function properly.

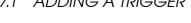
All the signals/quantities, that have been individually defined can be further processed in triggers. This also applies to internal signals.

A trigger is a one-line term made up of operators and functions that are applied to numbers and signals, which will have a calculated condition as a result.

The triggers are divided into four groups and the details on each group can be found in the respective section:

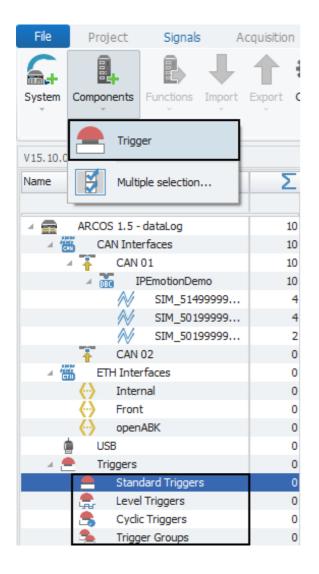
- Standard Triggers ( $\rightarrow$ 7.5)
- Level Triggers ( $\rightarrow$ 7.6)
- Cyclic Triggers ( $\rightarrow$ 7.7)
- Trigger groups ( $\rightarrow$ 7.8)

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#### 7.1 Adding a trigger

To add a new trigger select the desired type of trigger in the tree, click on the "Components" button in the Ribbon and then again choose the desired type of trigger.



This will add a generic trigger condition, which in the beginning will have the value "1". Technically this trigger condition works the same way as a formula and instructions on how to modify it will be explained in the section "Calculation" ( $\rightarrow$ 6.23.4).



## 7.2 Tree elements for triggers

By default the "Measurement task tree" will contain all four categories of triggers.

🛛 🔺 🚊 🛛 Tri	1	
_	Standard Triggers	1
<b>.</b>	Level Triggers	0
	Cyclic Triggers	0
<b>A</b>	Trigger Groups	0

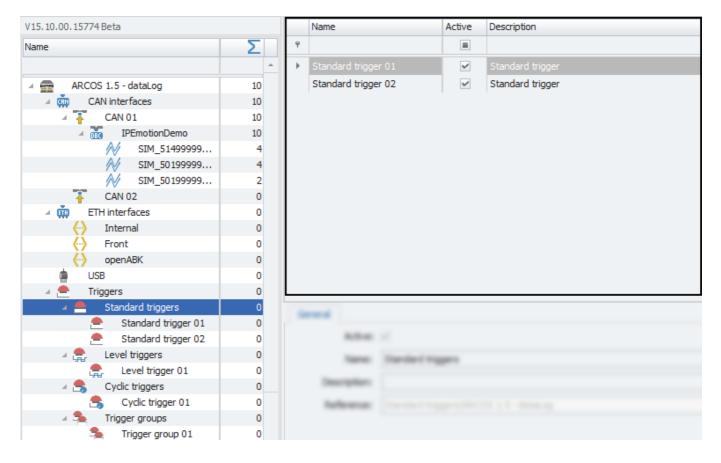
Each trigger that you add to your system will be shown and accessible in the measurement task tree in its respective trigger category.



## 7.3 Grid area for Triggers

The grid area for each Trigger category will present you with an overview of the triggers that have been added to your system so far.

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).





## 7.4 Details area for Triggers

The Details area shows settings either for a selected tree element. In case the "Triggers" element or one of the four categories ("Standard Trigger", "Level Triggers", "Cyclic Triggers" or "Trigger groups") is selected, the details area will only show the "General" tab. Please refer to ( $\rightarrow$ 4.2.2).

#### Settings

In case a single trigger is selected in the tree or the grid area, the details area will additionally contain the **"Settings"** tab.

This tab provides the main functionality for working with Triggers. Here you can define the functions and operators for the formula of your trigger and what numbers and/or signals they should be applied to, as well as cycling rates, levels and groups.

As this tab is different for each trigger category, it will be explained in the respective section for each trigger category:

General Settings		
Trigger condition:	'Pressure_Abs' + 'MAP'	
	f(x)	

- Standard Triggers ( $\rightarrow$ 7.5)
- Level Triggers ( $\rightarrow$ 7.6)
- Cyclic Triggers ( $\rightarrow$ 7.7)
- Trigger groups ( $\rightarrow$ 7.8)

### 7.5 Standard Triggers

For standard triggers, only an activation condition is specified. If the condition is met, the trigger is set; once it is no longer met, the trigger is reset. This makes the standard trigger a simple and quick way to define a trigger. In the following will be explained how work with "Standard Triggers".

• Trigger mode

This field allows you to manually enter a formula for your trigger condition.





General Format Sc	ing Display Trigger	
Trigger mode	1	
		f(x)

#### • Formula editor

Although there is the possibility to manually define formulas, most of the time it will be more convenient to define formulas using the **"Formula editor"**. To do so, please refer to the section **"Formula editor"** ( $\rightarrow$ 6.23.4

### 7.6 Level Triggers

A "Level Trigger" is an event with multiple levels of conditions, which have to be set consecutively, in a specified order. As trigger condition for one level, you can either define a single condition, which if met activates the level, and once it is no longer met, resets the trigger. Or else two conditions are defined, one to activate the level (set condition) and one to reset the trigger (reset condition). The program always checks the reset condition of the current level and the set condition of the next level, and reacts accordingly.

The trigger is set once the highest defined level is reached, and remains set until the reset condition of this level is met.

In the following will be explained how to work with "Level Triggers".

#### Settings

If a "Level trigger" is selected in the tree or the grid are, the settings tab allows for settings regarding the general behaviour of a level trigger.

General Settings		
Last value hold:	Until the next reboot	Ŧ
Timeout:	0 s	
Continuity:	0 s	
Maximum trigger count:	0	
Logfile message:		

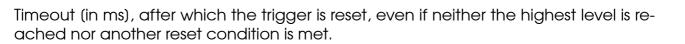
• Last value hold

Sustains the trigger counter, i.e. the number of activated triggers, even beyond logger restart, at which point their count continues.

• Timeout

Changes and errors excepted.

#### 7.6 LEVEL TRIGGERS



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#### • Continuity

Minimum duration of the trigger condition (in ms) before the trigger is activated.

#### • Maximum trigger count

Maximum number of activations for this trigger (0 = unlimited)

#### • Logfile message

If activated, an information on this trigger event will be written to the logfile.

#### Adding trigger levels

Working with a "Level trigger", allows you to add additional trigger levels, for which you can later define trigger conditions and settings. To add a trigger level, select the desired "Level trigger" in the tree, click the "Components" button of the Ribbon and choose "Level".

An overview of all Levels of a "Level trigger" will be presented in the grid area of the respective "Level trigger".

#### Level xx

The settings for each separate level of a "Level trigger" can be accessed by selecting the desired Level in the grid area and then navigating to the "Settings" tab in the details area.

#### • Priority

The priority defines in which order the single levels of a "Level trigger" have to be met. A "Level trigger" will always ascend in priority starting from "Priority 1" to "Priority 2" and so on until the final defined priority is met or a reset condition is met.

#### • Mode

Define the Mode of this trigger level.

- "Inactive" means, this trigger level is deactivated.
- "Reset is inverted set" meanst, this trigger level is activated and will be reset, as soon as the defined set condition is no longer met.
- "Set- and Reset-condition" means that you can define a set condition as well, as a reset condition.

#### • Set condition

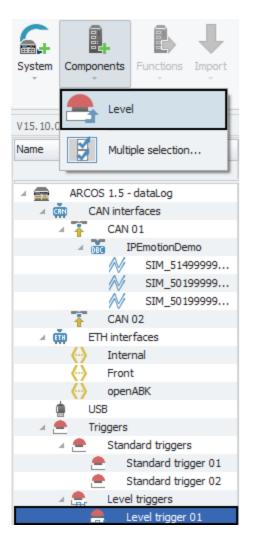
Formula for the condition to activate this level.

The result of the formula must always be 0 (not met) or 1(met), apart from that creating a formula is described in section ( $\rightarrow$ 6.23).





## **IPTRONIK**



#### Reset condition

Formula for the condition to reset the trigger from this level. Once the reset condition is met, the entire trigger is reset and must therefore run through all levels again. If reset term =1 is set for the highest level, the trigger is immediately reset, i.e. only a single trigger impulse is generated. If no resetterm is specified, the end of the set condition is automatically used as the reset condition. This can be prevented by setting =0. The result of the formula must always be 0 (not met) or 1(met), apart from that creating a formula is described in section ( $\rightarrow 6.23$ ).

#### • Timeout

Define a level timeout after which the trigger is reset, regardless of whether the reset condition has been mat or the highest level has been reached.

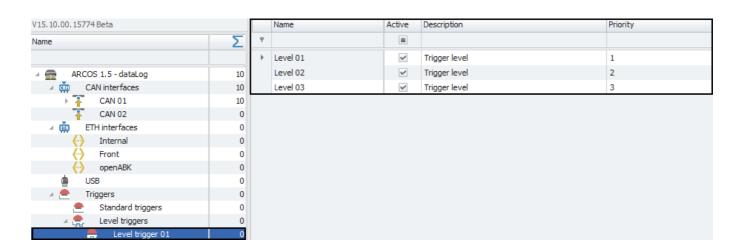
### 7.7 Cyclic Triggers

A "Cyclic Trigger" is an event, that is not defined by a formula. Its only condition is the cycle time to which it is set. According to this time, the trigger will be set periodically. In the following will be explained how to work with "Level Triggers".



**IPTRONIK** 

#### 7.7 CYCLIC TRIGGERS



Settings		
Priority:	1	
Mode:	Reset is inverted Set 🔹	
Set condition:	1	f(x)
Reset condition:		f(x)
Timeout:	0 s	

#### Settings

The "Settings" tab in the details area of the Cyclic Trigger allows you to set the Cycle time according to which the trigger will be set periodically.

General Settings	
Cycle time	:: 1s



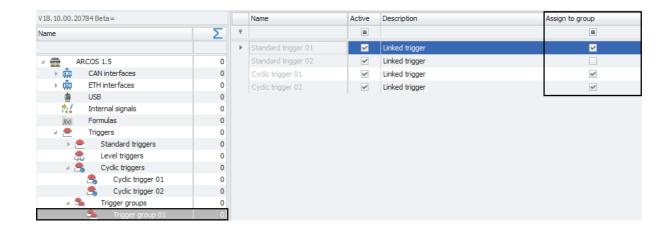
### 7.8 Trigger groups

"Trigger groups" allow you to combine two or more existing triggers and thus create a new trigger condition. Source trigger signals can be combined via "disjunction (or)" or "conjunction (and)".

#### Selecting Triggers

In order for a "Trigger group" to function you will need to select at least two existing triggers to be part of the "Trigger group". To do so, select the "Trigger group" you wish to work with in the measurement task tree.

This will present you with an overview of all available triggers in the details area. Set active the tickbox "Assign to group" for each trigger, that you wish to assign to the group.



#### Settings

en The "Settings" tab in the details area of your "Trigger group" allows you to set the operation mode of the group and whether a logfile should be created.

Operation mode: OR 👻	
Logfile message:	

#### • Operation Mode

Allows you to set the operation mode of the "Trigger group". You may choose between "AND" or "OR".



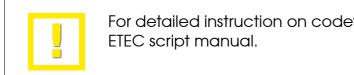
## • Logfile message

If activated, an information on this trigger event will be written to the logfile.



# 8 Scripts

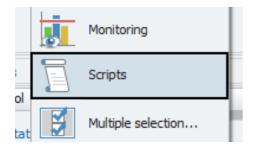
The "Scripts" interface allows you to write customized scripts for a configuration or to import existing scripts in the format "DataLog script" (\*.dls).



For detailed instruction on codewriting for scripts please refer to the CA-ETEC script manual.

## 8.1 Adding the Scripts-Interface

In order to work with scripts, you will first need to add the "Scripts" interface to your system. To do so, select the system in the tree, click the "Components" button in the Ribbon and then choose "Scripts".





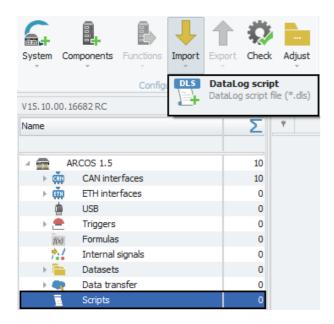
# 8.2 Adding a script

Once the "Scripts" interface has been added to your system, you can then add one or multiple scripts. To do so, select the "Scripts" interface in the tree, click the "Components" button in the Ribbon and then choose "Script".

System	Components	Export Chec
V15.10.0	Script	
Name	Multiple selection	Σ
- 8	ARCOS 1.5	0
	CAN interfaces	0
⊢ ¢	ETH interfaces	0
ą	USB	0
	Triggers	0
fl	x) Formulas	0
7	/ Internal signals	0
> F 🖡	Datasets	0
	Data transfer	0
	Scripts	0

# 8.3 Importing a script

It is also possible to import previously written scripts of the format "DataLog script file (\*.dls)". To do so, select the "Scripts" interface in the tree, click the "Import" button in the Ribbon and then choose "DataLog script".



The following window lets you choose the desired script file and import it by clicking "open".



# 8.4 Tree elements for Scripts

After having added the "Scripts" interface to your system it will appear as a tree element wit the name "Scripts".



Once a script has been created or imported, it will apper as a child element to the "Scripts" interface with three child elements of its own.

The tree child elements labeled "Triggers", "Signals" and "Methods" are non-interactive elements. Their purpose is to show, how many triggers, signals or methods have been defined by the script.

⊿ 🚊 Scripts	0
🔺 📃 Script 01	0
🐚 Triggers	0
Signals	0
🔄 Methods	0

# 8.5 Grid area for Scripts (Composing a script)

The grid area for a script is where the actual composing of the script (writing the code) happens. The grid area provides an editor for writing the code or composing it out of prefabricated block of code, and also for checking for syntax errors of the code. The functions of the editor will be explained in the following.

AETEC

For detailed instructions on codewriting in scripts please refer to the CAETEC script manual. This can be found in the Script editor toolbar next to the syntax check.

Edit	Event	Special functions	Signal	Misc	Trigger	Gateway	User-def. function	Syntax check
1								

The functions of the editor, which can all be found in the toolbar at the top of the editor window, are divided in three groups:

- Edit script code ( $\rightarrow$ 8.5.0.1)
- Prefabricated code blocks ( $\rightarrow$ 8.5.0.2)
- Syntax check ( $\rightarrow$ 8.5.0.3)



If either the "Triggers", "Signals" or "Methods" element has been selected in the tree, the grid area will provide you with extra fucntionalities. These will be explained in the sections "Triggers in Scripts" ( $\rightarrow$ 8.5.1), "Signals in Scripts" ( $\rightarrow$ 8.5.2) and "Methods in Scripts" ( $\rightarrow$ 8.5.3) of this chapter.



#### 8.5.0.1 Edit script code

Here you can find the functions "Find & Replace" and "Comment".



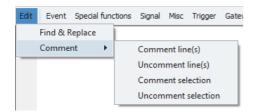
### Find & Replace

The "Find & Replace" function allows you to search your code or a selection of it for characters/words. It also allows you to directly replace the search result.

🃭 Find & Replace 🗕 🗖 🗙	🏴 Find & Replace 📃 🗆 🗙
Find Replace	Find Replace
Find	Find
Highlight	Replace
Match Case	Match Case
Whole Word	Whole Word
Selection	Selection
Find All Clear Find Previous Find Next	Replace All         Replace Previous         Find Previous         Find Next         Replace Next

### Comment

The "Comment" function allows you to comment or uncomment an entire line or a selection. A line/selection, that is commented, is not part of the code.



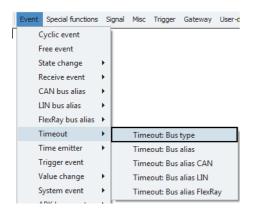


### 8.5.0.2 Prefabricated code blocks

In the middle part of the editor's toolbar you will find a number of dropdown menus that offer prefabricated blocks of code. This allows you to completely compose your script of these blocks instead of writing it manually.

Edit	Event	Special functions	Signal	Misc	Trigger	Gateway	User-def. function	Syntax check
1								

Any code block that is selected in one of these menus will be added to the script at the cursor's current postition. For example choosing "Event->Timeout->Timeout: Bus type", like seen below



will insert the following line of code in the script.



If entering code manually, the editor offers an autocompletion of words. However, this only completes words, but does not check whether the result is an errorfree syntax.



### 8.5.0.3 Syntax check

The "Syntax check" function will check whether the syntax of the code is correct. The result of the syntax check will be presented in a pop-up window.

AETE(

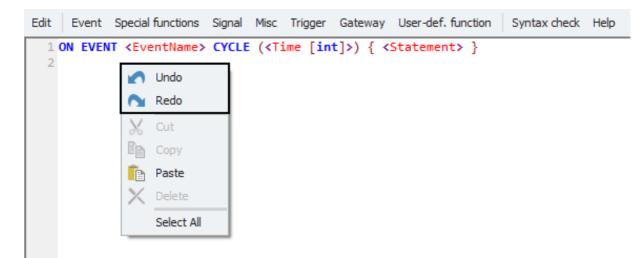
As you can see in the picture below, this pop-up window also offers a line jump feature. That means, if you click on an error in the pop-up window, the editor will automatically jump to the corresponding line and highlight it, so it is easier to correct any errors.

2 userevent(	<pre>EventName&gt; CYCLE (<time [int]="">) { <statement> } <name [string]="">, <value>); wer(<bustype>, <channelnumber>, <state [bool]="">);</state></channelnumber></bustype></value></name></statement></time></pre>	
	IPE Syntax check	_ 🗆 X
	Line 1: syntax error near "ON EVENT <" Line 1: syntax error near "ON EVENT <eventname> CYCLE (<time [int]="">) { &lt;" Line 3: syntax error near "set bus nower(&lt;"</time></eventname>	
	Line 3: syntax error near "set_bus_power( <bustype>, <channelnumber>, <state [bool]="">); parsing aborted due to unrecoverable parsing error, script may be incomplete</state></channelnumber></bustype>	;"

### 8.5.0.4 Undo in scripts / Redo in scripts

The IPEmotion "Undo" button (Ctrl. + Z) and "Redo" button (Ctrl. + Y) do not work to undo or redo actions or parts of scriptcode in the script editor.

In order to undo/redo an action or a part of scriptcode in the script editor, right click in the script editor and choose "Undo" or "Redo" from the resulting context menu.





#### 8.5.1 Triggers in Scripts

When the "Triggers" treeelement of a script is selected, the grid area will present you with an overview of all the triggers, that have been defined by the script. You can also see, whether a trigger is active or not, the description and type of the trigger.

AETE(

	Name	Active 📍	Description	Trigger type
۴		>		
	test_trigger 1	~	Trigger defined by the script	Standard
	test_trigger2	>	Trigger defined by the script	Level

#### 8.5.2 Signals in Scripts

When the "Signals" treeelement of a script is selected, the grid area will present you with an overview of all the Signals, that have been defined by the script. You can also see, whether a signal is active or not and relevant settings, regarding the signal, such as Phy. Min/Max or Sampling Rate. Some of these setting can be edited directly in the grid area.

	Name	Active	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate
۴								
•	test_signal1	<b>×</b>		-1,797693	1,797693	-1,797693	1,7976931	100 Hz

Additional display settings regarding the signal can be accessed via the details area "Display" tab.

General Format	Scaling Display Signal	
Displaying area		
Min:	-1,79769313486:	Max: 1,797693134862
Formatting		
Decimal places:	Automatic 🔻	
Name		
Name:	test_signal1	

#### • Displaying area

Shows the value range which will be shown on a display. It usually should match the "Physical range" from the "Scaling" tab.

#### • Formatting

The dropdown menu **"Decimal places"** allows you to set how many decimal numbers of the value will be shown on a display.



#### • Name

Allows you to set a Name to be shown on a display.

### 8.5.3 Methods in Scripts

When the "Methods" treeelement of a script is selected, the grid area will present you with an overview of all the methods, that have been defined by the script. You can also see, whether a method is active or not, the description and type of the method as well as the file type.

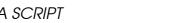
	Name	Active	Description	Method type	File type
۴					
Þ	test_blf	~	Method defined by the script	Trace	Vector BLF
	test_asc	~	Method defined by the script	Trace	Vector ASCII
	test_asc_compressed	\$	Method defined by the script	Trace	Vector ASCII compressed
	test_pcap	~	Method defined by the script	Trace	PCAP

# 8.6 Details area for Scripts

The Details area provides settings for the script, that has been selected in the measurement task tree.

#### General

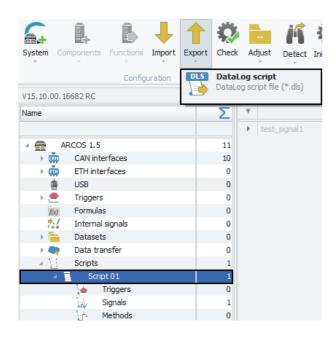
Please refer to ( $\rightarrow$ 4.2.2).





# 8.7 Exporting a script

It is also possible to export a script and thus make it available for use in other configurations. To do so, select the desired script in the measurement task tree, click the "Export" button in the Ribbon and then select "DataLog script".



The following window lets you choose the path, where to save the script file. Confirm with "Save".

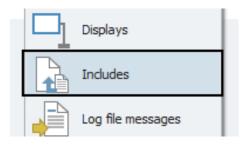


# 9 Includes

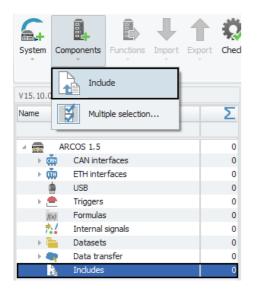
The "Includes" interface allows you to include partial configurations in your system. This can be especially helpfull for components of a configuration that are likely to change over time, such as Wifi accesspoints, and are used by a large number of loggers at the same time.

# 9.1 Adding the Includes-Interface

In order to work with Includes, you will first need to add the "Includes" interface to your system. To do so, select the system in the tree, click the "Components" button in the Ribbon and then choose "Includes".



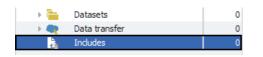
Once the "Includes" interface has been added to your system, you can then add multiple "Includes". To do so, select the "Includes" interface in the tree, click the "Components" button in the Ribbon and then choose "Include".





# 9.2 Tree elements for Includes

After having added the "Includes" interface to your system it will appear as a tree element wit the name "Includes".



# 9.3 Grid area for Includes

If the "Includes" interface is selected in the tree, the Grid area will present you with an overview of the Includes which have been added to your system so far.

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

	Name	Active	Description	Mode	Path	Copy to dataset
٩						
•	Include 01	~	Included partial configuration	Include a specific file		~
	Include 02	~	Included partial configuration	Include a specific file		4

# 9.4 Details area for Includes

The Details area provides settings for the Include, that has been selected in the grid area. General

```
Please refer to (\rightarrow4.2.2).
```

### Settings

This tab provides settings regarding the include file.

General Settings	
Copy to dataset:	
Mode:	Include a specific file 🔹
Path:	

• Copy to dataset

Activating this setting will include a copy of this include file in the dataset for traceability.



### • Mode

Define, whether you want to include a specific file or the entire directory of the include path.

### • Path

Define the cfginclude file path relative to "(cfgdir (see data transfer))/includes/". The file path must end wit a slash (/).



# 10 External files

The function "External files" allows to include in the .ccmc a database file (DBC, AUTOSAR, FIBEX etc.), that has been used to import signals into a signal channel (CAN, LIN, FlexRay or ETH), as external file. When exporting your configuration, the external file will be included in the .ccmc container and can thus be made available for later use in acquisition data analysis or can be included in a dataset. All external files will be stored on the logger alongside the configuration file.

The function "External files" is available for CAN, LIN, FlexRay and ETH.

# 10.1 Automatically add external files

In addition to manually adding a database as external file to your configuration, it is possible to set up a configuration in such a way, that every signal database that gets imported in any one signal channel will automatically be added as external file to that signal channel.

To enable this setting, navigate to the "Options" window of IPEmotion.

File			
1	New		Recent projects list
	Open		
	Save		
昰	Save as		
	App-Export	۲	
jour la company	Runtime version		
Ó	Compare		
	Print	ł	
Ţ	View	ŀ	
	Administration	×	
	Options		
	About		
	Close		



In the following window navigate to the "PlugIns" tab of the sidebar and access the plugin-specific settings for "CAETEC dataLog" by clicking the button with the blue screw wrench symbol right next to "CAETEC dataLog".

Frequently used	Active	Title			Version	Descriptio	n	
Basic settings		CAETE	C dataLog	۲		CAETEC I	Data logger (A	RCOS and µC
Appearance								
View								
Data manager								
Import								
Export								
Analysis								
Directories								
Units								
Hotkey								
User administration								
IPEcloud								
PlugIns	4							
User displays								Downloa
User operations								Downloa
	Plugin se	ettings le plugins to be	unod					
					e list. If a version numb	المحاجب والمحاجب		and the second second

In the following window navigate to the "Options" tab and activate the tickbox for the setting "Create and synchonize external files". In this way, whenever you import a signal database to a channel, it will be automatically be added as external file.

Export requirements:	Error Free Configuration 🔻	
Extended FlexRay namespace:		
eate and synchronize external files:	V	
Communication		
Primary IP address:	203.0.113.1	
Secondary IP address:	192.168.1.88	
Alternative IP address:		
User name:		
Password:		



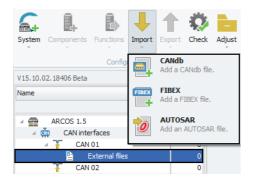
# 10.2 Adding the External files interface

To add the "External files" interface to a signal channel, select the desired channel in the measurement task tree, click the "Components" button in the Ribbon and then choose "External files".

6.			₽
System	Components ,	Functions	Import T
V15.10.0		statistic	F
Name	4.5	io recording	
4	OBD	-2	-
	Exte	ernal files	
× ¢		eway	

# 10.3 Adding an external file

Once the interface has been added to the signal channel, you can then add one or multiple external files. To do so, select the resepective "External files" interface in the measurement task tree, click the "Import" button in the Ribbon and then choose the desired database type.



The available database types for external files depend on the type of signal channel, to which they will be linked. So while an external file for a CAN channel may be of the type CANdb, AUTOSAR or FIBEX, an external file for an Ethernet channel can only be of the type AUTOSAR or FIBEX.

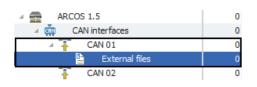


In the following window you may then choose your database file and confirm with "OK".

ganisieren 👻 Neuer Ordner			== -
Favoriten	Name	Änderungsdatum	Тур
💻 Desktop	IPEmotionDemo.DBC	19.02.2017 09:47	DBC-Datei
🚺 Downloads	IPEmotionDemo_J1939.dbc	19.02.2017 09:47	DBC-Datei
🔄 Zuletzt besucht	IPEmotionDemoFD.DBC	19.02.2017 09:47	DBC-Datei
	IPEspeed.dbc	21.11.2017 06:54	DBC-Datei
<ul> <li>Bibliotheken</li> <li>Bilder</li> <li>Dokumente</li> <li>Musik</li> <li>Subversion</li> <li>Videos</li> <li>Heimnetzgruppe</li> </ul>	Different_from_V01_02_01.dbc	21.11.2017 06:54	DBC-Datei
Heimnetzgruppe		1	

# 10.4 Tree elements for External files

Once the "External files" interface has been added to a signal channel it will appear as a child element to the respective channel in the measurement task tree.



# 10.5 Grid area for External files

The grid area for "External files" will provide you with an overview of the added external files for a signal channel. It also provides information on the type of database and the location of the original database file to be included.

	Name	Active	Description	Location
۴				
•	CANdb	<b>Z</b>	CANdb file	
	AUTOSAR	~	AUTOSAR file	
	FIBEX	~	FIBEX file	



# 10.6 Details area for External files

The details area for "External files" will provide you with settings regarding a single database file that has been selected in the grid area.

#### General

Please refer to ( $\rightarrow$ 4.2.2).

#### File settings

This tab allows you to select the database file, you wish to include. To do so, click the three dots at the right of the field. In the following window navigate to the location of your database file and confirm.

General File settings	
External file:	



# 11 Surveillance

There are multiple functions for monitoring data acquisition and logger activity. This section will give an overview of these functions and explain their functionality in detail.

# 11.1 Displays

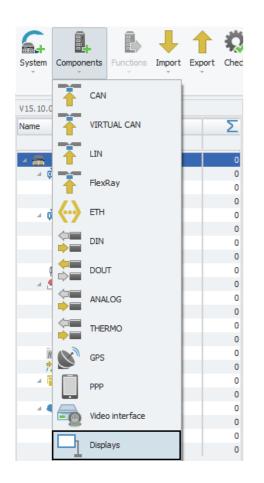
You can connect a display to your logger in order to display certain displays, events, video streams and messages. CAETEC dataloggers and the CAETEC dataLog PlugIn for IPEmotion support two types of displays:

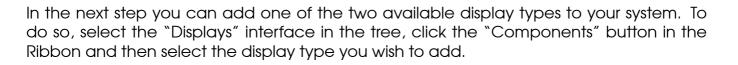
- CAETEC display ( $\rightarrow$ 11.1.3)
- third party openABK display ( $\rightarrow$ 11.1.4)

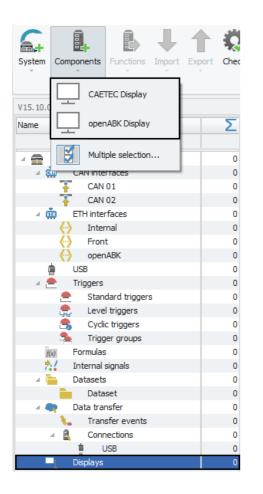
Configuration of these displays via the plugin will be explained in detail in the following.

## 11.1.1 Adding a display

In order to add a display to your system, you will first need to add the "Displays" interface. To do so, select the system in the measurement task tree (the topmost element in the tree, in this case ARCOS 1.5), click the "Components" button in the Ribbon and select "Displays".







For instructions regarding the configuration of the single display types please refer to the respective sections of this manual:

- CAETEC display ( $\rightarrow$ 11.1.3)
- third party openABK display ( $\rightarrow$ 11.1.4)

For instructions regarding the configuration of the entire "Displays" interface please keep reading on below.







### 11.1.2 The "Displays" interface

In order to access the settings regarding the entire "Displays" interface including all additionally connected display types, select the tree element "Displays" and navigate to the details area. The details area contains two tabs which will be explained here.

- 🗨 Intertande	General Settings	
Tarafa averts	Active: 🗹	
1	Name: Displays	
Displays	0 Description: All connected displays	
	Reference: Displays/ARCOS 1.5	

General Please refer to  $(\rightarrow 4.2.2)$ .

### Settings

This tab contains settings specific for the "Displays" interface.

General Settings		
Language:	English	<b>T</b>
Display trigger counter:	Reset at system restart	▼
	L	

• Language

Choose the standard display language.

• Display trigger counter Set the behaviour of the display trigger counter. There are three available settings.

Display trigger counter setting	Characteristics
Reset at new configuration	The trigger counter will be reset, when the logger
	receives a new configuration.
Reset at system start	The trigger counter will be reset, whenever the
	logger restarts.
Never reset	The trigger counter will never be reset.



#### 11.1.3 CAETEC Display-specific settings

This section will explain settings specific for the CAETEC Display. These settings are to be found in the details area of the CAETEC Display.

#### **Autoscroll**

Settings regarding the display's autoscroll function. Pressing the trigger button will interrupt autoscroll for a defined time interval.

General Extended Autoscroll	
Autoscroll: 🗹	
Interval: 7,2 s	]

#### • Autoscroll

Activate or deactivate the autoscroll function.

• Interval

Time interval after which autoscroll will be reactivated. Setting this parameter to 0 will also deactivate the autoscroll function.



#### 11.1.4 openABK Display-specific settings

This section will explain settings specific for the openABK Display. These settings are to be found in the details area of the openABK Display.

#### **Files**

Define which display-configuration files will be included in the loggers configuration.

General Extended Files	Priorities
IPEmotion APP:	
EMBU-Chart layout:	

#### • Export IPEmotion APP

This setting allows you to export a display-configuration for the IPEmotion APP. The display-configuration file will be included in the logger configuration. As soon as a display gets connected to the logger, the display will check whether a corresponding display-configuration file is available on the logger. If so, the display will automatically download the display-configuration and apply it.



For instructions on how to configure the IPEmotion APP as a display device, please refer to the IPEmotion documentation.

#### • Export EMBU-Chart

This setting allows you to export a display-configuration for an EMBU display device. The display-configuration file will be included in the logger configuration. As soon as a display gets connected to the logger, the display will check whether a corresponding display-configuration file is available on the logger. If so, the display will automatically download the display-configuration and apply it.



### **Priorities**

Set the priorities for the "Violation" and the "Status" dialog. The dialog with the higher priority will be shown if both dialogs appear at the same time.

General Extended Priorities	
Violation dialog: 9	]
Status dialog: 8	]

#### 11.1.5 General Display settings

### 11.1.5.1 Tree elements for a Display

Adding the a to your system will add one new child element with the name "CAETEC/openABK Display" to the "Displays" interface. The "CAETEC/openABK Display" will again possess the three child elements: **Signals, Buttons, Messages**.

🛛 🖳 Displays	0
🔺 💻 CAETEC Display	0
🖄 Signals	0
Buttons	0
📄 Messages	0

## 11.1.5.2 Grid area for a Display

In the "Grid area" you will be presented with an overview of the available Signals, Buttons or Display messages, depending which tree element has been selected. Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

	Name	Active	Description
٩			
۶.	Display message 01	~	
	Display message 02	~	



	Name	Active	Description
٩			
•	Display message 01	~	
	Display message 02	~	

### 11.1.5.3 Details area for a Display

The details area for a display provides settings for the behaviour of the display.

#### General

Please refer to  $(\rightarrow 4.2.2)$ . Extended Settings regarding the display of the selected signal.



#### • Export display name

Set checkbox to force export of the parameter display name to the connected display device.

#### • Add signals automatically

If set, all eligible signals will be automatically added to the display. Any signals that have already been added will not be removed if they becom ineligible.



### 11.1.5.4 Signals for Display

The "Signals" element allows you to select one or more signals to be displayed on the connected display-device. To do so, select the "Signals" element, click on the "Components" button in the Ribbon and then choose "Signal".

System	Components Functions Import Exp	ort Chec
V15.10.0		
Name		Σ
4 💼	ARCOS 1.5	10
► Q	CAN interfaces	10
•           •	ETH interfaces	0
	USB	0
	Triggers	0
fb	Ø Formulas	0
2	Internal signals	0
🕞 🕨 🖥	Datasets	0
<b>&gt;</b> ■	🕴 Data transfer	0
I 🗆	] Displays	0
	CAETEC Display	0
	🕺 Signals	0
	E Buttons	0
	🛁 Messages	0

In the following window you will be presented with an overview of all the available signals for display. Choose one or more signals that you wish to display and confirm with "OK".

Pressure_Abs         bar         0,00000         2,00000         0         65535         1 Hz           Pressure_Rel         bar         -2,00000         2,00000         0         65535         1 Hz           MAP         bar         0,00000         3,00000         0         65535         1 Hz           TPS_Volt         V         -8,0000         8,0000         0         65535         1 Hz           Front_left         C         -50,000         200,000         0         65535         1 Hz           Rear_left         C         -50,000         200,000         0         65535         1 Hz           Read_right         C         -50,000         200,000         0         65535         1 Hz           Exhaust_1         C         -50,000         200,000         0         65535         1 Hz           Exhaust_2         C         -50,001         1200,00         0         65535         1 Hz	Name	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate	
Pressure_Rel         bar         -2,00000         2,00000         0         65535         1 Hz           MAP         bar         0,00000         3,00000         0         65535         1 Hz           TP5_volt         V         -8,0000         8,0000         0         65535         1 Hz           Front_right         C         -50,000         200,000         0         65535         1 Hz           Front_right         C         -50,000         200,000         0         65535         1 Hz           Rear_left         C         -50,000         200,000         0         65535         1 Hz           Exhaust_1         C         -50,000         200,000         0         65535         1 Hz								
MAP         bar         0,00000         3,0000         0         65535         1 Hz           TPS_Volt         V         -8,000         8,000         0         65535         1 Hz           Front_left         C         -50,000         200,000         0         65535         1 Hz           Front_right         C         -50,000         200,000         0         65535         1 Hz           Rear_left         C         -50,000         200,000         0         65535         1 Hz           Read_right         C         -50,000         200,000         0         65535         1 Hz           Exhaust_1         C         -50,000         1200,000         0         65535         1 Hz	Pressure_Abs	bar	0,00000	2,00000	0	65535	1 Hz	
TPS_Volt         V         -8,000         8,0000         0         65535         1 Hz           Front_left         C         -50,000         200,000         0         65535         1 Hz           Front_left         C         -50,000         200,000         0         65535         1 Hz           Front_right         C         -50,000         200,000         0         65535         1 Hz           Rear_left         C         -50,000         200,000         0         65535         1 Hz           Read_right         C         -50,000         200,000         0         65535         1 Hz           Exhaust_1         C         -50,000         1200,000         0         65535         1 Hz	Pressure_Rel	bar	-2,00000	2,00000	0	65535	1 Hz	
Front_left         C         50,000         200,000         0         65535         1 Hz           Front_right         C         -50,000         200,000         0         65535         1 Hz           Rear_left         C         -50,000         200,000         0         65535         1 Hz           Read_right         C         -50,000         200,000         0         65535         1 Hz           Exhaust_1         C         -50,000         1200,000         0         65535         1 Hz	MAP	bar	0,00000	3,00000	0	65535	1 Hz	
Front_right         C         -50,000         200,000         0         65535         1 Hz           Rear_left         C         -50,000         200,000         0         65535         1 Hz           Read_right         C         -50,000         200,000         0         65535         1 Hz           Exhaust_1         C         -50,000         1200,000         0         65535         1 Hz	TPS_Volt	v	-8,0000	8,0000	0	65535	1 Hz	
Rear_left         C         -50,000         200,000         0         65535         1 Hz           Read_right         C         -50,000         200,000         0         65535         1 Hz           Exhaust_1         C         -50,000         1200,000         0         65535         1 Hz	Front_left	с	-50,000	200,000	0	65535	1 Hz	
Read_right         C         -50,000         200,000         0         65535         1 Hz           Exhaust_1         C         -50,00         1200,000         0         65535         1 Hz	Front_right	С	-50,000	200,000	0	65535	1 Hz	
Exhaust_1 C -50,00 1200,00 0 65535 1Hz	Rear_left	С	-50,000	200,000	0	65535	1 Hz	
	Read_right	С	-50,000	200,000	0	65535	1 Hz	
Exhaust_2 C -50,00 1200,00 0 65535 1Hz	Exhaust_1	С	-50,00	1200,00	0	65535	1 Hz	
	Exhaust_2	С	-50,00	1200,00	0	65535	1 Hz	

In order to access the settings regarding the signals to be displayed please proceed as follows. Select the treeelement "Signals", then select the desired signal in the grid area and access the settings in the details area.



### General

The description field allows you to give a user specific description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

General Display	1
Name:	
Description:	
Reference:	Pressure_Abs/CAETEC Display/ARCOS 1.5

# Display

Settings regarding the display of the selected signal.

General	Display		
	Display name:	Pressure_Abs	
	Decimal places:	Automatic	-

## • Display name

Define a name for the selected signal, which will be displayed if the function "Export display name" has been enabled.

## • Decimal places

Define the count of decimal places for the signal.



#### 11.1.5.5 Buttons for Display

The CAETEC and openABK Displays possess one "Trigger button", which will be shown in the grid area when selecting the "Buttons" element in the measurement task tree.

To access settings regarding this "Trigger button", select the treeelement "Buttons" and then select the "Trigger button" in the grid area. The setting can be found in the "Trigger button's" details area.

#### General

The name field allows you to give a user specific name of the trigger button and the description field allows you to give a user specific description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

General Trigger	General Trigger					
Active:	V					
Name:	Trigger button					
Description:	Trigger button					
Reference:	Trigger button/CAETEC Display/ARCOS 1.5					

### Trigger

The field "Fired trigger" tells you the trigger to be fired if the button is pressed.

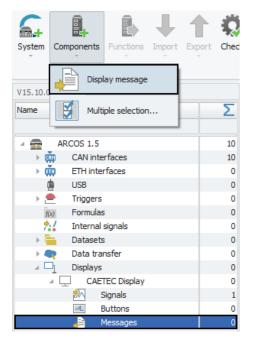
General Trigger	
Fired trigger:	trig_display



### 11.1.5.6 Messages for Display

The "Messages" element allows you to set up one or more customized "Display messages" which will be displayed when triggered. To do so, select the "Messages" element, click on the "Components" button in the Ribbon and then choose "Display message". Multiple "Display messages" can be defined.

The content and trigger of the message may be defined in the message's settings in the details area.



To access a message's settings, select it in the grid area and then navigate to the details area.

#### General

This tab allows you to activate or deactivate a Display message by ticking/unticking the checkbox.

It also allows you to give a user specific name if wished and add an additional description. The Reference field serves as the unique identifier inside the measurement task tree. It cannot be changed.





In the field "Name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .



## Trigger

In this tab you can define which trigger will cause the display of a "Display message".

General Trigger Setti	ngs
Trigger:	Select

## Settings

In the "Text" field you may type in the message you would like to be displayed.

General Trigger Settings	
Text:	



In the field "Text" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .



# 11.2 E-mails

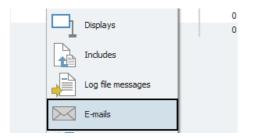
For surveillance-purposes it is possible to configure e-mails with user-specific content. Sending of these e-mails will be triggered by user-defined events.

### 11.2.1 Setting up the E-mails interface

In order to set up the "E-mails" interface, you will first need to add it to your system and then configure its SMTP settings. These steps will be explained in the following.

### 11.2.1.1 Adding the E-mails interface

In order to add the "E-mails" interface select your system in the measurement task tree (the topmost elemenet of the tree), click the "Components" button in the Ribbon and then select "E-mails".



# 11.2.1.2 Configure SMTP

In order for the logger to be able to send e-mails, the SMTP settings have to be correctly set. To do so, fill in your e-mail provider's SMTP server details as well as your user name, password and sender.

To do so, select the "E-mails" interface in the measurement task tree, navigate to the "SMTP" tab in the details area and fill in the fields.

Dataset	U		
🔺 🗬 🛛 Data transfer	0	General SMTP	
🐛 Transfer events	0	Host name:	
Z Connections	0		
USB USB	0	Port:	25
📨 E-mails	0	Communication security:	None 👻
		Authentication method:	None •
		User name:	
		Password:	
		Sender:	



In the field "Sender" project parameters can be used as variables. For more information please refer to ( $\rightarrow$ 5.6).

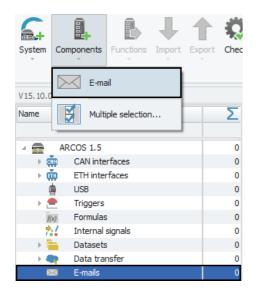


### 11.2.2 Composing e-mails

This section will explain how to compose new e-mails and how to define a trigger for sending an e-mail.

### 11.2.2.1 Creating a new e-mail

In order to compose an e-mail, you will first need to create it. To do so, select the "E-mails" interface in the measurement task tree, click on the "Components" button in the Ribbon and choose "E-mail":



## 11.2.2.2 Grid area for E-mails

In the "Grid area" you will be presented with an overview of all the e-mails, that have been created so far, as well as details regarding those e-mails, such as subject, recipient, trigger etc. Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

	Name	Active	Description	Subject	Text	Trigger	Recipient
٩							
+	E-mail 01	~	E-mail configuration	Notification E-mail 01 @ [tri			
	E-mail 02	~	E-mail configuration	Notification E-mail 02 @ [tri			



### 11.2.2.3 Details area for E-mails (Composing)

The Details area shows settings for "E-mails" allows you to compose an e-mail and set its trigger, as well as general settings.

#### General

This tab allows you to activate or deactivate the e-mail by ticking/unticking the checkbox. It also allows you to give a user specific name if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

General Trig	General Trigger Settings				
Activ	Active: 🗹				
Name	e: E-mail 01				
Description	n: E-mail configuration				
Reference	e: E-mail 01/ARCOS 1.5				



In the field "Name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .

### Trigger

This tab allows you to set the trigger which will cause an e-mail to be sent. For each e-mail a trigger needs to be defined. And while each e-mail can only have one trigger defined, the same trigger can be defined for multiple mails.

General Trigger Settings	
Trigger:	Select





#### Settings

This is the tab, where the actual composing of the e-mail happens.

General Trigger Settings			
Recipient:			
Subject:	Notification E-mail 01 @ [triggerdate] [triggertime] (datalog FN [frontnumber])		
Body:			

#### • Recipient

Fill in the e-mail addresse, that will receive the e-mail. Multiple recipients are possible. They have to be separated by comma, semicolon or a white space.

#### • Subject

Fill in a subject for the e-mail.

• Body

Fill in the text, that will be contained in the e-mail.



In the field "Body" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .

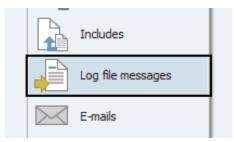


# 11.3 Log file messages

For surveillance-purposes it is possible to configure log file messages with user-specific content. These messages will be written into the log file when triggered by a user defined trigger.

### 11.3.1 Adding the Log file messages interface

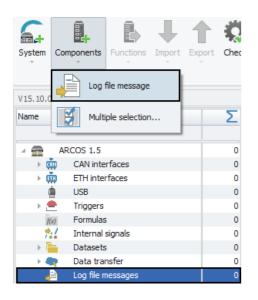
In order to create log file messages, you will first need to add the "Log file messages" interface to your system. To do so, select the system in the measurement task tree (the topmost element of the tree), click the "Components" button in the Ribbon and then choose "Log file messages".



### 11.3.2 Create a new Log file messages interface

Once the "Log file message" interface has been added to your system, you can now create a new message. To do so, select the "Log file messages" interface in the measurement task tree, click the "Components" button in the Ribbon and then choose "Log file message".

Composing and configuration of the message will be explained in the section "Details area for Log file messages" ( $\rightarrow$ 11.3.3.2).



### 11.3.3 Composing Log file messages

This section will explain how to compose log file messages and how to define a trigger for writing the message to the log file.

#### 11.3.3.1 Grid area for Log file messages

In the "Grid area" you will be presented with an overview of all the Log file messages, that have been created so far, as well as details regarding those Log file messages, such as the trigger and text of the message.

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

	Name	Active	Description	Trigger	Text
٩					
•	Log file message 01	~	Log file configuration		
	Log file message 02	~	Log file configuration		
	Log file message 03	~	Log file configuration		

### 11.3.3.2 Details area for Log file messages (Composing)

The Details area for "Log file messages" allows you to compose the message and set its trigger, as well as general settings.

To access the details area for a certain "Log file message", select the message in the grid area and then navigate to the grid area.

#### General

This tab allows you to activate or deactivate the Log file message by ticking/unticking the checkbox.

It also allows you to give a user specific name if wished and add an additional description. The Reference field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

General Trigger Settings				
Active: 🗸				
Name:	Log file message 01			
Description:	Log file configuration			
Reference:	Log file message 01/ARCOS 1.5			



In the field "Name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .

### Trigger

This tab allows you to set the trigger which will cause a Log file message to be written to the log file. For each Log file message a trigger needs to be defined. And while each Log file message can only have one trigger defined, the same trigger can be defined for multiple mails.





# Settings

This is the tab, where the actual composing of the Log file message happens. Write in any text you wish in the field labeled "Text". This text will then be written as a message to the log file when triggered.

General Trigger	Settings
	Text:



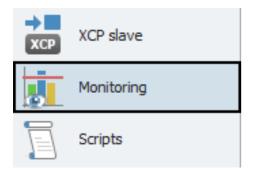
In the field "Text" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .



# 11.4 Monitoring

The "Monitoring" interface allows you to define certain limit values or ranges for a signal or channel and monitor if these limits are being violated. The result of monitoring operations can be displayed live on any connected display.

In order to do so, you will first need to add the "Monitoring" interface to your system. Select the system (the topmost element of the tree) in the measurement task tree, click the "Components" button in the Ribbon and then choose "Monitoring".



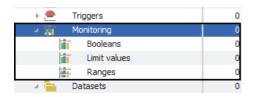
Next you will need add and configure either a "Limit value" or a "Range". To do so please refer to the respective sections of this chapter:

- Booleans ( $\rightarrow$ 11.4.2)
- Limit value ( $\rightarrow$ 11.4.3)
- Range ( $\rightarrow$ 11.4.4)

# 11.4.1 Tree elements for Monitoring

Once the "Monitoring" interface has been added to your system, it will apper as a new tree element in the measurement task tree. It will also contain three child elements called **"Booleans"**, **"Limit value"** and **"Range"**.

These child elements will contain all the "Booleans", "Limit values" and "Ranges", that you later add to your system.



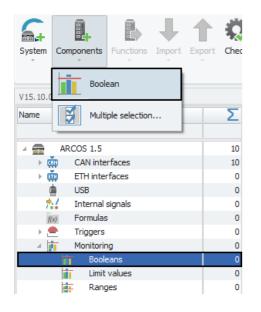


# 11.4.2 Booleans

The "Booleans" function in "Monitoring" allows you to define a boolean condition in connection with a signal. If the boolean condition becomes true, a user-specific action will be executed.

# 11.4.2.1 Adding Booleans

In order to add a boolean, select the tree element "Booleans", click on the "Components" button in the Ribbon and then choose "Boolean".



# 11.4.2.2 Grid area for Booleans

In the "Grid area" you will be presented with an overview of all the Booleans, that have been created so far, as well as details regarding those Booleanss, such as signal, operation, etc..

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

	P     Image: Constraint of the second s	Name	Active Description	Channel Operation	Output
		٩			
ue 02 = No output	Limit value 02 = No output	Limit value 01	01 🔽	=	No output
		Limit value 02	02	=	No output
		Limit value 02	J2	=	No output

# 11.4.2.3 Details area for Booleanss

The Details area contains settings regarding the Booleans.

# General

Please refer to ( $\rightarrow$ 4.2.2).

Changes and errors excepted.



# Configuration

This tab allows you to define to which signal a boolean should apply.

General Configuration	Actions	
Signal:		Select
Operation:	Boolean 👻	
Reference value:	1	f(x)
	-	

• Signal

Choose the Signal to which the boolean will apply.

• Operation

This setting is by default set to boolean and cannot be changed.

• Reference value

The reference value is the boolean condition. It can be a fixed value, a signal or a formula. For details on working with the formula editor please refer to ( $\rightarrow$ 6.23.4).

#### Actions

This tab allows you to define what action will be taken, should a boolean condition become true.

General Configuration Actions	
Display:	
Trigger: Desitive edge	
Eventist:	

• Display

If activated, a Display option will be used. The Display option comes with further settings in extra tabs, that need to be set. These extra settings will be explained in the sections concerning the "Display" tabsheet ( $\rightarrow$ 11.4.2.3) and the "Parameter x" tabsheet ( $\rightarrow$ 11.4.2.3).

• Trigger

If set, a trigger action will be used. You may further set the trigger mode to **Posi**tive/Negative Edge or Stateful.

• Eventlist

If set, an eventlist entry will be created, if either the "EVENT" or the "FEGER" header is used in the dataset. Please refer to  $(\rightarrow 12.2)$ .

Changes and errors excepted.



# Display

Define the display output settings.

General Configuration	Actions	Display	Parameter 1	Parameter 2	Parameter 3	Parameter 4	Parameter
HID dialog priority:	0						
HID dialog class:							

• HID dialog priority

Define the HID dialog priority. Higher priorities are ranked higher and will thus be preferred if there is a multiple occurrence of display actions.

• HID dialog class

Define the HID dialog class, that will be displayed when a display action occurrs.

#### Parameter x

This tab allows you define the type fo parameter that should be displayed and its content. Up to 5 parameters can be defined.

General	Configuration	Actions	Display	Parameter 1	F	arameter 2	Parameter 3	Parameter 4	Parameter
	Mode:	Static Para	meter		Ŧ				
	Name:								
	Static value:								
	Dynamic value:					Select			

• Mode

Define whether no parameter, a static parameter or a dynamic parameter should be displayed.

• Name

Define the parameter name.

- Static value Define the parameter value for a static parameter.
- Dynamic value

Select a signal as the parameter value for a dynamic parameter.

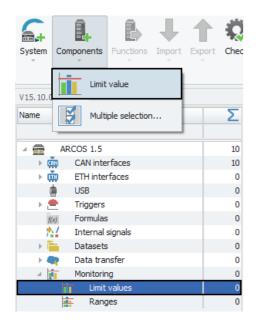


# 11.4.3 Limit value

The "Limit value" function in "Monitoring" allows you to define a single value for a signal and to compare the signal to this value. The result of this comparison will be put out to the connected display.

# 11.4.3.1 Adding a limit value

In order to add a limit value, select the tree element "Limit value", click on the "Components" button in the Ribbon and then choose "Limit value".



# 11.4.3.2 Grid area for Limit values

In the "Grid area" you will be presented with an overview of all the limit values, that have been created so far, as well as details regarding those limit values, such as channel, operation, output etc..

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

	Name	Active	Description	Channel	Operation	Output
٩						
+	Limit value 01				=	No output
	Limit value 02	~			=	No output



# 11.4.3.3 Details area for Limit values

The Details area contains settings regarding the limit value.

#### General

This tab provides general settings for a limit value.

General	Configu	ration Actions
	Active:	
	Name:	Limit value 01
Desc	ription:	Limit value
Refe	erence:	Limit value 01/ARCOS 1.5

• Name

Give a user-defined Name to the selected Limit value.

• Description

Give a user-defined description to the selected Limit value.

• Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



In the field "Name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .

# Configuration

This tab allows you to define to which signal a limit value should apply, as well as in what way.

General Configuration	Actions	
Signal:		Select
Operation:	- *	
Reference value:	1	f(x)
	-	

• Signal

Choose the Signal to which the limit value will apply.



#### • Operation

Select the boolean operator by which the signal will be compared to the limit value. This will determine whether you will get a result when the signal hits the reference value, exceeds it or falls below it.

#### • Reference value

The reference value is the value to which the signal will be compared. It can be a fixed value, a channel or a formula. For details on working with the formula editor please refer to ( $\rightarrow$ 6.23.4).

# Actions

This tab allows you to define what action will be taken, should a limit violation occurr.

General Configuration Actions	
Display:	
Trigger: Dositive edge	
Eventlist:	

#### • Display

If activated, a Display option will be used. The Display option comes with further settings in extra tabs, that need to be set. These extra settings will be explained parts of this section concerning the "Display" tabsheet ( $\rightarrow$ 11.4.3.3) and the "Parameter x" tabsheet ( $\rightarrow$ 11.4.3.3).

# • Trigger

If set, a trigger action will be used. You may further set the trigger mode to **Posi**tive/Negative Edge or Stateful.

# • Eventlist

If set, an eventlist entry will be created, if either the "EVENT" or the "FEGER" header is used in the dataset. Please refer to ( $\rightarrow$ 12.2).

# Display

Define the display output settings.

General Configuration	Actions	Display	Parameter 1	Parameter 2	Parameter 3	Parameter 4	Parameter
HID dialog priority:	0						
HID dialog class:				-			



#### • HID dialog priority

Define the HID dialog priority. Higher priorities are ranked higher and will thus be preferred if there is a multiple occurrence of display actions.

#### • HID dialog class

Define the HID dialog class, that will be displayed when a display action occurrs.

#### Parameter x

This tab allows you define the type fo parameter that should be displayed and its content. Up to 5 parameters can be defined.

Configuration	Actions	Display	Parameter 1		Parameter 2	Parameter 3	Parameter 4	Parameter
Mode:	Static Para	meter		Ŧ				
Name:								
Static value:								
Dynamic value:					Select			
	Mode: Name: Static value:	Mode: Static Para Name: Static value:	Mode: Static Parameter Name: Static value:	Mode: Static Parameter Name: Static value:	Mode: Static Parameter  Name: Static value:	Mode: Static Parameter  Name: Static value:	Mode: Static Parameter  Name: Static value:	Mode: Static Parameter  Name: Static value:

# • Mode

Define whether no parameter, a static parameter or a dynamic parameter should be displayed.

# • Name

Define the parameter name.

#### • Static value

Define the parameter value for a static parameter.

#### • Dynamic value

Select a signal as the parameter value for a dynamic parameter.

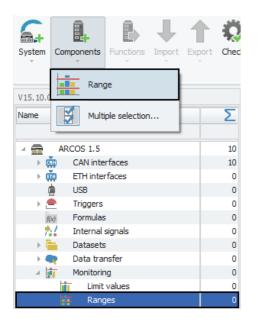


# 11.4.4 Range

The "Range" function in "Monitoring" allows you to define a double set of limit values. You can thus create a Range of values to which to compare the signal. The result of this comparison will be put out to the log file and can can additionally be displayed on a connected display.

# 11.4.4.1 Adding a Range

In order to add a Range, select the tree element "Range", click on the "Components" button in the Ribbon and then choose "Range".



# 11.4.4.2 Grid area for Ranges

In the "Grid area" you will be presented with an overview of all the Ranges, that have been created so far, as well as details regarding those Ranges, such as channel, operation, output etc..

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

	Name	Active	Description	Channel	Operation	Top output
٩						
+	Range 01	~			Limit violation out of range	No output
	Range 02	~			Limit violation out of range	No output
	Range 03	~			Limit violation out of range	No output



# 11.4.4.3 Details area for Ranges

The Details area contains settings regarding the Range.

#### General

Please refer to ( $\rightarrow$ 4.2.2).

### Configuration

This tab allows you to define to which signal a Range should apply, as well as in what way.

For a Range you need to define a top limit value and a bottom limit value. You can then compare the signal to that range and see if it is inside or outside of the range.

General	Configuration	Actions			
Signal and	d operation mode				
	Signal:	Select	Operation:	Limit violation out of range 🔹	
Тор			Bottom		
Тор	reference value:	1	Bottom reference value:	1	
		-		-	
		f(x)		f(x)	

• Signal

Choose the Signal to which the Range will apply.

• Operation

Select the boolean operator by which the signal will be compared to the Range.

#### • (Top/Bottom) Reference value

The reference value is the value to which the signal will be compared. It can be a fixed value, a channel or a formula. For details on working with the formula editor please refer to ( $\rightarrow$ 6.23.4).

#### Actions

This tab allows you to define what action will be taken, should a limit violation occurr.

General Configuration	Actions
Display:	
Trigger:	Positive edge
Eventlist:	

• Display

If activated, a Display option will be used. The Display option comes with further settings in extra tabs, that need to be set. These extra settings will be explained parts of this section concerning the "Display" tabsheet ( $\rightarrow$ 11.4.4.3) and the "Parameter x" tabsheet ( $\rightarrow$ 11.4.4.3).

Changes and errors excepted.



#### • Trigger

If set, a trigger action will be used. You may further set the trigger mode to **Posi**tive/Negative Edge or Stateful.

• Eventlist

If set, an eventlist entry will be created, if either the "EVENT" or the "FEGER" header is used in the dataset. Please refer to  $(\rightarrow 12.2)$ .

# Display

Define the display output settings.

General Configuration	Actions	Display	Parameter 1	Parameter 2	Parameter 3	Parameter 4	Parameter
HID dialog priority:	0						
HID dialog class:							

• HID dialog priority

Define the HID dialog priority. Higher priorities are ranked higher and will thus be preferred if there is a multiple occurrence of display actions.

• HID dialog class

Define the HID dialog class, that will be displayed when a display action occurrs.

# Parameter x

This tab allows you define the type fo parameter that should be displayed and its content. Up to 5 parameters can be defined.

General	Configuration	Actions	Display	Parameter 1	Parameter 2	Parameter 3	Parameter 4	Parameter
	Mode:	Static Para	meter	]	<b>*</b>			
	Name:							
	Static value:							
	Dynamic value:				Select			

• Mode

Define whether no parameter, a static parameter or a dynamic parameter should be displayed.

• Name

Define the parameter name.

Changes and errors excepted.



# • Static value

Define the parameter value for a static parameter.

# • Dynamic value

Select a signal as the parameter value for a dynamic parameter.

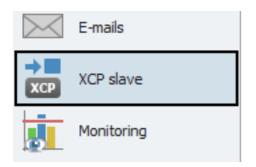


# 11.5 XCP slave

"XCP slave" allows you to connect the logger to a PC via ethernet and let the PC function as XCP master. That means, the PC will be requesting and receiving signals from the logger.

# 11.5.1 Adding XCP slave

In order to add XCP slave, select the system in the measurement task tree (the topmost element of the tree), click the "Components" button in the Ribbon and then choose "XCP slave".



# 11.5.2 Tree elements for XCP slave

Adding "XCP slave" to the system will add one new tree element called "XCP slave".



# 11.5.3 Grid area for XCP slave

The Grid area provides you with an overview of the ethernet channels available for XCP slave. Here you need to select the ethernet channel you wish to use by ticking the "Use as XCP slave" tickbox.

	Name	Active	Description	Channel number	Use as XCP slave
٩					
I	Front	<b>Z</b>	Ethernet channel	3	
	openABK	~	Ethernet channel	2	
	ETH 04	~	Ethernet channel	4	



It is possible to select multiple ethernet channels for XCP slave, but if you choose more than one channel, all available channeles will be activated automatically.



# 11.5.4 Details area for XCP slave

The details area for XCP slave contains all the important settings regarding the xcp slave <u>connection</u>.



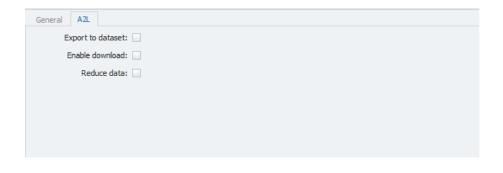
The important settings for XCP slave are located in the details area of the tree element "XCP slave", not in the details area of any of the ethernet connections in the grid area.

#### General

Please refer to ( $\rightarrow$ 4.2.2).

# A2L

This tab provides settings regarding the type and location of the A2L file provided to a PC for establishing a connection with the ECU.



# • Export to dataset

Activating this option will store the entire A2L file of the logger, including all bus-, ECUand logger-signals, inside the dataset. From there it can be copied to your PC and used for XCP slave.

# • Enable download

Activating this option will make the A2L file of the logger, including all bus-, ECU- and logger-signals, available for download from the web interface. From there it can be downloaded to your PC and used for XCP slave.

# • Reduce data

If this option is activated, only a reduced file size A2L file will be available for copying/download. This A2L file will only contain the information necessary for the PC to connect to the logger, from where it can then download the entire A2L file including all bus-, ECU- and logger-signals.

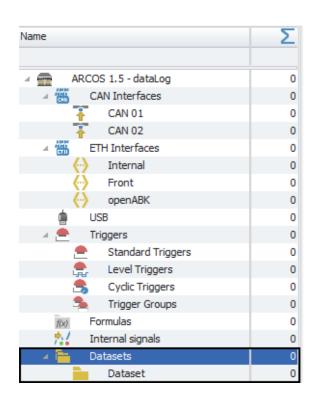


# 12 Datasets

Data acquired throughout a measurement task will be stored in a dataset by the logger. This chapter will explain how to configure the created dataset.

# 12.1 Tree elements for Datasets

The tree element **"Datasets"** will contain all the datasets you define for your system. The child element **"Dataset"** then contains the single components of your dataset.





# 12.2 Details area for Datasets

This section contains settings regarding the overall behaviour of your dataset. These settings are global and will affect all components of your dataset.

In case the parent tree element "Dataset" selected, the details area will only show the "General" tab. Please refer to  $(\rightarrow 4.2.2)$ .

In case the child element "Dataset" is selected, the details area will contain additional tabs which will be explained in the following.

General File se	ttings Dataset settings Generate Header						
Active:							
Name:	Name: Dataset						
Description:	A dataset for one/multiple datafile(s)						
Reference:	Reference: Dataset/ARCOS 1.5 - dataLog						

# General

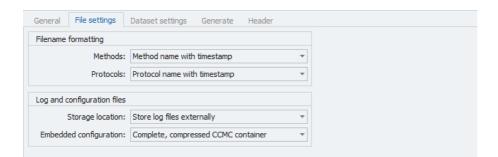
Please refer to  $(\rightarrow 4.2.2)$ .



In the field "Name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .

# File settings

This tab contains settings regarding filename and location.



#### • Filename formatting

This field allows you to define the filename formatting of the final dataset file. Both methods and protocols have to possible formatting options:

 Method/Protocol name with timestamp: protocol name with timestamp (date and time)(default setting)

Changes and errors excepted.



- Timestamp, trigger name and counter: Appends the name of the activating trigger and its number/counter to the right of the timestamp in the file name.
- Log and configuration files This field allows you to set whether your dataset file wil be stored externally or internally and what type of configuration to embed. There are four types of configuration available:
  - Complete, compressed CCMC container: Entire container is stored as is.
  - Uncompressed contents of CCMC container: Content of the container is unpacked and stored.
  - Only CFG: Only the cfg is extracted.
  - Complete, compressed CCMC container and uncompressed contents: Entire container is stored as is and the unpacked content of the container is stored as well.

# Dataset settings

This tab allows for settings regarding the dataset itself.

taset format			Dataset encoding	
Directories	: With subdirectories	-	Type:	zip
			Compression level:	6
ataset name				
Append timestamp	:			

#### Dataset format

Define whether the directory structure of data within a dataset contains subdirectories or not.

#### • Dataset encoding

Set the type of encoding and compression level for the dataset.

#### • Dataset name

Select, whether a timestamp will be appended to the dataset name.



# Generate

Define settings regarding the creation of the dataset.

Start-trigger:     Select     Remove     Condition:     On shutdown       Pause-trigger:     Select     Remove     Trigger:     Select     Remove	General File settings Dataset settings Generate Header Start and pause	Completion
Compress after completion: 🗹		Trigger: Select Remove

#### • Start and Pause

This field allows you, to set triggers to start or pause dataset creation. If you do not set a start trigger, then by default dataset creation is always active during measurement.

# • Completion

The dropdown menu **"Condition"** allows you to set a condition under which the dataset should be closed and completed. In case your condition for completion requires a trigger, you may choose the trigger in the below field.

If you choose **"Compress after completion"**, the will be compressed directly after completion. If you do not choose this option, the dataset will be compressed before transfer.



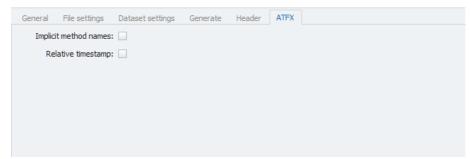
#### Header

When storing the data, the logger saves general information about the measurement (identification, comments, start, stop) and information about the data files (name, structure) in a header file. For additional functionality a various headers with specific options can be attached. The options of each activated header-type will be accessible in a separate tab with the header-type's name.

Multiple header-types can be activated at the same time.



• ATFX



• EVENT



• FEGER

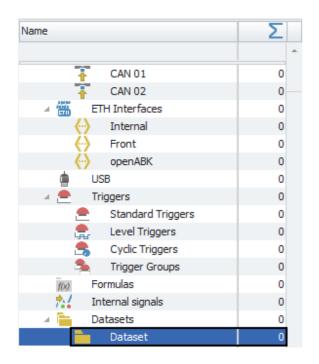




# 12.3 Setting up a dataset

A dataset can be set up using different filetypes, according to what information you want it to contain. Each filetype you include in your dataset has specific functionalities and for each included filetype will later be included a file in the exported dataset with its preivously configured name and the according filetype extension.

In order to include a filetype in your dataset, select the tree element "Dataset".





Then click the "Components" button in the Ribbon and choose the desired filetype from the resulting menu.

File	Project	Signals	Acquisit
System	Components	Functions Im	port Expor
	🚌 🛓 Proj	ect settings	
V15.10.0		udes	
	GPX GPX		
		x	
ą		<sup>:</sup> 4.0	
A (		4.1	
		tor BLF	
R		tor ASCII	
7 		tor ASCII compre	essed
- 4		Р	
	WAY WAY	/	
Symbol		TEC Binary	
		TEC ASCII	
	Mult	iple selection	1

The following sections will explain in detail the different filetypes.



# 12.4 Dataset Project settings

The "Project settings" filetype is meant for including Project information such as company name, serial number, project name etc. in your dataset. Multiple "Project settings" files can be included in your dataset. The "Project settings" filetype for dataset creates a set of project parameters that will be included only in the respective dataset. In order to define "Project settings" that apply globally to the entire configuration and that get exported with every dataset, please refer to  $(\rightarrow 5)$ .

# 12.4.1 Adding project parameters

It is possible, to add user-specific project parameters in addition to the default project parameters. To do so, select the desired "Project settings xx" element in the measurement task tree, select the "Components" button in the Ribbon and then choose "Project parameter".

System	Components	Functions	Import T	Export	Chec
V15.10.0	📻 📄 Proje	ect paramete	r		
Name	Multi	ple selection			Σ
- 💼	ARCOS 1.5				0
► Q		0			
ETH interfaces					0
USB (					0
Triggers					0
f(x) Formulas					0
1 Internal signals					0
🔺 🚞 Datasets					0
	🛛 📄 🛛 Data	set			0
	<u>e:</u>	Project settin	gs 01		0
	<b>œ</b> ₽ P	roject settin	gs 02		0

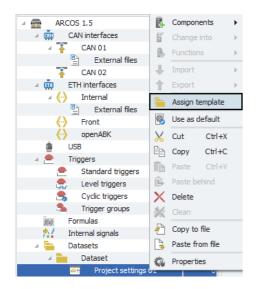
The new parameter will appear in the respective "Project settings xx" Grid area as customizable parameter in the table.

	File name	
	Date	27.06.2018 10:18:39
Ø.	Project parameter 14	



# 12.4.2 Assigning a template of project parameters

It is also possible, to assign a template which contains a predefined set of user-specific project parameters. To do so, right-click on the "Project settings xx" tree element and then choose "Assign template".

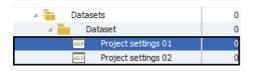


In the following window you may choose the template file and confirm wit "Open". The file type needs to be .xml.

🦳 Öffnen		<b>—X</b> —
CO V IPETRONIK > IPEmotion	• • ProjectTemplate • EDR -	EDR durchsuchen
Organisieren 🔻 Neuer Ordner		i≡ <b>-</b> □ 0
🖳 Zuletzt besucht	Name	Änderungsdatum Typ
<ul> <li>➡ Bibliotheken</li> <li>➡ Bilder</li> <li>➡ Dokumente</li> <li>Jusik</li> <li>➡ Subversion</li> <li>➡ Videos</li> <li>➡ Heimnetzgruppe</li> </ul>	ProjectPar.xml	08.05.2017 17:58 XML-Dokument
P Computer Lokaler Datenträger (C:) C Lokaler Datenträger (K:)	• • • III	
Dateiname: projectPr	ar.xml	▼ projectPar (projectPar.xml) (prc      ▼     Õffnen      Abbrechen

# 12.4.3 Tree elements for Project settings

Including a "Project settings" file in your dataset will add one new child element per included "Project settings" file to your tree element "Dataset". The tree element is labeled "**Project settings xx**".



Changes and errors excepted.



# 12.4.4 Grid area for Project settings

If a "Project settings xx" element is selected in the Measurement task tree, the grid area will provide you with a table, that allows you to access all default or previously defined user-specific projet parameters.

	Name	Value
٩		
Þ	Company name	
	Serial number	
	Manufacturer	
	Project name	
	Project manager name	
	E-mail address project manager	
	User	
	E-mail address user	
	User login	bachl
	Description	
	IPEmotion version	V08.00.01
	File name	
	Date	27.06.2018 10:18:39
	Project parameter 14	

# 12.4.5 Details area for Project settings

If a "Project settings xx" element has been selected in the measurement task tree, additional settings are available in the details area.

# General

This tab provides general settings for the selected Project settings file.

V
Project settings 01
Project settings
Project settings 01/ARCOS 1.5

• Name

Give a user-defined Name to the selected formula/signal.

• Description

Give a user-defined description to the selected formula/signal.

### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



# Info

Tells you the type of template that has been assigned.

General Info		
Template type:	EDR	



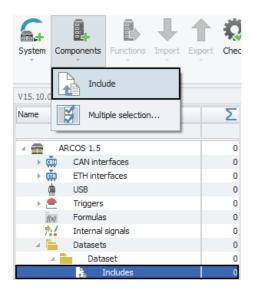
# 12.5 Includes

The "Includes" filetype allows you to include partial configurations in your dataset. This can be especially helpfull for components of a configuration that are likely to change over time, such as Wifi accesspoints, and are used by a large number of loggers at the same time.

# 12.5.1 Adding the Includes-Interface

Adding the "Includes" filetype as described in the chapter "Setting up a dataset" ( $\rightarrow$ 12.3), will add the "Includes" interface to your dataset.

Once the "Includes" interface has been added to your dataset, you can then add multiple "Includes". To do so, select the "Includes" interface in the tree, click the "Components" button in the Ribbon and then choose "Include".



# 12.5.2 Tree elements for Includes

After having added the "Includes" interface to your dataset it will appear as a child element to the dataset with the name "Includes".





# 12.5.3 Grid area for Includes

If the "Includes" interface is selected in the tree, the Grid area will present you with an overview of the Includes which have been added to your system so far. Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1)

and the "Filter editor" ( $\rightarrow$ 4.3.2).

	Name	Active	Description	Mode	Path	Copy to dataset
۴						
Þ	Include 01	~	Included partial configuration	Include a specific file		~
	Include 02	~	Included partial configuration	Include a specific file		~

#### 12.5.4 Details area for Includes

The Details area provides settings for the Include, that has been selected in the grid area. General

Please refer to ( $\rightarrow$ 4.2.2)	)
Settings	

This tab provides settings regarding the include file.

General Settings	
Copy to dataset:	V
Mode:	Include a specific file 🔹
Path:	

• Copy to dataset

Activating this setting will include a copy of this include file in the dataset for traceability.

• Mode

Define, whether you want to include a specific file or the entire directory of the include path.

• Path

Define the cfginclude file path relative to "(cfgdir (see data transfer))/includes/". The file path must end wit a slash (/).



The "ATFX" filetype is meant for recording of signals. It is compatible with all signals that produce values that can be represented on a 2-D graph. It is not compatible with video or audio files.

The recorded signal values will be represented in a timelog.

# 12.6.1 Tree elements for ATFX

Including the "ATFX" filetype in your dataset will add three new child elements to your tree element "Dataset":

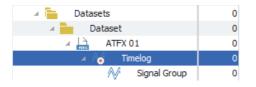
# • ATFX xx

This element represents the ATFX file, which will later be included in your exported dataset. You may add multiple files of the same filetype.



#### • Timelog

This element represents the timelog for recording signal values.



# • Signal Group

The signal is a group of all the signals that the timelog will record and that will ultimately be included in the exported dataset.

🔺 🚞 🛛 Datasets	0
🔺 🧰 Dataset	0
ATFX 01	0
🔺 🎊 Timelog	0
🛝 Signal Group	0

# 12.6.2 Grid area for ATFX

If the "Signal Group" is selected in the Measurement task tree, the grid area will show an overview of the signals included in the "Signal Group"



#### 12.6.3 Details area for ATFX

The details area contains settings for the behaviour of your ATFX file, timelog or signal group.

12.6.3.1 ATFX file

#### General

This tab provides general settings for the selected ATFX file.

General File	
Active:	
Name:	ATFX 01
Description:	File for saving acquisition data
Reference:	ATFX 01/ARCOS 1.5 - dataLog

#### • Active

Allows you to activate or deactivate the selected file.

#### • Name

Give a user-defined Name to the selected formula/signal.

#### • Description

Give a user-defined description to the selected formula/signal.

#### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



# File

This tab provides settings regarding the creation of the file.

General File		
File type:	ATFX	
File create event:	On dataset begin 👻	
Maximum file size:	1,953125 GB	
Create new file:		
Data type:	Float 👻	

# • File type

Tells you the type of the created file.

#### • File create event

Define, when the ATFX file should be created. There are four possibilities:

File create event	Characteristics
On dataset begin	The file will be created everytime, the dataset is started
	or restarted after a pause. This may result in a splitting
	of the current ATFX file into multiple files, as a new file is
	created for each time a dataset ist started.
On recording start	The file will be created once at logger start.
On trigger	The file will be created on a trigger and record for a
	user defined duration. These settings can be defined
	in the timelog settings ( $ ightarrow$ 12.6.3.2). This will result in a
	splitting of the current ATFX file into multiple files, as a
	new file is created for each timethe trigger is set.
On first trigger	The file will be created once, when the defined trig-
	ger is set for the first time and record for a user defined
	duration. These settings can be defined in the timelog
	settings $\rightarrow$ 12.6.3.2). Each following thime the trigger is
	set, the data will be written in the same previously cre-
	ated file. Therefore there will only be one file.

#### • Maximum file size

Define the maximum file size. It is recommended not to raise the maximum file size above 2GB, as some third party analysis tools cannot handle files, that are larger.

# • Create new file

If this box is marked active, a new file will be created, if the current file exceeds the maximum file size.

# • Data type

This dropdown menu allows you to switch the data type between float or double.



# 12.6.3.2 ATFX Timelog

# General

This tab provides general settings for the selected ATFX timelog.

User
Timelog
Contains one/multiple signal group(s)
Timelog/ATFX 01/ARCOS 1.5 - dataLog

#### Active

Allows you to activate or deactivate the selected file.

#### • Name

Give a user-defined Name to the selected file.

• Description

Give a user-defined description to the selected file.

• Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



In the field "Name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .



# Trigger

This tab provides settings regarding the trigger for the start and stop of the timelog. When the timelog is started, all signals contained in the signal group will be stored to the ATFX file according to their settings.

Furthermore will this trigger provoke the creation of the ATFX file, if you have choosen either "On trigger" or "On first trigger" as "File create event".

General Trigger User			
Mode:	Continuous acquisition 🔻		
Start-trigger:		Select	Remove
Stop-trigger:		Select	Remove
Pre-trigger duration:	0 s		
Post-trigger duration:	0 s		
Master:		Select	Remove

#### • Mode

Define whether you wish to continuously store data or if you want to start/stop data storage via a trigger. There are two modes to control data storage via trigger:

**Start and stop trigger** allows you to set any previously defined trigger as start and/or stop condition.

**Stop is inverted start** will store data as long as the start trigger condition is met. Once it is no longer met and a possibly set **Post-trigger duration** has run out, data storage will stop.

• Start-trigger

Define a trigger, that will start the timelog.

• Stop-trigger

Define a trigger, that will stop the timelog.

• Pre-trigger duration

Pre-trigger duration allows you to define, how long before the start trigger was set, the timelog will start.

• Post-trigger duration

Post-trigger duration allows you to define, how long after the start trigger was set, the timelog will stop.

#### User

The field "Identifier" allows you to give a user identifier to the timelog. It does not have any effect other than helping the user identifiy a specific timelog.



# 12.6.3.3 ATFX Signal Group

# General

This tab provides general settings for the selected ATFX timelog.

Active: Name:	
Description:	Signal-based measurement method
Reference:	Signal Group/ATFX 01/ARCOS 1.5 - dataLog

### Active

Allows you to activate or deactivate the selected file.

#### • Name

Give a user-defined Name to the selected formula/signal.

#### • Description

Give a user-defined description to the selected formula/signal.

#### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

# Storage

This tab allows for setting regarding the storage of the contained signals inside the ATFX file.

# • Storage mode

The storage mode in ATFX is fixed. It cannot be changed.

Changes and errors excepted.



neral	Storage				
	Storage mode:	Fixed	*		
	Storage rate:	: 1 Hz			

# • Storage rate

The storage rate defines how often the signals contained in this "Signal Group" will be stored.



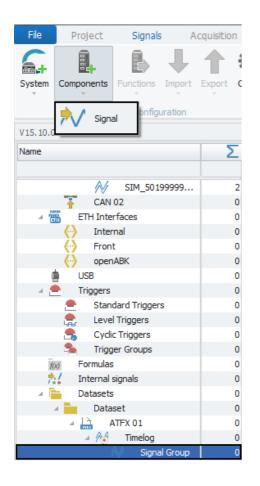
Storage rates with decimal places will be rounded to three decimal places.



### 12.6.4 Working with Signal Groups for ATFX

For filetypes intended for signal recording such as ATFX, MDF 4.0 and MDF 4.1, signals need to be included in a "Signal Group" belonging to the timelog, to which you would like the signal to be included. The signals, that are included in a "Signal Group" can then be stored.

To achieve this, select the "Signal group" in the "Measurement task tree", click the "Components" button in the Ribbon and choose "Signal".







In the following window you may choose all the available signals, that you wish to include within this group and confirm by clicking OK'.

Pressure_Abs         bar         0,00000         2,00000         0         65535         1 Hz         None           Pressure_Rel         bar         -2,00000         2,00000         0         65535         1 Hz         None           MAP         bar         0,00000         3,0000         0         65535         1 Hz         None           TPS_Volt         V         -8,0000         8,0000         0         65535         1 Hz         None           Front_jeft         C         -50,000         200,000         0         65535         1 Hz         None           Rear_left         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None
Pressure_Rel         bar         -2,0000         2,0000         0         65535         1 Hz         None           MAP         bar         0,0000         3,0000         0         65535         1 Hz         None           TPS_Volt         V         -8,0000         8,0000         0         65535         1 Hz         None           Front_left         C         -50,000         200,000         0         65535         1 Hz         None           Front_left         C         -50,000         200,000         0         65535         1 Hz         None           Rear_left         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None
MAP         bar         0,0000         3,0000         0         65335         1 Hz         None           TPS_Volt         V         -8,0000         8,0000         0         65535         1 Hz         None           Front_left         C         -50,000         200,000         0         65535         1 Hz         None           Front_right         C         -50,000         200,000         0         65535         1 Hz         None           Rear_left         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None
TPS_volt         V         -8,0000         8,0000         0         55355         1 Hz         None           Front_left         C         -50,000         200,000         0         65535         1 Hz         None           Front_right         C         -50,000         200,000         0         65535         1 Hz         None           Rear_left         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None
Front_left         C         -50,000         200,000         0         65535         1 Hz         None           Front_right         C         -50,000         200,000         0         65535         1 Hz         None           Rear_left         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None
Front_right         C         -50,000         200,000         0         65535         1 Hz         None           Rear_left         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None
Rear_left         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None
Read_right C -50,000 200,000 0 65535 1 Hz None
Exhaust_1 C -50,00 1200,00 0 65535 1 Hz None
Exhaust_2 C -50,00 1200,00 0 65535 1 Hz None
Exhaust_2 C -50,00 1200,00 0 65535 1 Hz None

i

ATFX can only contain one "Signal Group" and this "Signal Group" can only have one storage rate. That means, all signals, that are contained in the same "Signal Group", will be stored with the same storag rate.



# 12.7 MDF 4.0

The "MDF 4.0" filetype is meant for recording of signals. It is compatible with all signals that produce values that can be represented on a 2-D graph. It is not compatible with video or audio files.

The recorded signal values will be represented in a timelog.



MDF 4.0 and MDF 4.1 files can have (Other than ATFX) multiple "Signal Groups" and some of those groups allow for include signals to be stored in various rates.

## 12.7.1 Tree elements for MDF 4.0

Including the "MDF 4.0" filetype in your dataset will add three new child elements to your tree element "Dataset":

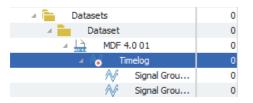
## • MDF 4.0 xx

This element represents the MDF 4.0 file, which will later be included in your exported dataset. You may add multiple files of the same filetype.

🛛 🧮 Datasets	0
🛛 🧰 🛛 Dataset	0
🔺 🚉 MDF 4.0 01	0
🔺 🎊 Timelog	0
Signal Grou	0
N Signal Grou	0

# Timelog

This element represents the timelog for recording signal values.



### • Signal Group

The signal is a group of all the signals that the timelog will record and that will ultimately be included in the exported dataset.



# 12.7.2 Grid area for MDF 4.0

If the "Signal Group" is selected in the Measurement task tree, the grid area will show an overview of the signals included in the "Signal Group"



### 12.7.3 Details area for MDF 4.0

The details area contains settings for the behaviour of your MDF 4.0 file, timelog or signal group.

### 12.7.3.1 MDF 4.0 File

#### General

This tab provides general settings for the selected MDF 4.0 file.

General File	
Active:	V
Name:	ATFX 01
Description:	File for saving acquisition data
Reference:	ATFX 01/ARCOS 1.5 - dataLog

#### Active

Allows you to activate or deactivate the selected file.

## • Name

Give a user-defined Name to the selected file.

#### • Description

Give a user-defined description to the selected file.

#### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



# File

This tab provides settings regarding the creation of the file.

General File			
File type:	ATFX		
File create event:	On dataset begin 🔹		
Maximum file size:	1,953125 GB		
Create new file:			
Data type:	Float 👻		

## • File type

Tells you the type of the created file.

### • File create event

Define, when the MDF 4.0 file should be created. There are four possibilities:

File create event	Characteristics
On dataset begin	The file will be created everytime, the dataset is started
	or restarted after a pause. This may result in a splitting
	of the current MDF 4.0 file into multiple files, as a new
	file is created for each time a dataset ist started.
On recording start	The file will be created once at logger start.
On trigger	The file will be created on a trigger and record for a
	user defined duration. These settings can be defined
	in the timelog settings ( $ ightarrow$ 12.7.3.2). This will result in a
	splitting of the current MDF 4.0 file into multiple files, as
	a new file is created for each timethe trigger is set.
On first trigger	The file will be created once, when the defined trig-
	ger is set for the first time and record for a user defined
	duration. These settings can be defined in the timelog
	settings $\rightarrow$ 12.7.3.2). Each following thime the trigger is
	set, the data will be written in the same previously cre-
	ated file. Therefore there will only be one file.

### • Maximum file size

Define the maximum file size. It is recommended not to raise the maximum file size above 2GB, as some third party evaluation tools cannot handle files, that are larger.

### • Create new file

If this box is marked active, a new file will be created, if the current file exceeds the maximum file size.

### • Data type

This dropdown menu allows you to switch the data type between float or double.



# 12.7.3.2 MDF 4.0 Timelog

# General

This tab provides general settings for the selected MDF 4.0 timelog.

General Trig	ger User			
Activ	e: 🗸			
Name	e: Timelog			
Description	n: Contains one/multiple signal group(s)			
Reference	Reference: Timelog/ATFX 01/ARCOS 1.5 - dataLog			

### Active

Allows you to activate or deactivate the selected file.

# • Name

Give a user-defined Name to the selected file.

### • Description

Give a user-defined description to the selected file.

### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



# Trigger

This tab provides settings regarding the trigger for the start and stop of the timelog. When the timelog is started, all signals contained in the signal group will be stored to the MDF 4.0 file according to their settings.

Furthermore will this trigger provoke the creation of the MDF 4.0 file, if you have choosen either "On trigger" or "On first trigger" as "File create event".

General Trigger User			
Mode:	Continuous acquisition 🔻		
Start-trigger:		Select	Remove
Stop-trigger:		Select	Remove
Pre-trigger duration:	0 s		
Post-trigger duration:	0 s		
Master:		Select	Remove

#### • Mode

Define whether you wish to continuously store data or if you want to start/stop data storage via a trigger. There are two modes to control data storage via trigger:

**Start and stop trigger** allows you to set any previously defined trigger as start and/or stop condition.

**Stop is inverted start** will store data as long as the start trigger condition is met. Once it is no longer met and a possibly set **Post-trigger duration** has run out, data storage will stop.

• Start-trigger

Define a trigger, that will start the timelog.

• Stop-trigger

Define a trigger, that will stop the timelog.

• Pre-trigger duration

Pre-trigger duration allows you to define, how long before the start trigger was set, the timelog will start.

• Post-trigger duration

Post-trigger duration allows you to define, how long after the start trigger was set, the timelog will stop.

#### User

The field "Identifier" allows you to give a user identifier to the timelog. It does not have any effect other than helping the user identify a specific timelog.



# 12.7 MDF 4.0

eneral Trigger	User		
Iden	tifier:		

# 12.7.3.3 MDF 4.0 Signal Group

## General

This tab provides general settings for the selected MDF 4.0 timelog.

General Storage	General Storage					
Active:	Active: 🗹					
Name:	Signal Group					
Description:	Signal-based measurement method					
Reference:	e: Signal Group/ATFX 01/ARCOS 1.5 - dataLog					

### Active

Allows you to activate or deactivate the selected file.

### • Name

Give a user-defined Name to the selected formula/signal.

#### • Description

Give a user-defined description to the selected formula/signal.

#### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

### Storage

This tab allows for setting regarding the storage of the contained signals inside the MDF 4.0 file.

### • Storage mode

Changes and errors excepted.



General	Storage				
	Storage mode:	Fixed	Ŧ		
	Storage rate:	1 Hz			

Storage mode	Characteristics
Fixed	The rate, at which the signals included in the "Signal Group" will be stored, is the same for all included sig- nals. You may set the rate below at "Storage Rate
From channel	The rate, at which the signals included in the "Signal Group" will be stored, is the same as each signal's source channel. This may result in a "Signal Gruop" with different storage rates for different signals, according to their sourche channel's sampling rate.
Individual	The rate, at which the signals included in the "Signal Group" will be stored, can be individually set for each signal. This may result in a "Signal Gruop" with different storage rates for different signals.

## • Storage rate

The storage rate defines how often the signals contained in this "Signal Group" will be stored.



Storage rates with decimal places will be rounded to three decimal places.

# 12.7.4 Working with Signal Groups for MDF 4.0

For filetypes intended for signal recording such as ATFX, MDF 4.0 and MDF 4.1, signals need to be included in a "Signal Group" belonging to the timelog, to which you would like the signal to be included. The signals, that are included in a "Signal Group" can then be stored.

Other than for ATFX files, MDF 4.0/4.1 files support multiple "Signal Groups" and storage modes with different characteristics and therefore allow for a more flexible storage of your data. For details ont the different storage modes please refer to ( $\rightarrow$  12.7.3.3).

This allows for example to create one "Signal Group" with a fixed storage rate of 10Hz, one that stores signals according to their channel's sampling rate and one that has an individual storage rate for each signal.



12.7 MDF 4.0

To include signals within one group, select the "Signal group" in the "Measurement task tree", click the "Components" button in the Ribbon and choose "Signal".

File	Proj	ect	Signals	A	cquisition
System	Compon	ents Fur	nctions	Import	Export C
V15.10.0	*	Signal	onfigur	ation	
Name					Σ
		N/ s	IM_5019	9999	2
	1	CAN 02			0
4 (8	5 ETI	H Interfac	es		0
	$\langle \cdot \rangle$	Internal			0
	$\langle \cdot \rangle$	Front			0
	$\langle \cdot \rangle$	openABK			0
	US				0
- 4 2		ggers			0
	-	Standard			0
	50	Level Trig			0
		Cyclic Trig			0
	- Eor	Trigger G mulas	roups		0
f0	9	ernal signa	ale		0
/ •	-	tasets	013		0
		Dataset			0
			01		0
	-		imelog		0
		N	-	Group	0



In the following window you may choose from all the available signals the ones, that you wish to include within this group and confirm by clicking "OK".

Pressure_Abs         bar         0,00000         2,00000         0         65535         1 Hz         None           Pressure_Rel         bar         -2,00000         2,00000         0         65535         1 Hz         None           MAP         bar         0,00000         3,00000         0         65535         1 Hz         None           TPS_Volt         V         -8,0000         8,0000         0         65535         1 Hz         None           Front_left         C         -50,000         200,000         0         65535         1 Hz         None           Rear_left         C         -50,000         200,000         0         65535         1 Hz         None           Exhaust_1         C         -50,000         200,000         0         65535         1 Hz         None           Exhaust_2         C         -50,000         200,000         0         65535         1 Hz         None	
Pressure_Rel         bar         -2,00000         2,00000         0         65535         1 Hz         None           MAP         bar         0,00000         3,0000         0         65535         1 Hz         None           TPS_Volt         V         -8,0000         8,0000         0         65535         1 Hz         None           Front_jeft         C         -50,000         200,000         0         65535         1 Hz         None           Front_right         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None           Exhaust_1         C         -50,000         200,000         0         65535         1 Hz         None	
MAP         bar         0,00000         3,0000         0         65535         1 Hz         None           TPS_Volt         V         -8,0000         8,0000         0         65535         1 Hz         None           Front_left         C         -50,000         200,000         0         65535         1 Hz         None           Front_right         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None           Exhaust_1         C         -50,000         200,000         0         65535         1 Hz         None	
TPS_Volt         V         -8,0000         8,0000         0         65535         1 Hz         None           Front_left         C         -50,000         200,000         0         65535         1 Hz         None           Front_left         C         -50,000         200,000         0         65535         1 Hz         None           Front_right         C         -50,000         200,000         0         65535         1 Hz         None           Rear_left         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None           Exhaust_1         C         -50,000         1200,000         0         65535         1 Hz         None	
Front_left         C         -50,000         200,000         0         65535         1 Hz         None           Front_right         C         -50,000         200,000         0         65535         1 Hz         None           Rear_left         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None           Exhaust_1         C         -50,000         1200,000         0         65535         1 Hz         None	
Front_right         C         -50,000         200,000         0         65535         1 Hz         None           Rear_left         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None           Exhaust_1         C         -50,000         1200,000         0         65535         1 Hz         None	
Rear_left         C         -50,000         200,000         0         65535         1 Hz         None           Read_right         C         -50,000         200,000         0         65535         1 Hz         None           Exhaust_1         C         -50,000         1200,000         0         65535         1 Hz         None	
Read_right         C         -50,000         200,000         0         65535         1 Hz         None           Exhaust_1         C         -50,000         1200,000         0         65535         1 Hz         None	
Exhaust_1 C -50,00 1200,00 0 65535 1 Hz None	
Exhaust_2 C -50,00 1200,00 0 65535 1 Hz None	

Even though the Plugin allows for different storage rates within one "Signal Group" in the case of the storage modes "From channel" and "Individual", technically each rate will be exported as a separate group in the loggerconfig.

That means, if you have a "Signal Group" called **"examplegroup"** with three different storage rates (1Hz, 10Hz, 100Hz), at export will be created three groups named "examplegroup\_1Hz", "examplegroup\_10Hz" and "examplegroup\_100Hz" (namemethod: signalgroup\_storagerate).

12.8 MDF 4.1



# 12.8 MDF 4.1

MDF 4.1 can largely be treated the same as MDF 4.0, with two main differences:

- MDF 4.1 supports file compression
- MDF 4.1 supports video attachments

# 12.8.1 File compression in MDF 4.1

MDF 4.1 files are by default compressed. The standard compression rate is 7-10.

For further compression MDF 4.1 offers the option "Transpose data blocks". To access this option, select the tree element "MDF 4.1 xx" and open the "File" tab in the details section.

Genera	al File		
	File ty	MDF 4.1	
	File create eve	ent: On dataset begin	-
	Maximum file s	ize: 1,953125 GB	
	Create new	file:	
Tra	anspose data blo	cks:	

# 12.8.2 Video attachments in MDF 4.1

When working with an MDF 4.1 filesystem, you can attach "Video Streams" to your timelog. As the video is only an attachment, it can not have its own triggers nor duration settings. The video-file will be attached in the \*.avi format and have the same filename as the MDF file it belongs to. The MDF file knows about the existence and automatically synchonizes the timelog and video.



# 12.8.2.1 Attaching a video

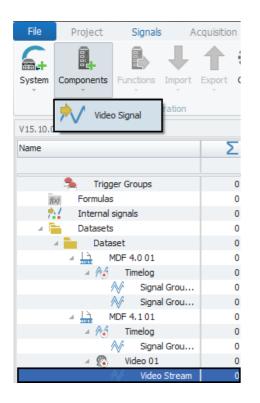
In order to attach a video, you will first need to add the "Video" component to your MDF 4.1 file.

Select the tree element "MDF 4.1 xx", click the "Components" button in the Ribbon and then choose "Video".

File	Project	Signals	Acquisition				
6.			<b>L</b> † :				
System	Components ,	Functions In	nport Export (				
V15.10.0	Video	D					
Name	Multi	ple selection	Σ				
Strigger Groups 0							
f(x) Formulas							
7	0						
- A 🖡	Datasets	;	0				
	🛛 📄 🛛 Data	set	0				
	A Press	MDF 4.0 01	0				
	🔺 🏄 Timelog						
	rou 0						
Signal Grou							
	Haras	MDF 4.101	0				
	- 🔺 🏄	Timelog	0				
		💉 🕺 Signal G	rou 0				

Once the video component has been added to your MDF file, you can choose a video signal, that you wish to attach.

Select the new tree element "Video stream", click the "Components" button in the Ribbon and then choose "Video signal".





In the resulting window you will be presented with an overview of all the available video signals. Choose the one, you wish to attach, and confirm with "OK".



It is possible to attach multiple videos by adding an additinal "Video Stream". To do so, select the "Video" tree element, click on the "Components" button in the ribbon and choose "Video Stream".

### 12.8.2.2 Details area for video in MDF 4.1

This section will explain the relevant settings for video attachments in MDF 4.1

### Video xx General

The tab "General" for the tree element "Video xx" allows you to activate or deactivate the video and give a user specific name.

General Trigger User							
Active:	V						
Name:	Video						
Description:							
Reference:	Video/MDF 4.101/ARCOS 1.5						



In the field "Name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .

# Video xx Trigger

The tab "Trigger" for the tree element "Video xx" can mainly be neglected. The only relevant field of this tabsheet is the "Mode"-field. It is read-only and shows you that your video is an attachment to the MDF-file.

General Trigger User		
Mode: Attachment	~	
Start-trigger:	Select	Remove
Stop-trigger:	Select	Remove
Pre-trigger duration: 0 s		
Post-trigger duration: 0 s		
Master:	Select	Remove

12.8 MDF 4.1



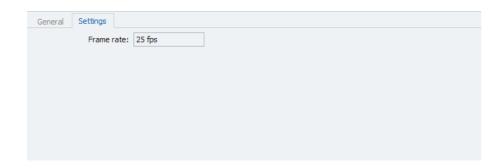
### Video xx User

The tab "User" for the tree element "Video xx" allows you to define a user-specific identifier to the video attachment. This identifier helps the user to later identify a specific video attachment.

General	rigger User
	Identifier:

# Video Stream Settings

The tab "Settings" for the tree element "Video Stream" allows you to set the framerate for the video.



# 12.9 Vector BLF / Vector ASCII / Vector ASCII compressed

These three filetypes are equal in fuctionality and differ only in the final exported file. The trace method records all the messages that arrive on the input bus (CAN, LIN, FlexRay). Regardless of the signals defined, all the messages are recorded. Filter rules can be defined to reduce the data volume. A typical trace application is the acquisition of all raw data in order to later evaluate the total traffic on the channel. Unlike most of the other methods, traces are event-oriented. This means the messages are not retrieved from the channels according to a set time pattern, but are recorded as soon as they arrive on the channel. This method accordingly has no parameter for sampling rate.

i	Including a bus tracing filetype in your datasete will produce a "Warning" message, saying that "at least one channel must be set active".							
	Symbol	Time 🔻	Туре	Source	Message			
	À	22.02.2018 10:39:04,991	WARNING	Bus trace	At least one channel must be set active			
		se refer to the s nnel for tracing		Bus trace	e" ( $ ightarrow$ 12.9.4.3), in order	to activate a		
The function trigger trace, which allows to trace all activity of a trig is available for the following dataset methods:								
	Vector ASCII							
	lt is n	<b>ot available</b> fo	r:					
	Vector BLF							

# 12.9.1 Tree elements for bus/trigger tracing

Including a bus tracing filetype in your dataset will add various new child elements to your tree element "Dataset":

Vector BLF / Vector ASCII / Vector ASCII compressed xx
 This element represents the bus tracing file, which will later be included in your exported dataset. You may add multiple files of the same filetype.

🔺 🚞 Datasets						
A Dataset 01	0					
🔺 🛁 🛛 Vector ASCII 01						
🚓 Trigger trace	0					
A Bus trace 01	0					
CAN 01	0					
😄 CAN 02	0					
🗧 Front	0					
🗧 Internal	0					
a openABK	0					

Changes and errors excepted.

# • Trigger trace

This element represents the "Trigger trace" for recording trigger activity.

Datasets					
A Dataset 01					
🔺 💂 🛛 Vector ASCII 01					
	Trigger trace	0			
A 12 0	Bus trace 01	0			
3	CAN 01	0			
	CAN 02	0			
3	Front	0			
	Internal	0			
	openABK	0			

### • Bus trace

This element represents the "Bus trace" for recording all the traffic on a selected bus channel.

(AETE(

🔺 🚞 Datasets						
A Dataset 01	0					
🔺 🛁 🛛 Vector ASCII 01						
👧 Trigger trace	0					
A Bus trace 01	0					
CAN 01	0					
CAN 02	0					
🗧 Front	0					
😸 Internal	0					
apenABK	0					

### • Bus channels available for tracing

As child elements to the tree element "Bus trace" will appear all the Bus channels which are currently available for tracing.

🔺 늘 🛛 Datasets					
A Dataset 01					
🔺 📄 🛛 Vector ASCII 01					
👧 Trigger trace	0				
A Bus trace 01	0				
🗧 CAN 01	0				
😸 CAN 02	0				
S Front	0				
🗧 Internal	0				
i openABK	0				

# 12.9.2 Grid area for trigger tracing

If the "Trigger trace" is selected in the Measurement task tree, the grid area will show an overview of the triggers available for tracing.

At least one channel must be marked active for tracing, by setting active the setting "Trace trigger".

V18.10.00.20784 Beta=			Name	Active	Description	Trace trigger
Name	Σ	۴				
			Standard trigger 01	~	Recorded trigger	V
4 🛖 ARCOS 1.5	0		Standard trigger 02	~	Recorded trigger	×
CAN interfaces	0		Cyclic trigger 01	~	Recorded trigger	
<ul> <li>ETH interfaces</li> </ul>	0	I	Cyclic trigger 02		Recorded trigger	¥
USB USB	0		Trigger group 01	~	Recorded trigger	
1 Internal signals	0		trig_display		Recorded trigger	
f(x) Formulas	0					
Triggers	0					
A Datasets	0					
Dataset 01	0					
🔺 📄 🛛 Vector ASCII 01	0					
🚗 Trigger trace	0					
Bus trace 01	0					
GAN 01	0					
S CAN 02	0					
S Front	0		terms in the			
a Internal	0					
g openABK	0		Advent 11			

# 12.9.3 Grid area for bus tracing

If the "Bus trace" is selected in the Measurement task tree, the grid area will show an overview of the Bus channels available for tracing.

At least one channel must be marked active for tracing, by setting active the setting "Trace channel".

V15.10.00.15774 Beta				Name	Active	Description		Trace channel
Name	Σ		٩					
	-	•	•	CAN 01	~	Bus trace channel		~
FlexRay 01	0			CAN 02	~	Bus trace channel		
∡ m ETH interfaces	0			FlexRay 01	~	Bus trace channel		
<li>Internal</li>	0							
	0							
openABK	0							
USB	0							
🔺 🚍 Triggers	0							
Standard triggers	0							
Eevel triggers	0							
Cyclic triggers	0							
🛛 🛸 Trigger groups	0							
🛸 Trigger group 01	0							
f(x) Formulas	0							
nternal signals	0							
🛛 🧎 🔁 Datasets	0			and the last				
A Dataset	0							
Vector ASCII compr	0			Dart trapper			. Select	
🔺 📴 🛛 Bus trace	0			Day Support			Ann	
S CAN 01	0							
CAN 02	0			and a state of the				
FlexRay 01	0			Post-tragger duration:	2.4			

If an ID Filter has been added for a Bus trace channel, selecting this Bus trace channel in the tree will show an overview of the existing ID Filters in the grid area. For information on working with ID Filters for Bus trace, please refer to the chapter **Bus trace ID Filter** ( $\rightarrow$ 12.9.5).

## 12.9.4 Details area for bus/trigger tracing

The details area contains settings for the behaviour of your bus tracing file (Vector BLF / Vector ASCII / Vector ASCII compressed), the "Bus trace" component or a tracable Bus channel.

### 12.9.4.1 Bus tracing file

#### General

This tab provides general settings for the selected bus tracing file.

General File	
Active:	V
Name:	Vector BLF 01
Description:	File for saving acquisition data
Reference:	Vector BLF 01/ARCOS 1.5 - dataLog

### • Active

Allows you to activate or deactivate the selected file.

• Name

Give a user-defined Name to the selected file.

### • Description

Give a user-defined description to the selected file.

• Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



In the field "Name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .

# File

This tab provides settings regarding the creation of the file.

General File					
File type:	BLF				
File create event:	On dataset begin	Ŧ	r i		
Maximum file size:	1,953125 GB				
Create new file:					
Timestamp:	Fileformat default	Ŧ	,		

## • File type

Tells you the type of the created file.

### • File create event

Define, when the bus tracing file should be created. There are four possibilities:

File create event	Characteristics
On dataset begin	The file will be created everytime, the dataset is started or restarted after a pause. This may result in a splitting of the current bus tracing file into multiple files, as a new file is created for each time a dataset ist started.
On recording start	The file will be created once at logger start.
On trigger	The file will be created on a trigger and record for a user defined duration. These settings can be defined in the "Bus trace" settings ( $\rightarrow$ 12.9.4.3). This will result in a splitting of the current bus tracing file into multiple files, as a new file is created for each timethe trigger is set.
On first trigger	The file will be created once, when the defined trigger is set for the first time and record for a user defined du- ration. These settings can be defined in the "Bus trace" settings $\rightarrow$ 12.9.4.3). Each following thime the trigger is set, the data will be written in the same previously cre- ated file. Therefore there will only be one file.

### • Maximum file size

Define the maximum file size. It is recommended not to raise the maximum file size above 2GB, as some third party evaluation tools cannot handle files, that are larger.

### • Create new file

If this box is marked active, a new file will be created, if the current file exceeds the maximum file size.

# • Timestamp

This dropdown menu allows you to set the format of the timestamp for the file.

Changes and errors excepted.

# 12.9.4.2 Trigger trace

# General

This tab provides general settings for the selected "Trigger trace".

General	Setting	S
	Active:	V
	Name:	Cyclic trigger 01
Des	cription:	Recorded trigger
Ref	ference:	Cyclic trigger 01/Vector ASCII 01/ARCOS 1.5

## Active

Allows you to activate or deactivate the selected file.

# • Name

Give a user-defined Name to the selected file.

### • Description

Give a user-defined description to the selected file.

### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

# Settings

This tab provides settings for a trigger, that is selected in the grid area.

General Settings		
Trace trigger:	<b>~</b>	
Message mode:	Text	*
Channel number:	16	
CAN ID:	std 0 h	h

# • Trace trigger

Set active in order to trace this trigger.

## • Message mode

Select the type of message written to the trace file.

# • Channel number

If the message mode has been set to "Virtual message", this field allows you to define the virtual channel number to identify the virtual message.

# CAN ID

If the message mode has been set to "Virtual message", this field allows you to define the virtual CAN ID to identify the trigger message.

# 12.9.4.3 Bus trace

# General

This tab provides general settings for the selected "Bus trace".

Active	er Extended
Name	: Bus trace
Description	: Contains one/multiple bus trace(s)
Reference	Bus trace/Vector BLF 01/ARCOS 1.5 - dataLog

### Active

Allows you to activate or deactivate the selected file.

# • Name

Give a user-defined Name to the selected file.

### • Description

Give a user-defined description to the selected file.

### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

# Trigger

This tab provides settings regarding the trigger for the start and stop of the "Bus trace". When the "Bus trace" is started, all traffic on the channel will be stored to the bus tracing file.

Furthermore will this trigger provoke the creation of the bus tracing file, if you have choosen either "On trigger" or "On first trigger" as "File create event".

General Trigger User			
Mode:	Continuous acquisition 💌		
Start-trigger:		Select	Remove
Stop-trigger:		Select	Remove
Pre-trigger duration:	0 s		
Post-trigger duration:	0 s		
Master:		Select	Remove

#### • Mode

Define whether you wish to continuously store data or if you want to start/stop data storage via a trigger. There are two modes to control data storage via trigger:

**Start and stop trigger** allows you to set any previously defined trigger as start and/or stop condition.

**Stop is inverted start** will store data as long as the start trigger condition is met. Once it is no longer met and a possibly set **Post-trigger duration** has run out, data storage will stop.

• Start-trigger

Define a trigger, that will start the "Bus trace".

• Stop-trigger

Define a trigger, that will stop the "Bus trace".

• Pre-trigger duration

Pre-trigger duration allows you to define, how long before the start trigger was set, the "Bus trace" will start.

#### • Post-trigger duration

Post-trigger duration allows you to define, how long after the start trigger was set, the "Bus trace" will stop.

### Extended

This tab provides extended settings for "Bus trace".

• Include internal events

Define whether the occurrance of internal events should be stored in the trace data.

Changes and errors excepted.



General	Trigger	Extended
Includ	de internal ev	ents: 🗸
Include	all trigger ev	ents: 🗸
	Iden	tifier:

### • Include all trigger events

Define whether all trigger events should be stored in the trace data.

• Identifier

The field Identifier allows you to give a user identifier to the Bus trace. It does not have any effect other than helping the user identifiy a specific Bus trace.

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#### 12.9.4.4 Tracable Bus channel

#### Settings

General Settings				
Trace channel:	Trace channel: 🗹			
Default filter action:	Block all, except specified ID or ID range			

### • Trace channel

Mark this box activ in order to trace this channel.

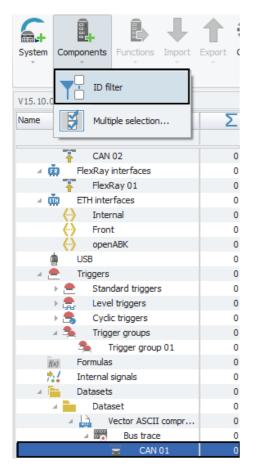
#### • Default filter action

Define the default action for an ID Filter if it has been defined. For information on working with ID Filters for Bus trace, please refer to the chapter **Bus trace ID Filter**  $(\rightarrow 12.9.5)$ .

# 12.9.5 Bus trace ID Filter

For "Bus trace" it is possible to specify one or more "ID Filters". Such it is possible to specify a singe ID or an ID range for a Bus and filter incoming traffic on that bus accrodingly. It is possible to either block all traffic except the specified ID/ID range or to pass all traffic except the specified ID/ID range.

In order to specify an "ID Filter", you will first need to add the "ID Filter" component to the desired Bus channel. To do so, select the desired Bus trace channel in the tree, click on the "Components" button in the Ribbon and then choose "ID Filter". The new "ID Filter"



will appear in the grid area of the channel it belongs to. Select the filter and navigate to the "Filter settings" tab in the details area. Here you will be able to specify the settings for the filter.

General	Filter settings	
	Mode:	Specific ID 🔹
	CAN ID:	std 0 h
	Stopping ID:	std 0 h

# • Mode

Specify whether a specific ID or a range of IDs should be used for the filter.

- CAN/LIN ID (For CAN and LIN channels only) Allows you to define the specific/starting ID of your filter.
- Frame ID (For FlexRay channels only) Allows you to define the specific/starting ID of your filter.
- Stopping ID

If using a range of IDs, this field allows you to define the stopping ID.

- Cycle repetition (For FlexRay channels only) Allows you to define cycle repetition of the frame.
- Base cycle (For FlexRay channels only) Allows you to define Base cycle of the frame.



All numbers in this tab can be entered in binary, decimal or hexadecimal format. Furthermore can the ID mode for the CAN ID switched from standard (0-7FF) to extended (0-1FFFFFF).

Now the "ID Filter" has been specified and you will be able to define what the default action for filters on the traced Bus channel should be. To do so, select the respective Bus trace channel in the tree and navigate to the "Settings" tab in the details area. Here you will be able to choose between to default actions for filters on this channel.

General	Settings	
	Trace channel:	V
Def	ault filter action:	<b>*</b>
		Block all, except specified ID or ID range
		Pass all, except specified ID or ID range

- Block all, except specified ID or ID range will block out and ignore all incoming traffic on the channel except the specified ID/ID range.
- Pass all, except specified ID or ID range will store all incoming traffic on this channel except the spdecified ID/ID range, which will be blocked and ignored.



It is possible to add and specify multiple ID Filters for one Bus trace channel.

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# 12.10 PCAP

PCAP is a filetype for message orientated rawdate recordings on ethernet channels. The trace method records all the messages that arrive on the ethernet channel. Regardless of the signals defined, all the messages are recorded. Filter rules can be defined to reduce the data volume. A typical trace application is the acquisition of all raw data in order to later evaluate the total traffic on the channel. Unlike most of the other methods, traces are event-oriented. This means the messages are not retrieved from the channels according to a set time pattern, but are recorded as soon as they arrive on the channel. This method accordingly has no parameter for sampling rate.

Symbol	Time 💌	Туре	Source	Message
A	22.02.2018 11:41:50,708	WARNING	ETH trace	At least one channel must be set active

# 12.10.1 Tree elements for PCAP

Including PCAP in your dataset will add various new child elements to your tree element "Dataset":

• PCAP

This element represents the PCAP file, which will later be included in your exported dataset. You may add multiple files of the same filetype.

🔺 🚞 🛛 Datasets		0
🔺 📩 Dataset		0
🔺 📄 🛛 PCAP		0
4 😪 E	TH trace	0
8	Internal	0
8	Front	0
8	openABK	0

# • ETH trace

This element represents the "ETH trace" for recording all the traffic on a selected ethernet channel.

🔺 🚞 🛛 Datasets	0
🔺 🧰 Dataset	0
🔺 💂 🛛 PCAP	0
🔺 😪 🛛 ETH trace	0
🗧 Internal	0
🗧 Front	0
a openABK	0



### • ETH channels available for tracing

As child elements to the tree element "ETH trace" will appear all the ETH channels which are currently available for tracing.

🔺 🚞 🛛 Datasets	0
A Dataset	0
🔺 💂 🛛 PCAP	0
🔺 🚷 🛛 ETH trace	0
😸 Internal	0
🗧 Front	0
🥃 openABK	0

# 12.10.2 Grid area for PCAP

If the "ETH trace" is selected in the Measurement task tree, the grid area will show an overview of the ethernet channels available for tracing.

At least one channel must be marked active for tracing, by ticking the checkbox labeled "Trace channel".

V15.10.00.15774 Beta			Name	Active	Description	Trace channel
Name	Σ	۴				
			Internal	4	ETH trace channel	
FlexRay 01	0	Þ	Front		ETH trace channel	~
<ul> <li>ETH interfaces</li> </ul>	0		openABK	~	ETH trace channel	
<ul> <li>Internal</li> </ul>	0					
	0					
openABK	0					
i USB	0					
🛛 🚔 Triggers	0					
Standard triggers	0					
Eevel triggers	0					
Equation Cyclic triggers	0					
🛛 🏂 🛛 Trigger groups	0					
Trigger group 01	0					
(x) Formulas	0					
http://internal.signals	0					
Datasets	0		terms in the second			
A Dataset	0		Tax danat 12			
PCAP	0		Two Parriel 17			
🛛 🎸 ETH trace	0					
a Internal	0					
S Front	0					
apenABK	0					

# 12.10.3 Details area for PCAP

The details area contains settings for the behaviour of your PCAP file or "ETH trace".

# 12.10.3.1 PCAP file

# General

This tab provides general settings for the selected Eth tracing file.

General File Active:	
Name:	PCAP
Description:	File for saving ETH trace data
Reference:	PCAP/ARCOS 1.5 - dataLog





### • Active

Allows you to activate or deactivate the selected file.

### • Name

Give a user-defined Name to the selected file.

#### • Description

Give a user-defined description to the selected file.

#### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



In the field "Name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .

# File

This tab provides settings regarding the creation of the file.

General File		
File type:	PCAP	
File create event:	On dataset begin	Ŧ
Maximum file size:	1,953125 GB	
Create new file:		
Timestamp:	Fileformat default	-

• File type

Tells you the type of the created file.

• File create event

Define, when the PCAP file should be created. There are four possibilities:



File create event	Characteristics
On dataset begin	The file will be created everytime, the dataset is started or restarted after a pause. This may result in a splitting of the current PCAP file into multiple files, as a new file is created for each time a dataset ist started.
On recording start	The file will be created once at logger start.
On trigger	The file will be created on a trigger and record for a user defined duration. These settings can be defined in the "ETH trace" settings ( $\rightarrow$ 12.10.3.2). This will result in a splitting of the current Eth tracing file into multiple files, as a new file is created for each timethe trigger is set.
On first trigger	The file will be created once, when the defined trigger is set for the first time and record for a user defined du- ration. These settings can be defined in the "ETH trace" settings $\rightarrow$ 12.10.3.2). Each following thime the trigger is set, the data will be written in the same previously created file. Therefore there will only be one file.

## • Maximum file size

Define the maximum file size. It is recommended not to raise the maximum file size above 2GB, as some third party analysis tools cannot handle files, that are larger.

## • Create new file

If this box is marked active, a new file will be created, if the current file exceeds the maximum file size.

# • Timestamp

This dropdown menu allows you to set the format of the timestamp for the file.

# 12.10.3.2 Eth trace

### General

This tab provides general settings for the selected "ETH trace".

General T	Trigger	Extended
Ad	ctive:	
N	lame:	ETH trace
Descrip	otion:	Contains one/multiple ETH trace(s)
Refere	ence:	ETH trace/PCAP/ARCOS 1.5 - dataLog

# • Active

Allows you to activate or deactivate the selected file.



### • Name

Give a user-defined Name to the selected file.

# • Description

Give a user-defined description to the selected file.

## • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

## Trigger

This tab provides settings regarding the trigger for the start and stop of the "ETH trace". When the "ETH trace" is started, all traffic on the channel will be stored to the PCAP file. Furthermore will this trigger provoke the creation of the PCAP file, if you have choosen either "On trigger" or "On first trigger" as "File create event".

General Trigger User			
Mode:	Continuous acquisition 🔻		
Start-trigger:		Select	Remove
Stop-trigger:		Select	Remove
Pre-trigger duration:	0 s		
Post-trigger duration:	0 s		
Master:		Select	Remove

### • Mode

Define whether you wish to continuously store data or if you want to start/stop data storage via a trigger. There are two modes to control data storage via trigger:

**Start and stop trigger** allows you to set any previously defined trigger as start and/or stop condition.

**Stop is inverted start** will store data as long as the start trigger condition is met. Once it is no longer met and a possibly set **Post-trigger duration** has run out, data storage will stop.

• Start-trigger

Define a trigger, that will start the "ETH trace".

# • Stop-trigger

Define a trigger, that will stop the "ETH trace".

• Pre-trigger duration

Pre-trigger duration allows you to define, how long before the start trigger was set, the "ETH trace" will start.

Changes and errors excepted.



# • Post-trigger duration

Post-trigger duration allows you to define, how long after the start trigger was set, the "ETH trace" will stop.



# Extended

This tab provides extended settings for "ETH trace".

General Trigger Extended	General
Indude internal events: 🖌	Include
Indude all trigger events: 🖌	Include a
Identifier:	

• Include internal events

Define whether the occurrance of internal events should be stored in the trace data.

- Include all trigger events Define whether all trigger events should be stored in the trace data.
- Identifier

The field Identifier allows you to give a user identifier to the ETH trace. It does not have any effect other than helping the user identifiy a specific ETH trace.



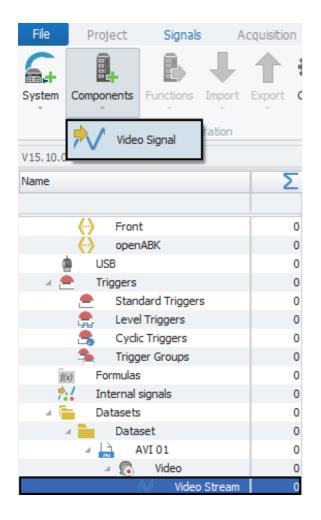
# 12.11 AVI

The "AVI" filetype is meant for recording of video streams. For each AVI file, that you add to your dataset you can only record one video stream.

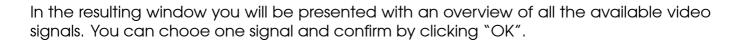
# 12.11.1 Including a video signal in the Video Stream

In order to store a "Video Stream", you will need to include a video signal in your "Video Stream".

To do so, select the tree element "Video Stream", click the "Compontents" button in the Ribbon and choose "Video Signal".



12.11 AVI



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	Name	Unit	Phys Min	Phys Max	Sensor Min	Sensor Max	Sampling rate	Special function
٩								
Þ	Video signal 01						1 Hz	None
	Video signal 02						1 Hz	None
	Video signal 03						1 Hz	None
	Video signal 04						1 Hz	None
	Video signal 05						1 Hz	None

# 12.11.2 Tree elements for AVI

Including the "AVI" filetype in your dataset will add three new child elements to your tree element "Dataset":

• AVI xx

This element represents the AVI file, which will later be included in your exported dataset. You may add multiple files of the same filetype.

🔺 🚞 🛛 Datasets	0
A Dataset	0
🔺 📄 🛛 AVI 01	0
🛛 🕵 Video	0
N/ Video Stream	0

### • Video

Represents the video element in your AVI file. It tells you, that the type of signal, which can be stored, is a video signal.



### • Video Stream

This element represents the video signal which will be stored.

🔺 🚞 🛛 Datasets	0
🔺 🧰 Dataset	0
AVI 01	0
🔺 🕵 Video	0
📈 🛛 Video Stream	0

Changes and errors excepted.

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# 12.11.3 Grid area for AVI

If the "Video Stream" is selected in the Measurement task tree, and a video signal has already been included in the "Video Stream", the grid area will show the video signal which has been included in the "Video Stream".

1	1	~		1 Hz
	1		1 🗾 🖬	1 🗾 🖌

### 12.11.4 Details area for AVI

The details area contains settings for the behaviour of your AVI file, Video element or Video Stream.

## 12.11.4.1 AVI File

#### General

This tab provides general settings for the selected AVI file.

General	File						
	Active:	V					
	Name:	AVI 01					
Desc	cription:	File for saving video data					
Ref	erence:	AVI 01/ARCOS 1.5 - dataLog					

### Active

Allows you to activate or deactivate the selected file.

### • Name

Give a user-defined Name to the selected file.

### • Description

Give a user-defined description to the selected file.



#### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



In the field "Name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .

#### File

This tab provides settings regarding the creation of the file.

General File	
File type:	AVI
File create event:	On dataset begin 👻
Maximum file size:	1,953125 GB
Create new file:	

#### • File type

Tells you the type of the created file.

#### • File create event

Define, when the AVI file should be created. There are four possibilities:

File create event	Characteristics
On dataset begin	The file will be created everytime, the dataset is started or restarted after a pause. This may result in a splitting of the current AVI file into multiple files, as a new file is
On recording start	created for each time a dataset ist started.
On recording start On trigger	The file will be created once at logger start. The file will be created on a trigger and record for a user defined duration. These settings can be defined in the timelog settings ( $\rightarrow$ 12.11.4.2). This will result in a splitting of the current AVI file into multiple files, as a new file is created for each timethe trigger is set.
On first trigger	The file will be created once, when the defined trig- ger is set for the first time and record for a user defined duration. These settings can be defined in the timelog settings $\rightarrow$ 12.11.4.2). Each following thime the trigger is set, the data will be written in the same previously cre- ated file. Therefore there will only be one file.



#### • Maximum file size

Define the maximum file size. It is recommended not to raise the maximum file size above 2GB, as some third party evaluation tools cannot handle files, that are larger.

#### • Create new file

If this box is marked active, a new file will be created, if the current file exceeds the maximum file size.

# 12.11.4.2 Video

# General

This tab provides general settings for the selected Video element.

General Trig	iger User
Activ	ve: 🗹
Nam	e: Video
Descriptio	n:
Reference	e: Video/AVI 01/ARCOS 1.5 - dataLog

# • Active

Allows you to activate or deactivate the selected file.

#### • Name

Give a user-defined Name to the selected file.

#### • Description

Give a user-defined description to the selected file.

#### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



# Trigger

This tab provides settings regarding the trigger for the start and stop of the Video element. When the Video element is started, the "Video Stream" will be stored to the AVI file. Furthermore will this trigger provoke the creation of the AVI file, if you have choosen either "On trigger" or "On first trigger" as "File create event".

General Trigger User			
Mode:	Continuous acquisition 🔻		
Start-trigger:		Select	Remove
Stop-trigger:		Select	Remove
Pre-trigger duration:	0 s		
Post-trigger duration:	0 s		
Master:		Select	Remove

#### • Mode

Define whether you wish to continuously store data or if you want to start/stop data storage via a trigger. There are two modes to control data storage via trigger:

**Start and stop trigger** allows you to set any previously defined trigger as start and/or stop condition.

**Stop is inverted start** will store data as long as the start trigger condition is met. Once it is no longer met and a possibly set **Post-trigger duration** has run out, data storage will stop.

# • Start-trigger

Define a trigger, that will start the Video element.

# • Stop-trigger

Define a trigger, that will stop the Video element.

#### • Pre-trigger duration

Pre-trigger duration allows you to define, how long before the start trigger was set, the Video element will start.

# • Post-trigger duration

Post-trigger duration allows you to define, how long after the start trigger was set, the Video element will stop.

12.11 AVI



#### User

The field "Identifier" allows you to give a user identifier to the timelog. It does not have any effect other than helping the user identify a specific timelog.

General Trigger <b>User</b>		
Identifier:		

# 12.11.4.3 Video Stream

# General

This tab provides general settings for the selected "Video Stream".

General	Settings	3
	Active:	
	Name:	Video Stream
Desc	ription:	Video stream to be stored
Refe	erence:	Video Stream/AVI 01/ARCOS 1.5 - dataLog

# • Active

Allows you to activate or deactivate the "Video Stream".

• Name

Give a user-defined Name to the selected "Video Stream".

# • Description

Give a user-defined description to the selected "Video Stream".

• Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



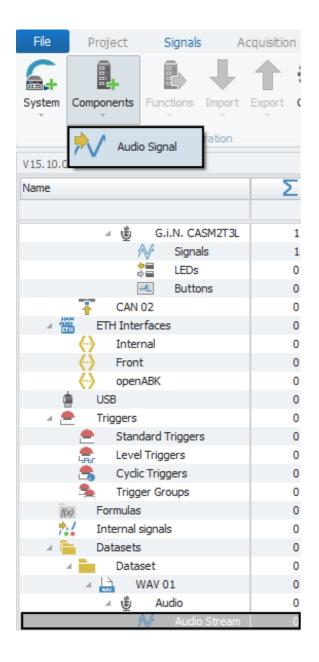
# 12.12 WAV

The "WAV" filetype is meant for recording of audio streams. For each WAV file, that you add to your dataset you can only record one audio stream.

# 12.12.1 Including an audio signal in the audio Stream

In order to store an "Audio Stream", you will need to include a audio signal in your "Audio Stream".

To do so, select the tree element "Audio Stream", click the "Compontents" button in the Ribbon and choose "Audio Signal".





In the resulting window you will be presented with an overview of all the available audio signals. You can chooe one signal and confirm by clicking "OK".

Audio signal 01         -32768         32767         -32768         32767         1 Hz         None           Audio signal 02         -32768         32767         -32768         32767         1 Hz         None	
Audio signal 01 -32768 32767 -32768 32767 1 Hz None	
Audio signal 02 -32768 32767 -32768 32767 1 Hz None	

# 12.12.2 Tree elements for WAV

Including the "WAV" filetype in your dataset will add three new child elements to your tree element "Dataset":

• WAV xx

This element represents the WAV file, which will later be included in your exported dataset. You may add multiple files of the same filetype.



#### • Audio

Represents the audio element in your WAV file. It tells you, that the type of signal, which can be stored, is an audio signal.



#### • Audio Stream

This element represents the audio signal which will be stored.

🛛 🚞 🛛 Datasets	0
🛛 🧰 Dataset	0
A 🔄 WAV 01	0
⊿ 🦉 Audio	0
Audio Stream	1

Changes and errors excepted.



# 12.12.3 Grid area for WAV

If the "audio Stream" is selected in the Measurement task tree, and a audio signal has already been included in the "audio Stream", the grid area will show the audio signal which has been included in the "audio Stream".

V15.10.00.14946 Beta				Channel		Index	Active	Unit	Sampling rate
Name	Σ		۴						
		•	Þ	Audio signal 01		1	<b>Z</b>		1 Hz
Sa LEDs	0								
-L Buttons	0								
ETH Interfaces	0								
<li>Internal</li>	0								
💮 Front	0								
openABK	0								
i USB	0								
🛛 🚔 Triggers	0								
🚔 Standard Triggers	0								
🚍 Level Triggers	0								
🗂 Cyclic Triggers	0								
🛸 Trigger Groups	0								
f(x) Formulas	0		. *						
📩 Internal signals	0								
🛛 🚞 🛛 Datasets	0								
A Dataset	0								
4 🔛 WAV 01	0			Description	Auto april 1		6		
🛛 💆 🛛 Audio	0			and the second					
Audio Stream	1								

# 12.12.4 Details area for WAV

The details area contains settings for the behaviour of your WAV file. General

This tab provides general settings for the selected WAV file.

General	File	
	Active:	
	Name:	WAV 01
Desc	ription:	File for saving audio data
Refe	erence:	WAV 01/ARCOS 1.5 - dataLog

# Active

Allows you to activate or deactivate the selected file.

• Name

Give a user-defined Name to the selected file.

# • Description

Give a user-defined description to the selected file.



#### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



In the field "Name" project parameters can be used as variables. For more information please refer to ( $\rightarrow$ 5.6).

#### File

This tab tells you the filetype of your file.

General File	
	File type: WAV

12.13 GPX



# 12.13 GPX

The "GPX" filetype is meant for GPS Tracking.

# 12.13.1 Assigning GPS signals

Other than for other filetypes, when working with GPX, you will not be able to choose the signals you wish to store from a list of available signals, but you will need to assign a GPS task (latitude, longitude or altitude) to a signal. That means, that technically any signal can be used as GPS signal.

For instructions on assignig GPS tasks please refer to ( $\rightarrow$  6.14.2.1).

One GPS task may only be assigned to one signal. Use the **"Check"** button in the Ribbon to verify, that GPS tasks are uniquely assigned. If a GPS task is multiply assigned, navigate to the "Format" tab of the wrongly assigned signal and deassign the GPS task.

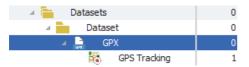
Exporting a configuration will also check your system for validity and inform you, if you have multiply assigned GPS tasks.

#### 12.13.2 Tree elements for GPX

Including the "GPX" filetype in your dataset will add two new child elements to your tree element "Dataset":

#### • GPX

This element represents the GPX file, which will later be included in your exported dataset.



#### • GPS Tracking

Represents the GPS signals you are tracking





#### 12.13.3 Grid area for GPX

The grid area is not used for configuration of GPX. Instead signal selection in this case works via assignation of GPS tasks. Please refer to ( $\rightarrow$  6.14.2.1).

#### 12.13.4 Details area for GPX

The details area contains settings for the behaviour of your GPX file and "GPS Tracking".

#### 12.13.4.1 GPX File

#### General

This tab provides general settings for the selected GPX file.

General	File	
4	Active:	
, i	Name:	GPX
Descri	iption:	File for saving position tracking data
Refer	rence:	GPX/ARCOS 1.5 - dataLog
		$\Box_{s}$

#### Active

Allows you to activate or deactivate the selected file.

#### • Name

Give a user-defined Name to the selected file.

#### • Description

Give a user-defined description to the selected file.

#### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



In the field "Name" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .





#### File

This tab tells you the filetype of your file.

General File	
File	type: GPX

# 12.13.4.2 GPS Tracking

#### General

This tab provides general settings for GPS Tracking.

General Trig	jger Storage
Activ	ve: 🗸
Nam	ne: GPS Tracking
Descriptio	n:
Reference	GPS Tracking/GPX/ARCOS 1.5 - dataLog

# Active

Allows you to activate or deactivate "GPS Tracking".

• Name

Give a user-defined Name to your "GPS Tracking".

#### • Description

Give a user-defined description to your "GPS Tracking".

#### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.



# Trigger

This tab provides settings regarding the trigger for the start and stop of the "GPS Tracking". When the "GPS Tracking" is started, all activated signals with GPS task will be stored to the GPX file.

Mode:       Continuous acquisition         Start-trigger:       Select       Remove         Stop-trigger:       Select       Remove         Pre-trigger duration:       0 s       Select       Select	General Trigger Stor	age		
Stop-trigger:     Select     Remove       Pre-trigger duration:     0 s	Mode:	Continuous acquisition 🔻		
Pre-trigger duration: 0 s	Start-trigger:		Select	Remove
	Stop-trigger:		Select	Remove
Post-trigger duration: 0 s	Pre-trigger duration:	0 s		
	Post-trigger duration:	0 s		

#### • Mode

Define whether you wish to continuously store data or if you want to start/stop data storage via a trigger. There are two modes to control data storage via trigger:

**Start and stop trigger** allows you to set any previously defined trigger as start and/or stop condition.

**Stop is inverted start** will store data as long as the start trigger condition is met. Once it is no longer met and a possibly set **Post-trigger duration** has run out, data storage will stop.

# • Start-trigger

Define a trigger, that will start "GPS Tracking".

# • Stop-trigger

Define a trigger, that will stop "GPS Tracking".

# • Pre-trigger duration

Pre-trigger duration allows you to define, how long before the start trigger was set, "GPS Tracking" will start.

# • Post-trigger duration

Post-trigger duration allows you to define, how long after the start trigger was set, "GPS Tracking" will stop.







# Storage

This tab allows you to set the storage rate for "GPS Tracking"

Genera	Trigger	Storage	
	Storage r	ate: 4 Hz	



Storage rates with decimal places will be rounded to three decimal places.

# 12.14 CAETEC binary (Classings / Min/Max Values)

The "CAETEC binary" filetype allows for classing of signals. Classings are processes for counting values or sequences (such as cycles) of signals. The standard procedure is to take the range in which the counted events are expected and divide this into so-called classes. Any values lying above the highest or below the lowest class are generally ignored (no open-border classes). Please refer to the chapter "Classing methods" ( $\rightarrow$ 12.16).

The methods fundamentally differ in their counting strategies (for example, when levels are crossed, when a class is reached, cycle amplitudes and so on), and they are standardized. Which particular standard was applied in the design of each method is explained in the chapters on the different classing methods.

A signal can be used in several classing processes simultaneously.

Some methods can be applied with different numbers of signals. This is what is referred to as the dimension of the particular classing. 1D, 2D, 3D specify how many signals are joined in a class (joint classing). When joined, the classes of the signals form a matrix. Counting is always performed in the matrix element in which the counting conditions for all the involved signals are met by the same sampling instance.

# 12.14.1 Tree elements for CAETEC binary

Including a "CAETEC binary" file in your dataset will add one new child element called "CAETEC binary xx" to your tree element "Dataset".

Multiple "CAETEC binary" files can be added to your dataset. They will be labeled equally and the counter will be raised by one for each new file. This may be necessary, if multiple classings should be included in the dataset, as each "CAETEC binary" file can only contain one classing.

🔺 🚞 🛛 Datasets	0
Jataset	0
CAETEC binary 01	0



# 12.14.2 Details area for CAETEC binary

The details area contains settings regarding the "CAETEC binary" file. General

This tab provides general settings for the selected CAETEC binary file.

General	File	
	Active:	
	Name:	CAETEC binary 01
Desc	ription:	File for saving classification data
		······································
Refi	erence:	CAETEC binary 01/ARCOS 1.5

Active

Allows you to activate or deactivate the selected file.

• Name

Give a user-defined Name to the selected formula/signal.

• Description

Give a user-defined description to the selected formula/signal.

• Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

#### File

This tab provides settings regarding the creation of the file.

Genera	al File		
	File type: CAETEC binary	/	
	Hold last value: Until end of da	taset 🔹	

• File type

Tells you the type of the created file.

• Hold last value

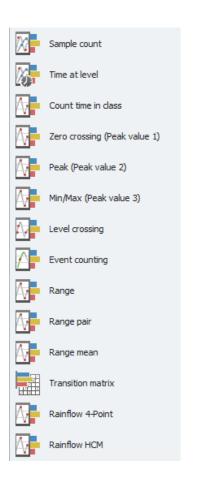
Specify, for how long the last value of the signal will be hold.

# 12.14.3 Adding a classing

In order to add a classing, select the "CAETEC binary" or "CAETEC ASCII" file, which should contain the classing, in the measurement task tree.

System	Components	Functions	Import	t Export	Chec
		Config	uration		
V15.10.0	0.16682 RC				
Name					Σ
4 💼	ARCOS 1.5				10
) → ¢	CAN inte	rfaces			10
⊨ Þ ¢	ETH inter	faces			0
ą	USB				0
► E	Triggers				0
ft	Ø Formulas				0
7.	🚺 Internal :	signals			0
	Datasets				0
	🖌 📄 Data	set			0
	📄 o	AETEC ASC	II 01		0

Then click the "Components" button in the Ribbon and choose the desired classing method.



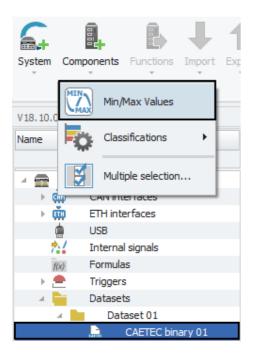
Once you have added a classing, you may now proceed to configure this classing. Please refer to the chapter "Classing methods" ( $\rightarrow$ 12.16) for instructions.

#### 12.14.4 Min/Max Values

The "Min/Max Values" function of the CAETEC binary method allows you to store the minimum and maximum incoming values of signals.

#### 12.14.4.1 Adding Min/Max Values and selecting signals

In order to store the min/max values of a signal, you will first need to add a "Min/Max Values" group to your CAETEC binary file. To do so, select the CAETEC binary file in the measurement task tree, click the "Components" button in the Ribbon and then select "Min/Max Values".



Once the "Min/Max Values" group has been added, the signals whose min/max values should be stored may be selected. To do so, select the tree element "Min/Max Values xx", click the "Components" button in the Ribbon and choose "Signal".

AETEC

System Cor	mponents Functions Import Exp
· ·	bnfiguration
V18.10.0	Signal
Name	
🔺 💼 🛛 A	RCOS 1.5
► ( <u>m</u> a	CAN interfaces
▶ m	ETH interfaces
	USB
<u>*1</u>	Internal signals
f(x)	Formulas
> 📥	Triggers
A 🚞	Datasets
4	Dataset 01
	CAETEC binary 01
	🗱 Min/Max Values 01

The following window lets you choose one or multiple signals whose min/max values may be stored.

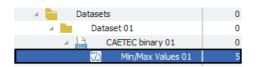
Select the desired signals and confirm with "OK". The selected signals will appear in the grid area.

Pressure_Abs         bar         0,00000         2,00000         0         6553           Pressure_Rel         bar         -2,00000         2,00000         0         6553	5 1 Hz
Pressure_Rel bar -2,00000 0 6553	5 1 Hz
	5 1 Hz
MAP bar 0,00000 3,00000 0 6553	5 1 Hz
TPS_Volt V -8,0000 8,0000 0 6553	5 1 Hz
Front_left C -50,000 200,000 0 6553	5 1 Hz
Front_right C -50,000 200,000 0 6553	5 1 Hz
Rear_left C -50,000 200,000 0 655	5 1 Hz
Read_right C -50,000 200,000 0 6553	5 1 Hz
Exhaust_1 C -50,00 1200,00 0 6553	5 1 Hz
Exhaust_2 C -50,00 1200,00 0 6553	5 1 Hz

#### 12.14.4.2 Tree elements for Min/Max Values

The "Min/Max Values" group will appear as a new child element of the CAETEC binary method labeled "Min/Max Values xx".

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# 12.14.4.3 Grid area for Min/Max Values

The grid area shows an overview of all signals that have been selected for storing their min/max values in this group. The grid area also shows related information such as unit and sampling rate of the signal.

	essure_Abs	1	<b>~</b>	bar	1 Hz
	essure_Rel	2	~	bar	1 Hz
MA	\Ρ	3	~	bar	1 Hz
TPS	S_Volt	4	~	V	1 Hz
Fro	ont_left	5	~	С	1 Hz



#### 12.14.4.4 Details area for Min/Max Values

The details area shows settings regarding this "Min/Max Values" group.

#### General

This tab provides general settings for the selected "Min/Max Values xx" tree element.

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#### • Active

Allows you to activate or deactivate the selected file.

#### • Name

Give a user-defined Name to the selected file.

#### • Description

Give a user-defined description to the selected file.

#### • Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

# Trigger

This tab provides settings regarding the trigger for the start and stop of the "Min/Max Values" storage. When the "Min/Max Values" storage is started, all traffic on the station will be stored to the "Min/Max Values" file.

Furthermore will this trigger provoke the creation of the "Min/Max Values" file, if you have choosen either "On trigger" or "On first trigger" as "File create event".

Mode:	Continuous acquisition 🔹		
Start-trigger:		Select	
Stop-trigger:		Select	
Pre-trigger duration:	0 s		
Post-trigger duration:	0 s		

#### • Mode

Define whether you wish to continuously store data or if you want to start/stop data storage via a trigger. There are two modes to control data storage via trigger:

**Start and stop trigger** allows you to set any previously defined trigger as start and/or stop condition.

**Stop is inverted start** will store data as long as the start trigger condition is met. Once it is no longer met and a possibly set **Post-trigger duration** has run out, data storage will stop.

#### • Start-trigger

Define a trigger, that will start the "Bus trace".

• Stop-trigger

Define a trigger, that will stop the "Bus trace".

• Pre-trigger duration

Pre-trigger duration allows you to define, how long before the start trigger was set, the "Bus trace" will start.

#### Post-trigger duration

Post-trigger duration allows you to define, how long after the start trigger was set, the "Bus trace" will stop.

#### Extended

The field "Alias" allows you to give an alias to the method. The alias has to be unique within the configuration.

An alias functions as a parameter that can later be referenced in includes/partial configurations.

General Trigger	Extended Storage	
	Alias:	
		•
		3

#### Storage

The storage rate sets the rate at which the min/max values in this "Min/Max Values" group will be stored.

General Trigger	er Extended Storage	
Stora	rage rate: 1 Hz	]

i

The signals contained in one "Min/Max Values" may have different sampling rates, but each "Min/Max Values" group may only have one storage rate. It is therefore possible to add multiple "Min/Max Values" groups per CAETEC binary file, so you can have different storage rates according to the different sample rates of the signals, if necessary.

# 12.15 CAETEC ASCII (Classings / Min/Max Values)

The "CAETEC ASCII" filetype allows for classing of signals. Classings are processes for counting values or sequences (such as cycles) of signals. The standard procedure is to take the range in which the counted events are expected and divide this into so-called classes. Any values lying above the highest or below the lowest class are generally ignored (no open-border classes).

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The methods fundamentally differ in their counting strategies (for example, when levels are crossed, when a class is reached, cycle amplitudes and so on), and they are standardized. Which particular standard was applied in the design of each method is explained in the chapters on the different classing methods. Please refer to the chapter "Classing methods" ( $\rightarrow$ 12.16).

A signal can be used in several classing processes simultaneously.

Some methods can be applied with different numbers of signals. This is what is referred to as the dimension of the particular classing. 1D, 2D, 3D specify how many signals are joined in a class (joint classing). When joined, the classes of the signals form a matrix. Counting is always performed in the matrix element in which the counting conditions for all the involved signals are met by the same sampling instance.

# 12.15.1 Tree elements for CAETEC ASCII

Including a "CAETEC ASCII" file in your dataset will add one new child element called "CAETEC ASCII xx" to your tree element "Dataset".

Multiple "CAETEC ASCII" files can be added to your dataset. They will be labeled equally and the counter will be raised by one for each new file. This may be necessary, if multiple classings should be included in the dataset, as each "CAETEC ASCII" file can only contain one classing.

🔺 🚞 🛛 Datasets	0
🛛 🧰 Dataset	0
CAETEC binary 01	0



# 12.15.2 Details area for CAETEC ASCII

The details area contains settings regarding the "CAETEC ASCII" file. General

This tab provides general settings for the selected CAETEC ASCII file.

General	File									
	Active:	V								
Name:		CAETEC binary 01								
Description:										
		File for saving classification data								
Ref	erence:	CAETEC binary 01/ARCOS 1.5								

Active

Allows you to activate or deactivate the selected file.

• Name

Give a user-defined Name to the selected formula/signal.

• Description

Give a user-defined description to the selected formula/signal.

• Reference

This field serves as the tree element's unique identifier inside the measurement task tree. It cannot be changed.

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#### File

This tab provides settings regarding the creation of the file.

General	File			
	File type:	CAETEC binary		
	Hold last value:	Until end of dataset	Ŧ	

• File type

Tells you the type of the created file.

• Hold last value

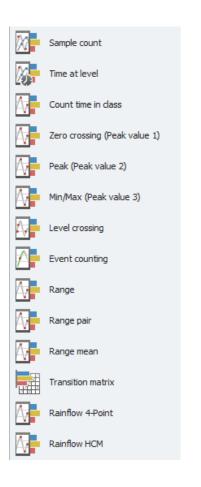
Specify, for how long the last value of the signal will be hold.

# 12.15.3 Adding a classing

In order to add a classing, select the "CAETEC binary" or "CAETEC ASCII" file, which should contain the classing, in the measurement task tree.

System	Components	Functions	Import	t Export	Chec
		Config	uration		
V15.10.0	0.16682 RC				
Name					Σ
4 💼	ARCOS 1.5				10
) → ¢	CAN inte	rfaces			10
⊨ Þ ¢	ETH inter	faces			0
ą	USB				0
► E	Triggers				0
ft	Ø Formulas				0
📩 Internal signals					0
	Datasets				0
	🖌 📄 Data	set			0
	📄 o	AETEC ASC	II 01		0

Then click the "Components" button in the Ribbon and choose the desired classing method.



Once you have added a classing, you may now proceed to configure this classing. Please refer to the chapter "Classing methods" ( $\rightarrow$ 12.16) for instructions.

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# 12.15.4 Min/Max Values

The "Min/Max Values" function of the CAETEC ASCII method allows you to store the minimum and maximum incoming values of signals. It is identical to the "Min/Max Values" function of the CAETEC binary method and has been described in the chapter "CAETEC binary (Min/Max Values). Please refer to  $(\rightarrow 12.14.4)$ .



# 12.16 Classing methods

This chapter will only explain the different classing methods. A classing is always a part of either a CAETEC binary or a CAETEC ASCII file for your dataset. So in order to work with a classing, you will need to add one of these filetypes for each classing, that you wish to define.

For instructions on how to do this, please refer to the chapters "Setting up a dataset" ( $\rightarrow$  12.3) and "CAETEC binary( $\rightarrow$  12.14) or "CAETEC ASCII( $\rightarrow$  12.15).



# 13 Datatransfer

Stored measurement data can later be transferred from the logger and thus made available for further analysis and processing. To do so, it is necessary, to configure one or more "Transfer events", that wilt trigger the transfer, and the desired connection method used for the transfer. The first chapter of this section will explain "Transfer events" and in the following chapter will be explained configuration of the transfer connection method.

Furthermore the logger will check whenever a data transfer is happening, if a newer version of the current logger-configuration (datalog.ccmc) and firmware are available. Instructions on how to set define the correct path will be explained for each type of transfer connection in the respective chapter.

# 13.1 Transfer events

In order for data transfer to take place, it must be triggered by an event. These events can be system events, such as starting or shutting down the logger; trigger events, i.e. reactions to defined triggers; or time events, such as the arrival of a particular point in time. Multiple events can also be defined, even of the same type.

In the event that data transfer limits have been defined, these can, if the need arises, be over-ridden by specific transfer events.

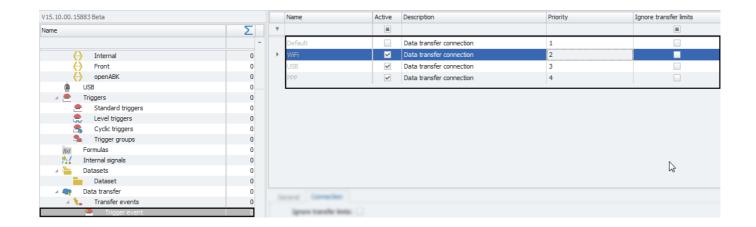


# 13.1.1 General Information about transfer events

#### Multiple targets for transfer events

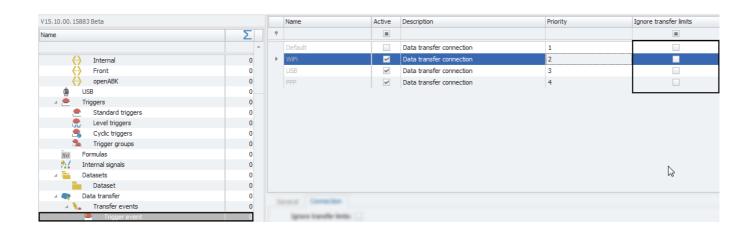
Each transfer event can use multiple connections to different targets, in order to ensure successfull data transfer. In order to do so, activate every connection you want to use for this transfer event in the transfer events grid area. For instructions on transfer connections please refer to  $(\rightarrow 13.2)$ .

By setting the priority you define, which connection will be used first, starting with priority 1. As soon as data transfer via one connection has been successfully completed, the other connections will be skipped and the dataset will be erased from the logger.



#### Ignore transfer limits

In the grid area of every transfer event you can choose to "Ignore transfer limits" for every transfer connection. This means, it will ignore any defined restrictions for that transfer connection. These restrictions can be set in the "Basic" settings tab in the details area of each transfer connection. Please refer to ( $\rightarrow$ 13.2) and then to the respective connection type's section.



# Default data transfer connection

Changes and errors excepted.



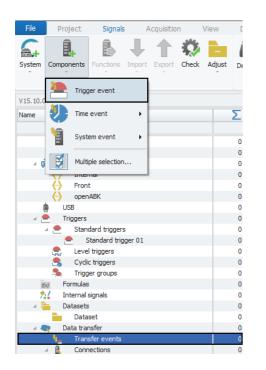
In the grid area of every transfer event you can choose choose the default data transfer connection for data transfer. This means, the connection, that has been defined as default data transfer connection will be used. This setting can be set in the "Basic" settings tab in the details area of each transfer connection. Please refer to ( $\rightarrow$ 13.2) and then to the respective connection type's section.

V15.10.00.15883 Beta			Name Ad		Description	Priority	Ignore transfer limits
Name	Σ	٩					
	A	I	Default	>	Data transfer connection	1	
Internal	0		WiFi		Data transfer connection	2	
	0		USB		Data transfer connection	3	
openABK	0		PPP		Data transfer connection	4	
i USB	0						
🛛 🚔 Triggers	0						
🚔 Standard triggers	0						
🚍 Level triggers	0						
🙈 Cyclic triggers	0						
🛸 Trigger groups	0						
f(x) Formulas	0						
📩 Internal signals	0						
🔺 🛅 Datasets	0						
Dataset	0						
🔺 🦏 🛛 Data transfer	0		and Complete				
🖌 🐛 🛛 Transfer events	0						
Trigger event	0		Igners transfer letter				

# 13.1.2 Trigger events

A "Trigger event" will trigger data transfer whenever the selected trigger is set. Any preivously configured trigger of your system can be used to trigger data transfer.

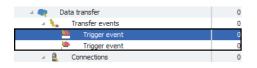
In order to configure a "Trigger event", you will first need to add the "Trigger event" as a "Transfer event". To do so, select the tree element "Transfer events", click on the "Components" button in the Ribbon and choose "Trigger event".





# 13.1.2.1 Tree elements for Trigger events

Adding a "Trigger event" for data transfer will add one new child element to the tree element "Transfer events", called "Trigger event". Multiple "Trigger events" may be added, which will each result in an extra tree element. The name of these elements can be changed in the details area of each tree element.



# 13.1.2.2 Grid area for Trigger events

The grid area for a "Trigger event" for data transfer will present you with an overview of the available connections for data transfer.

You can choose the desired connection for data transfer by ticking the "Use for transfer" tickbox, and you can override transfer limits by ticking the tickbox labeled "Ignore transfer limits".

You may also choose multiple connections for transfer and priorityze them.

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

	Name	Active	Description	Priority	Ignore transfer limits	Use for transfer
٩						
I	Default		Data transfer connection	1		<b></b>
		~	Data transfer connection	2		
	PPP	~	Data transfer connection	3		
	WiFi	~	Data transfer connection	4		



#### 13.1.2.3 Details area for Trigger events

The Details area shows settings for the "Triggger event", that has been selected in the tree. The different tabs of the details area will be explained in the following.

#### General

Please refer to ( $\rightarrow$ 4.2.2).

#### Trigger

This tab contains only the setting **"Event trigger"**, which allows you to select which trigger should be used to start data transfer.

General	Trigger	
	Event-trigger:	Select

Clicking the "Select" button will open a window, which allows you, to choose the desired trigger. Confirm with "OK".

Once a trigger has been chosen, the "Trigger event" will automatically named after this event.

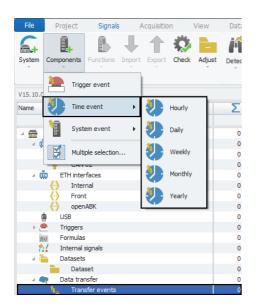
Name	Content	
Standard trigger 01	Standard trigger 01/ARCOS 1.5 - dataLog	



#### 13.1.3 Time events

A "Time event" will trigger data transfer according to a set time intervall.

In order to configure a "Time event", you will first need to add the "Time event" as a "Transfer event". To do so, select the tree element "Transfer events", click on the "Components" button in the Ribbon and choose the desired time intervall from the menu "Time event".



# 13.1.3.1 Tree elements for Time events

Adding a "Time event" for data transfer will add one new child element to the tree element "Transfer events", called "Time event". Multiple "Time events" may be added, which will each result in an extra tree element. The name of these elements can be changed in the details area of each tree element.





# 13.1.3.2 Grid area for Time events

The grid area for a "Time event" for data transfer will present you with an overview of the available connections for data transfer.

You can choose the desired connection for data transfer by ticking the "Use for transfer" tickbox, and you can override transfer limits by ticking the tickbox labeled "Ignore transfer limits".

You may also choose multiple connections for transfer and priorityze them.

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

	Name	Active	Description	Priority	Ignore transfer limits	Use for transfer
٩						
I	Default	<b>Z</b>	Data transfer connection	1		<b></b>
		~	Data transfer connection	2		
	PPP	~	Data transfer connection	3		
	WiFi	~	Data transfer connection	4		

# 13.1.3.3 Details area for Time events

The Details area shows settings for the "Time event", that has been selected in the tree. The different tabs of the details area will be explained in the following.

#### General

Please refer to  $(\rightarrow 4.2.2)$ .

#### Time

This tab allows you to specify the time intervall for the transfer event.

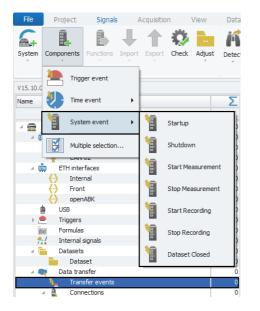
General Event	
Minute:	0
Hour:	0
Day:	
Month:	1



#### 13.1.4 System events

A "System event" will trigger according to a set "System event" such as "Startup", "Shutdown", "Dataset closed" and others.

In order to configure a "System event", you will first need to add the "System event" as a "Transfer event". To do so, select the tree element "Transfer events", click on the "Components" button in the Ribbon and choose the desired event from the menu "System event".

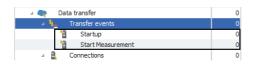


# Available System events

System event	Characteristics			
Startup	Data transfer will start as soon as startup is finished.			
Shutdown	Data transfer will start when shutdown is prompted. Shutdov will not occur until data transfer has finished.			
Start Measurement	Data transfer will start as soon as measurement has started.			
Stop Measurement	nt Data transfer will start as soon as measurement has stoped.			
Start Recording	Data transfer will start as soon as recording of measurement data in a dataset has started.			
Stop Recording	Data transfer will start as soon as recording of measurement data in a dataset has stoped.			
Dataset closed	Data transfer will start as soon as the current dataset is closed.			

# 13.1.4.1 Tree elements for System events

Adding a "System event" for data transfer will add one new child element to the tree element "Transfer events", called according to the type of "System event" you have chosen. Multiple "System events" may be added, which will each result in an extra tree element.



Changes and errors excepted.



# 13.1.4.2 Grid area for System events

The grid area for a "System event" for data transfer will present you with an overview of the available connections for data transfer.

You can choose the desired connection for data transfer by ticking the "Use for transfer" tickbox, and you can override transfer limits by ticking the tickbox labeled "Ignore transfer limits".

You may also choose multiple connections for transfer and priorityze them.

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).

	Name	Active	Description	Priority	Ignore transfer limits	Use for transfer
٩						
I	Default	<b>V</b>	Data transfer connection	1		
		~	Data transfer connection	2		
	PPP	4	Data transfer connection	3		
	WiFi	~	Data transfer connection	4		

# 13.1.4.3 Details area for System events

As "System events" are definite predefined events, there are no further settings for these events available in the details area. It contains only the "General" tab, which will allow you to give a user specific description to the event. Please refer to ( $\rightarrow$ 4.2.2).

# 13.2 Transfer connections

In order for data to be transferred, a transfer connection has to be set up. There are four different types of connections, that can be set up:

- USB (→13.2.1)
- WIFI ( $\rightarrow$ 13.2.2)
- LAN (→13.2.3)
- PPP/UMTS ( $\rightarrow$ 13.2.4)

# 13.2.1 Data transfer via USB

USB is the predefined default connection for data transfer and therefore it is included in the measurement task tree by default. Via USB it is possible to transfer data to and from an external storage device.

Configuration of a USB connection happens exclusively inside the details area of the tree element "USB".





#### 13.2.1.1 Details area for USB

#### General

Please refer to ( $\rightarrow$ 4.2.2).

#### Basic

This tab contains basic settings for the connection.

General Basic Paths	
Check for update:	Not restricted • os
Data transfer:	Not restricted 🔹 0 s
Show dialog:	
Use as default:	

#### • Check for update

Allows you to define, how often and when the logger should check for updated configuration or firmware.

If the option "Interval" is selected, the time interval may be set in the field on the right of the dropdown menu.

#### • Data transfer

Allows you to restrict, how often data transfer from the logger may occur. If the option "Interval" is selected, the time interval may be set in the field on the right of the dropdown menu.

#### • Show dialog

Tick or untick this box in order to show or hide the transfer dialog during measurement.

#### • Use as default

Tick or untick this box in order to make this your default connection for data transfer.

#### MD5

This tab provides settings regarding the MD5 check of transferred files.

Gene	ral Basic MD5		
	Checks	2	
D	elay between checks:	2 s	
	Accepted failures:	5	
	Access point scan	Once, by driver	Ŧ



#### Paths

This tab allows you to set the paths for data transfer.

General Basic Paths		
Measurement data:	1	
Configuration:	1	
Configuration archive:		

#### Measurement data

Define the path, where measurement data should be stored.

#### • Configuration

Define the path, where the logger will check for a newer version of the current configuration (datalog.ccmc) and firmware.

If there is a newer version, the logger will download it, append the current timestamp in the filename, and apply/install it at the next possible moment.

#### • Configuration archive (optional)

Define the subpath for previous logger configurations and firmwares. If this subpath has been defined, the logger will copy the previously used configuration/firmware here, when he receives a newer version. If this subpath is not defined, the logger will leave the file in the "Configuration" path, that has been defined before.



In the field "Measurement data" and "Configuration" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .



#### 13.2.2 Data transfer via WIFI

In order to transfer data via WIFI, you will first need to add a WIFI connection to your system. To do so, select the tree element "Connections", click on the "Components" button in the Ribbon and then choose "WIFI".

After having set up the WIFI connection, you will need to set up a fileserver to which to transfer data. For instructions on how to set up a fileserver please refer to the section "Fileserver" ( $\rightarrow$ 13.2.5).

File	Project	Signals	A	cquisitio	n	View	Data
6.			Ļ	1			K
System	Components	Functions Imp	port	Export	Check	Adjust	Detect
Ť	Ŧ	Ψ. ·				Ŧ	Ŧ
	🔿 WiFi						
V15.10.0	•		-				
Name							Σ
-	Multi	ple selection	ł				0
∡ 🤅			_				0
	🚹 CAN						0
	T CAN						0
						_	0
	Inter						0
	Fron					_	0
	💮 open	ABK					0
ų – ų	Triggers					_	0
		dard triggers					0
		l triggers					0
		c triggers					0
		er groups					0
f							0
2		signals					0
- A 1	Datasets						0
	Data	set					0
	🕴 🛛 Data tra	nsfer					0
	👠 Tran	sfer events					0
	4 🔒 🛛 Conr	nections					0
	1 U	JSB					0



#### 13.2.2.1 Tree elements for WIFI connections

Adding a WIFI connection for data transfer will add two new child elements to the tree element "Connections":

• WIFI

Represents the WIFI connection itself.

• Access point xx

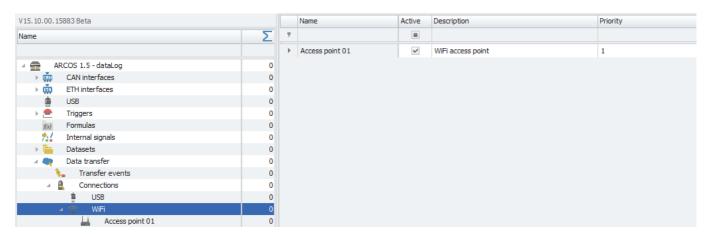
Represents the WIFI access point. A WIFI connection can have various access points, in order to connect to different networks. To add a new access point, select the tree element WIFI, then click the "Components" button in the Ribbon and select "Access point".

0
0
0
0
0
0

#### 13.2.2.2 Grid area WIFI connections

The grid area for a "WIFI connection" for data transfer will present you with an overview of all the currently defined access points for WIFI connections.

Also you can find here two important functions, which are the "Column chooser" ( $\rightarrow$ 4.3.1) and the "Filter editor" ( $\rightarrow$ 4.3.2).





#### 13.2.2.3 Details area for WIFI

The details area provides settings either for the WIFI connection in general or for a specific access point, depending on which element has been selected in the tree.

#### WIFI Settings

#### General

Please refer to  $(\rightarrow 4.2.2)$ .

#### Basic

This tab contains basic settings for the connection.

General Basic Paths	
Check for update:	Not restricted 0 s
Data transfer:	Not restricted    O s
Show dialog:	2
Use as default:	

#### • Check for update

Allows you to define, how often and when the logger should check for updated configuration or firmware.

If the option "Interval" is selected, the time interval may be set in the field on the right of the dropdown menu.

#### • Data transfer

Allows you to restrict, how often data transfer from the logger may occur. If the option "Interval" is selected, the time interval may be set in the field on the right of the dropdown menu.

#### • Show dialog

Tick or untick this box in order to show or hide the transfer dialog during measurement.

#### • Use as default

Tick or untick this box in order to make this your default connection for data transfer.



#### MD5

This tab provides settings regarding the MD5 check of transferred files.

General	Basic MD5		
	Checks:	2	
Delay	between checks:	2 s	
4	Accepted failures:	5	
Α	ccess point scan:	Once, by driver	*

• Checks

Define how often the check should be executed.

- Delay between checks Define the delay between two checks.
- Accepted failures Define the number of accepted failures before aborting the data transfer.
- Access point scan

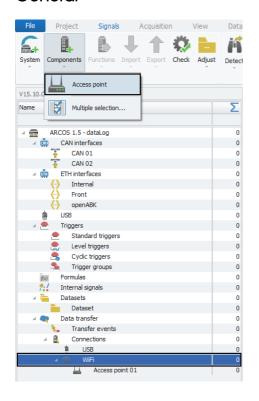
Specify the method how to search for WIFI access points.



#### Access point Settings

Each WIFI connection can have multiple access points, in order to be able to connect to different wireless networks. By setting the priority of the access points in the grid area, you define, which access point will be used first, starting with priority 1. As soon as data transfer via one access point has been successfully completed, the other access points will be skipped and the dataset will be erased from the logger.

In order to add an extra access point, select the tree element "WIFI", click on the "Components" button in the Ribbon and the choose "Access point". **General** 



Please refer to ( $\rightarrow$ 4.2.2).

#### Network

This tab contains settings regarding the network to which the logger will connect.

General Network Security	1
Network name:	
Get IP address automatically:	V
IP address:	0.0.0
Network mode:	Infrastructure 🔻

• Network name

Define the name of the WIFI network (SSID).



#### • Get IP address automatically

Define whether the logger will expect the allocation of a valid IP address automatically by a DHCP server, or whether you want to manually set an IP address.

#### • IP address

IF DHCP is disabled, this field allows you to manually enter an IP address.

#### • Network mode

Allows you to choose the mode of the network you wish to connect to.

#### Security

This tab provides security settings regarding the access point and the network you wish to connect to.

Authentication mode: WPA-PSK	-			
Network key:				
Login mode: Using a ce	rtificate (default)	Ŧ	Security protocol:	WPA 🔻
Identity:				
Password:				

#### • Authentication mode

Select the authentication mode of the network.

#### • Network key

Type in the authentication key of the network.

#### • Login mode

If the authentication mode of the network is WPA-EAP, then you may here set whether to login with a certificate or not, and if so, set the security protocol.

#### Identity

If the authentication mode of the network is WPA-EAP, then you may here enter your identity/username.

#### • Password

If the authentication mode of the network is WPA-EAP, then you may here enter your password.



#### 13.2.3 Data transfer via LAN

In order to transfer data via LAN, you will first need to add a LAN connection to your system. To do so, select the tree element "Connections", click on the "Components" button in the Ribbon and then choose "LAN".

After you have set up the LAN connection, you will need to additionally set up a fileserver, where the transferred data will be stored. Please refer to the section "Fileserver" ( $\rightarrow$ 13.2.5).



#### 13.2.3.1 Tree elements for LAN connections

Adding a LAN connection for data transfer will add one new child element called "LAN" to the tree element "Connections"

4 🗬 Data transfer	0
🐛 Transfer events	0
Connections	0
USB USB	0
🔶 LAN	0

#### 13.2.3.2 Details area for LAN

The details area provides settings for the LAN connection.

General Please refer to  $(\rightarrow 4.2.2)$ .



#### Basic

This tab contains basic settings for the connection.

General Basic Paths	
Check for update:	Not restricted • 0 s
Data transfer:	Not restricted  v 0 s
Show dialog:	
Use as default:	

#### • Check for update

Allows you to define, how often and when the logger should check for updated configuration or firmware.

If the option "Interval" is selected, the time interval may be set in the field on the right of the dropdown menu.

#### • Data transfer

Allows you to restrict, how often data transfer from the logger may occur. If the option "Interval" is selected, the time interval may be set in the field on the right of the dropdown menu.

#### • Show dialog

Tick or untick this box in order to show or hide the transfer dialog during measurement.

#### • Use as default

Tick or untick this box in order to make this your default connection for data transfer.

#### MD5

This tab provides settings regarding the MD5 check of transferred files.

General	Basic MI	)5
	Cheo	ks: 2
Delay I	between cheo	ks: 2 s
A	ccepted failur	es: 5
Ac	ccess point sc	an: Once, by driver
Ac	ccess point sc	an: Once, by driver

• Checks

Define how often the check should be executed.

• Delay between checks

Define the delay between two checks.



#### • Accepted failures

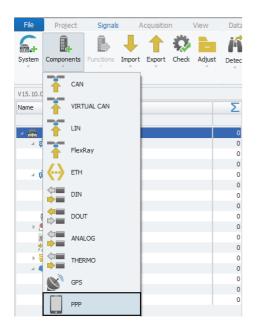
Define the number of accepted failures before aborting the data transfer.

#### 13.2.4 Data transfer via PPP/UMTS

In order to transfer data via PPP/UMTS, you will first need to configure a PPP/UMTS connection. To do so, please refer to ( $\rightarrow$ 13.2.4.1). Once a PPP/UMTS connection has been set up, you will need so set the basic settings for PPP data transfer and you will also need to set up a fileserver. This chapter treats the basic settings for data transfer via PPP. For instructions on how to set up a fileserver please refer to the section "Fileserver" ( $\rightarrow$ 13.2.5).

#### 13.2.4.1 Setting up a PPP/UMTS connection

To set up a PPP/UMTS connection, select your system (Arcos,  $\mu$ Cros,  $\mu$ Cros XL) in the tree, click the "Components" button in the Ribbon and choose "PPP".



This will add two elements called "PPP" to the measurement task tree. One as a childelement to the main system (Arcos,  $\mu$ Cros,  $\mu$ Cros XL) and one as a childelement to the tree element "Connections". Select the first of the two, navigate to the tab "Connection" in the details area and fill in the access data. This data can be obtained from your simcard provider.

The option "Persistent connection" allows you to maintain a connection not only during data transfer but also during measurement.

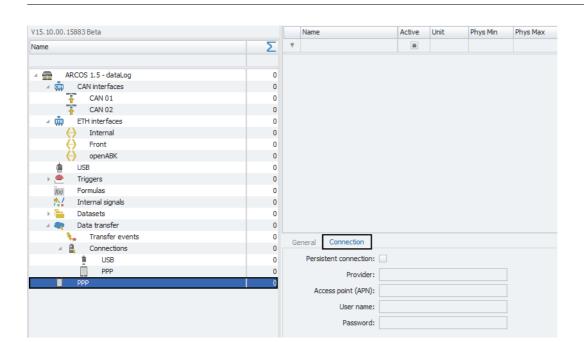
#### 13.2.4.2 Details area for PPP/UMTS

Configuration of a USB connection happens exclusively inside the details area of the tree element "USB".

#### General



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Please refer to ( $\rightarrow$ 4.2.2).

#### Basic

This tab contains basic settings for the connection.

Not restricted	
Not restricted	
V	
V	
	Not restricted 0 s

#### • Check for update

Allows you to define, how often and when the logger should check for updated configuration or firmware.

If the option "Interval" is selected, the time interval may be set in the field on the right of the dropdown menu.

#### • Data transfer

Allows you to restrict, how often data transfer from the logger may occur. If the option "Interval" is selected, the time interval may be set in the field on the right of the dropdown menu.

#### • Show dialog

Tick or untick this box in order to show or hide the transfer dialog during measurement.

#### • Use as default

Tick or untick this box in order to make this your default connection for data transfer.



#### MD5

This tab provides settings regarding the MD5 check of transferred files.

General	Basic	MD5		
	c	hecks:	2	
Delay	between o	thecks:	2 s	
A	ccepted f	ailures:	5	
A	ccess poin	t scan:	Once, by driver	*
	cccoo poin	C DCGITI	once, by anter	



#### 13.2.5 Setting up a Fileserver

Transferring data via WIFI/LAN/PPP/UMTS requires the configuration of a fileserver to which the data will be transferred. To do so, select the tree element for the connection you wish to configure: "PPP", "LAN", "Access point xx" (for WIFI connections the acccess point has to be selected instead of the WIFI connection), click the "Components" button in the Ribbon and choose "Fileserver".

File	Project	Signals	Acquisitio	n View	Data
System	Components	Functions Imp	Cort Export	Check Adjus	t Detec
V15.10.0	File s	erver			
Name		server			Σ
× 🖻 .		le selection			0
¢	CAN INTER		_		0
	CAN CAN				0
a d					0
- 4 Q	Christer				0
	G Front				0
	( open/				0
					0
	-				0
ft					0
2		ignals			0
- F 1	Datasets				0
	Data tran	sfer			0
	🐛 Trans	fer events			0
	🖌 🚉 🛛 Conn	ections			0
	1 U	SB			0
	PI	PP			0
	4 🎓 🛛	/iFi			0
	4	Access point	01		0
		AN			0
	PPP				0



#### 13.2.5.1 Multiple File servers

Each data transfer connection can have multiple file servers, in order to ensure successfull data transfer. By setting the priority of the file servers in the grid area, you define, which file server will be used first, starting with priority 1. As soon as data transfer via one file server has been successfully completed, the other file servers will be skipped and the dataset will be erased from the logger.

V15.10.00.15883 Beta			Name	Active	Description	Priority
Name $\Sigma$		٩				
		÷	File server 01	~	SFTP or SCP File Server	1
🔺 🚍 ARCOS 1.5 - dataLog	0		File server 02	~	SFTP or SCP File Server	2
CAN interfaces	0		File server 03	~	SFTP or SCP File Server	3
<ul> <li>ETH interfaces</li> </ul>	0					
i USB	0					
> 🚔 Triggers	0					
f(x) Formulas	0					
📩 Internal signals	0					
🕨 🚞 🛛 Datasets	0					
🔺 🦏 🛛 Data transfer	0					
🐛 Transfer events	0					
A Q Connections	0					
USB USB	0					
⊿ 🎓 WiFi	0					
Access point 01	0		and a second			
🔚 File server	0					

#### 13.2.5.2 Tree elements for File servers

Adding a Fileserver will add one new element called "Fileserver" to the tree. It is possible to add multiple fileservers, to one connection, but they will all be found under the same tree element. An overview of the fileservers can be seen in the grid area.

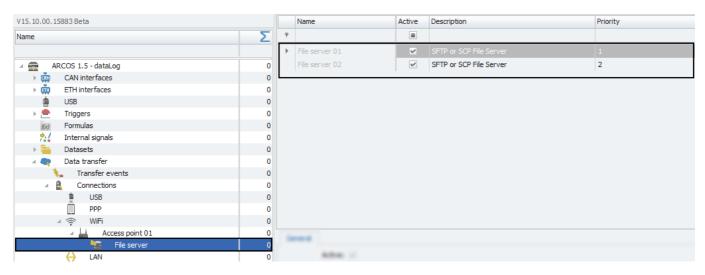
🖌 🚉 Connections	0
🗎 USB	0
PPP	0
⊿ 🎓 WiFi	0
Access point 01	0
🔄 File server	0
🔶 LAN	0



#### 13.2.5.3 Grid area for File servers

The grid area for a "Filserver" will present you with an overview of all the currently defined added fileservers. It also allows you to prioritize the various fileservers.

Also you can find here two important functions, which are the **"Column chooser"** ( $\rightarrow$ 4.3.1) and the **"Filter editor"** ( $\rightarrow$ 4.3.2).



#### 13.2.5.4 Details area for File servers

The details area provides settings for a file server. Choose the fileserver you wish to configure in the grid area of the tree element "File server" and then navigate to the details area.

#### General

Please refer to ( $\rightarrow$ 4.2.2).

#### Connection

This tab contains settings for the connection.

General	Connection	Paths
	Protocol:	SFTP
	Single session:	<b>~</b>
	Hostname:	
	Port:	22
	User name:	
	Password:	

• Protocol

Select the protocol used for data transfer to the file server.

• Single session

If set, the SFTP single session mode will be used.



• Hostname

Define the IP address or hostname of the SSH file server.

• Port

Define the port or hostname of the SSH file server.

- User name Fill in the user name to access the SSH file server.
- Password

Fill in the password to access the SSH file server.

#### Paths

This tab allows you to set the paths for data transfer.

General Connection Paths		
Measurement data:		
Configuration:		
Configuration archive:		

#### • Measurement data

Define the path, where measurement data should be stored.

#### • Configuration

Define the path, where the logger will check for a newer version of the current configuration (datalog.ccmc) and firmware.

If there is a newer version, the logger will download it, append the current timestamp in the filename, and apply/install it at the next possible moment.

#### • Configuration archive (optional)

Define the subpath for previous logger configurations and firmwares. If this subpath has been defined, the logger will copy the previously used configuration/firmware here, when he receives a newer version. If this subpath is not defined, the logger will leave the file in the "Configuration" path, that has been defined before.



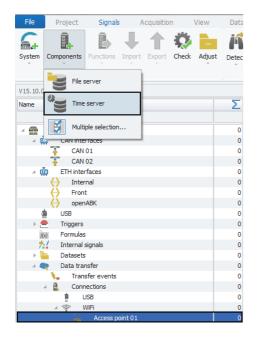
In the fields "Measurement data" and "Configuration" project parameters can be used as variables. For more information please refer to  $(\rightarrow 5.6)$ .



# 14 Setting up a time server

In order for your logger to always have the correct time, you will need to set up a time server to which the logger will connect and then synchronize its time with.

A time server can be configured for every LAN, WIFI or PPP/UMTS connection. To do so, select the tree element for the connection you wish to configure: "PPP", "LAN", "Access point xx" (for WIFI connections the acccess point has to be selected instead of the WIFI connection), click the "Components" button in the Ribbon and choose "Time server".



Then select the "Time server xx" in the grid area **of the tree element** "Time server xx" and navigate to the "Connections" tab in the details area and set the hostname/IP address in the field "Hostname".

General Connection
Hostname:





# 15 Obtaining extended support

support@caetec.de +49 8142 501365



# Hardware and Configuration

Version 1.0 Date of issue: March 20, 2019



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All specifications are based on the technical status of 09/01/2014. We reserve the right to make any changes required to technically improve the equipment.

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# Contents

1	Foreword	5
2	Introduction         2.1       Symbols         2.2       References         2.3       Notes	<b>6</b> 6 6
3	Hardware         3.1       Overview         3.2       ARCOS Basic Platform         3.2.1       About the Connections         3.2.2       Connection and LED Assignment         3.3       µCROS         3.3.1       About the connections         3.3.2       Connection and LED Assignment         3.4       Upper Expansion Chassis Unit (USB)         3.5       Lower Expansion Chassis Unit (ETH)         3.6       Interface Module for the Lower Expansion Chassis Unit         3.6.1       CAN	8 8 10 11 13 14 15 15 15 17 18 20 20
	3.6.1.1       Input Buffer         3.6.1.2       Switching Output for External Hardware (not CAN interface v2)         3.6.1.3       Assigning the connections         3.6.1.4       Technichal Data         3.6.2       LIN         3.6.2       Input Buffer         3.6.2       Power Supply on the LIN Channel         3.6.2.3       Setting the Baud Rate         3.6.2.4       Connection Assignment         3.6.2.5       Technichal Data         3.6.3       Ilput Buffer         3.6.3.1       Input Buffer         3.6.3.2       Timing Parameters         3.6.3.3       Connection Assignment	20 21 23 23 24 24 24 24 24 25 26 26 26 26
	3.6.3.4       Technical Data         3.6.4       Analog/Digital I/O         3.6.4.1       Input Buffer         3.6.4.2       Sampling Rate         3.6.4.3       Connection Assignment         3.6.4.4       Technical Data	27 28 28 28 28 28 28 30
Cł	3.7       Interface Modules for the Upper Expansion Chassis Unit         3.7.1       WiFi         3.7.1.1       Applications         3.7.1.2       Module Placement         3.7.1.3       Configuration parameters         3.7.1.4       Technical Data         3.7.2       UMTS	31 31 31 31 32 33 33 33 2

CONT	ENTS
------	------



	3.8	3.7.3 Moun 3.8.1 3.8.2	3.7.2.2Module Placement33.7.2.3Configuration Parameters33.7.2.4SIM Card33.7.2.5Technical Data3GPS/Galileo33.7.3.1Applications33.7.3.2Module Placement33.7.3.3Configuration parameters33.7.3.4Technical Data3ting the Slide-In Modules3Mechanical Installation3Initializing the modules4	
			3.8.2.1Upper Expansion Chassis Unit43.8.2.2Lower Expansion Chassis Unit4	11 11
			3.8.2.3 Adjusting for Changes in Installed Interfaces	
	3.9	Displa		2
		3.9.1		.3
		3.9.2	/ 0	3
		3.9.3		4
		3.9.4		6
				.6 .6
				.9
				-9 0
				2
				3
				4
				6
			3.9.4.9 Handling Messages	
		3.9.5		9
4	Con	nfigurat		0
	4.1	Gene	ral Information	0
		4.1.1	Basic Principles	0
		4.1.2	Configuration blocks	
		4.1.3	Standard logger run behavior	
		4.1.4	Starting/Stopping the logger	-
		4.1.5	Persistence	
		4.1.6	Bus channels/nodes	
		4.1.7	CAN channels	
		4.1.8 4.1.9	LIN channels	
		4.1.9		)/
5	<b>Date</b> 5.1 5.2		information	8 8 9
	5.3	Data <sup>•</sup>	transfer via USB	0
		5.3.1	Preparation	0
		5.3.2	Transfer procedure         7	0

#### CONTENTS



	5.4 5.5 5.6 5.7	Data transfer via WLAN/UMTS725.4.1 Preparation725.4.2 Transfer procedure72Importing the configuration to the logger73Data transfer via LAN74Filestructure of measurement data stored on the logger75
6		rice76Power outage76Fallback-behaviour76Firmware updates76Error codes, problems and suggested remedies766.4.1Error codes - WLAN786.4.2Error codes - USB796.4.3Error codes - PPP806.4.4Error codes XCP LAPI816.4.5Problems and suggested remedies81





# 1 Foreword



# 2 Introduction

# 2.1 Symbols

Various paragraphs in this manual are marked with special symbols. These symbols have the following meanings:



This symbol highlights important information that, if ignored, may prevent successful use of the program.



This symbol refers to additional information supplementing this manual.

### 2.2 References

References to other sections of this manual are generally placed in brackets and are indicated by an arrow:

 $(\rightarrow 2.1)$  refers to Section 2.1.

When this manual is read in digital form, a mouse-click on such a reference accesses the particular section of the book.

### 2.3 Notes

This manual explains the ARCOS and  $\mu$ CROS logger systems. It provides technical descriptions of the components and their technical data, along with a description of the configuration and the resulting application options.

The functionality of the systems depends on the particular firmware version in use. Therefore, all functions and parameters that are only available with a specific firmware version (or higher) have been marked with the respective version number in superscript (e.g., with 1.3). Which particular firmware version is installed can be determined by checking the display, the Web interface or the log file.

In addition, you will find brief instructions for a variety of useful procedures and methods for working with the logger. This information is provided with no claim to completeness, and revisions shall be made as development progresses



Using the logger and display while operating a vehicle can distract the driver. Concentration on traffic should be the driver's top priority at all times.





Operating a data logger in transmission mode can interfere with the proper functioning of safety and control components, resulting in the cancellation of the respective vehicle operating permit. It is the sole responsibility of the installing party to supervise this. Moreover, it is that same party's obligation to instruct vehicle drivers on this matter, as well as to advise them on proper procedures.



# 3 Hardware

#### 3.1 Overview

The "ARCOS" hardware system comprises a number of modules connected to a basic platform unit. The functioning of the particular system (ARCOS dL, ARCOS PC or ARCOS X-Over) varies according to the types of components used.

The  $\mu$ CROS is the little "brother" of the ARCOS dL – while it is only equipped with a logger function and is less modular, it is compacter and water-tight.

The complete ARCOS system comprising the basic platform, upper an lower units and modules:



The complete logger unit, comprising the basic platform and the chassis units (without slide-in modules):



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The basic platform consists of a housing containing the central processor assembly. The particular front employed determines the functionality of the system. The number of modules in the assembly is variable and depends on the interfaces required for a particular application.

A basic distinction is made between those modules that are designed to be mounted on top of the basic platform unit and those for assembly underneath. These two types (upper/lower units) are not interchangeable, if only due to their different connector channels (the so-called "backplane"). Separately, however, the chassis units for the lower (or upper) modules are interchangeable, irrespective of their order. There is no set limit to the number of chassis units assembled. The number is limited by the maximum size of the complete housing (installation space), the maximum permitted current draw, and similar peripheral parameters.

All modules are centrally connected to the supply voltage via the jack in the basic platform. Each chassis unit has its own power supply conditioning (DC/DC conversion), its own "power supply", so to speak.

The connecting sockets in the top or bottom chassis units can be covered with a protective plate. It is screwed onto the housing and is fitted with a rubber seal.

A display is auxiliary to the ARCOS dL and  $\mu$ CROS. Basically, the logger can be used without a display, as well, with no impairment of measurement. The significant advantage of the display is that it serves as the user interface for transferring the measured data at the end of a measurement (cf. Chapter "Display") or for documenting the driven track (track selection).



### 3.2 ARCOS Basic Platform

The basic platform unit comprises an x86 processor platform, to which all the information and signals are fed. The chassis units are connected to it via bus systems. All the connections between the basic platform unit and the external periphery (power supply, display,...) plug into the front plate.

The operating system with the data acquisition software, as well as the measured data, is stored on a compact flash memory card (CF card). Another option for data storage is a separate S-ATA hard drive (rotating or solid state). The removable front plate provides access to the storage media.

A so-called "heat spreader" connects the processor system to its housing. The heat produced by the processor is conveyed through the housing to the cooling fins. When required, the rear fans increase convection in the fins, but do not ventilate within the housing.

In the ARCOS dL, the USB connector is for transferring data (importing configurations or transferring measured data) and operating an external configuration provided. This port, therefore, is only used for inserting the same type of USB memory sticks or external USB hard drives as are used in PC technology (max. 500 mA). Expanding the periphery by using USB-CAN interfaces or comparable components via the USB connection is only supported for ARCOs as PC.

Along with the data lines, the ARCOS dL and X-Over display connection socket includes the power supply lines, i.e. the display receives its operating power from the basic unit. The connector is configured as an Ethernet port, connecting the basic platform unit via adapter cable with the Ethernet jack for diagnostic/webinterface with a PC. The ARCOS PC and X-Over are equipped with a standard VGA connector, while the AR-COS PC also has a standard LAN connector.

The power supply connector contains not only the pins for positive and ground (or, in automotive engineering terms, the "Clamps 30 and 31"), but also a pin for switch input (what automotive engineers often call a "Clamp 15"). A voltage level above approx. 3V on this pin starts the logger. This start capability exists in addition to start via bus messages (e.g., "Wake-on-CAN" = WoC). Regardless of whether WoX is activated, sufficient voltage at the control pin (Cl 15) will start the logger.

This behavior also enables an emergency start-up, ensuring there's always a way to safely start the logger (following a configuration error, e.g., such as Start on a CAN message that never occurs).

To minimize standby current consumption, the Clamp 15 has a very high impedance (> 10 kilohm). In surroundings with high disturbance levels, one should make sure the potential is properly connected to the clamp connector and not leave the pin open – in order to avoid unexpected system start-ups.

The external fuse is a vehicle fuse, for a maximum current of 7.5 A.

As an indication of the total current draw of a typical system, we measured a current draw of approx. 3A with 12 V for the following assembly:

• basic platform





- incl. four-channel CAN modules (2 units)
- plus WLAN module



The upper limit for supply voltage is 50 V. Loggers manufactured after February 2008 are equipped with an integrated over-voltage trip in the supply line. This protects the device against voltage > 50 V DC by tripping the fuse in a controlled manner. For this purpose, the supply source must be able to supply current at least twice as high as the nominal strength of the fuse. Otherwise the over-voltage device won't trip safely, in which case, over-voltage may cause serious damage to the logger. (In a vehicle, this condition is generally met.)



Loggers manufactured before February 2008 have no such over-voltage trip. Under no circumstances are the supply lines of these devices to be connected to voltages > 50 V DC.

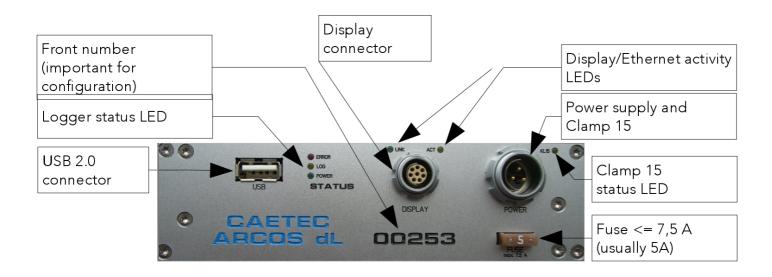
The fuse may only be changed when the logger is disconnected from the power supply. (Pull the plug in the front plate)

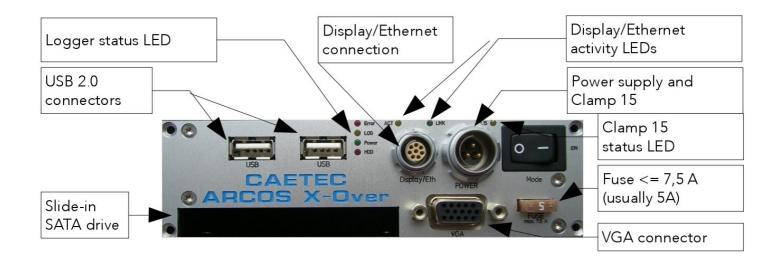
#### 3.2.1 About the Connections

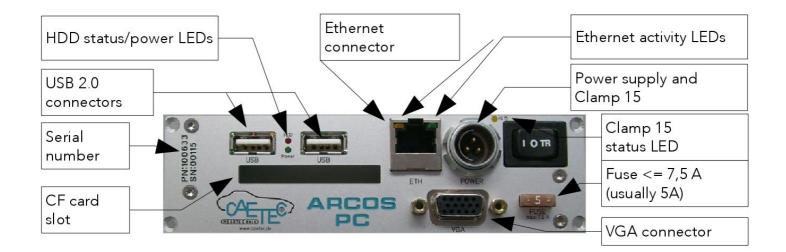




## **IPTRONIK**











### 3.2.2 Connection and LED Assignment

USB	
Standard assignment of	Transfers configurations and measure-
PC technology.	ment data (ARCOS dL), and (in the AR-
	COS PC) is available for other USB har-
	dware

Logger Operating Status (	(ARCOS dL and X-Over)
Error (red): Off	No error.
Briefly flashes	Firmware malfunction has occurred, fal-
	Iback will start shortly.
Blinks (lit/dark: 50/50 )	Firmware running with fallback configu-
	ration
Lit (steady)	Firmware malfunction
Log (yellow): Off	No measurement
Blinks 1.3 (lit/dark: 50/50 )	Measurement running, but there is no
	method storing data
On	Measurement running, data are being
	stored.
Power (green): Off	Measurement system is off - no power
	supply connected
Short blinks (lit/dark:	System booting, due to met start condi-
25/75)	tion (e.g. Clamp 15 of WoX)
Lit (steady)	Boot was successful, logger is operatio-
	nal. (Check the Log LED for the measu-
	rement mode.)
Long blinks (lit/dark:	System shutting down (takes approx.
75/25)	10s), ends with the mode "short blinks"

Display Pin Assignment ARCOS dL and X-Over		
1	Supply -	
2	Supply -	
3	Supply +	
4	Supply +	
5	Data 1 (RX+, orange and white)	
6	Data 2 (RX-, orange	
7	Data 3 (TX+, green and white)	
8	Data 4 (TX-, green)	

Display Activity LEDs (ARCOS dL and X-Over)		
Link	Lit when the cables are connected and	
	a link has been established	
Act	Blinks when data packets are being	
	transported	

Power Pin Assignment	
1	Supply +
2	Ground
3	Clamp 15



Clamp 15 Status Display							
LED on/off	Voltage	level	for	logger	start	is	pre-
	sent/not	prese	nt (v	oltage o	above	÷ 3	<b>√)</b>

VGA (ARCOS X-Over and PCStandard assignment of<br/>PC technologyConnection to a standard VGA monitor

LAN (RJ45) (ARCOS PC)	
Standard assignment of	LAN connector
PC technology	

# 3.3 µCROS

Unlike the ARCOS, the  $\mu$ CROS has a closed housing to which no expansion modules can be connected. Due to its hardware architecture, it runs the same  $\mu$ CROS software as an ARCOS dL; the configurations are also totally interchangeable – except that the  $\mu$ CROS has a lower computing power and supports fewer interfaces and bus interfaces.

In the µCROS LE version, the CAN channels are purely passive, no CAN Acknowledge is set and sending is not supported (which means there's no CCP/XCP!). However, an upgrade via software license is subsequently possible.

The  $\mu$ CROS comprises an x86 processor platform connected via internal Ethernet connector to the integrated two or four-channel CAN interface. The platform also provides two slots for any combination of GPS, WLAN or UMTS modules. Each module has an SMA jack on the front plate as antenna connector. All the  $\mu$ CROS connectors to external periphery (power supply, display, CAN, USB, the antenna connections of the custom options) are on the front plate.

The operating system with the data acquisition software and the measurement data are stored on a separate mSATA storage medium installed in the  $\mu$ CROS.

A so-called "heat spreader" connects the processor system to its housing. The heat produced by the processor is conveyed through the housing to the cooling fins. Since it produces less heat than the ARCOS, the housing is totally without fans. So the  $\mu$ CROS contains no moving parts.

The µCROS USB connector is for transferring data (importing configurations or transferring measured data) and operating an external configuration provided. This means this port is only used for inserting the same type of USB memory sticks or external USB hard drives (max. 500 mA) as are used in PC technology.

No provision has been made for expanding the periphery by means of USB-CAN interfaces or comparable components.

The  $\mu$ CROS display jack includes the data lines, as well as the power supply lines, i.e. the display receives its operating power from the logger. The  $\mu$ CROS connector is configured as an Ethernet port. This port is connected via adapter cable with the Ethernet jack for diagnostic/Webinterface with an PC.

The power supply jack contains not only the pins for positive and ground, but also a pin for switch input (a so-called "Clamp 15"). At this pin, a voltage level above approx. 3 V starts the logger. This start capability is provided in addition to start via bus messages ("Wake-on-CAN" = WoC). Regardless of whether WoX is activated, sufficient voltage at the control pin (Cl 15) will start the logger.

To minimize standby current consumption, the Clamp 15 has a very high impedance (> 10 kilohm). In surroundings with high disturbance levels, one should make sure the potential



is properly connected to the clamp connector and not leave the pin open – in order to avoid unexpected system start-ups.

The fuse of the complete system is an SMD fuse for a maximum current of 3 A. The display power supply has been equipped with a self-healing 500 mA fuse.

With the  $\mu$ CROS, typical total current draw is virtually independent of the options selected (WLAN, UMTS, GPS):

Current draw: approx. 0.5 A with 12 V

The upper limit for the supply voltage is 36 V, without an integrated overvoltage trip in the supply line. The fuse for the total system can only be changed by CAETEC.

#### 3.3.1 About the connections



#### 3.3.2 Connection and LED Assignment

Power Pin Assignment	
1	Clamp 15
2	Supply +
3	Supply +
4	Supply +
5	Ground
6	Ground
7	Ground
8	n.c.





Pin Assignment of Signal Connectors		
1	CAN 1 High	
2	CAN 1 Low	
3	CAN 2 High	
4	CAN 2 Low	
5	CAN 3 High	
6	CAN 3 Low	
7	CAN 4 High	
8	CAN 4 Low	
9	Display Vcc	
10	Display GND	
11	n.c.	
12	n.c.	
13	n.c.	
14	n.c.	
15	Ethernet RX+	
16	Ethernet RX-	
17	Ethernet TX+	
18	Ethernet TX-	
19	USB Vcc	
20	USB D-	
21	USB D+	
22	USB GND	

Logger Operating Status	
Logger Operating Status	
Error (red): Off	No error.
Briefly flashes	Firmware malfunction has occurred, fal-
	Iback will start shortly.
Blinks (lit/dark: 50/50 )	Firmware running with fallback configu-
	ration
Lit (steady)	Firmware malfunction
Log (yellow): Off	No measurement
Blinks 1.3 (lit/dark: 50/50 )	Measurement running, but there is no
	method storing data
On	Measurement running, data are being
	stored.
Power (green): Off	Measurement system is off - no power
_	supply connected
Short blinks (lit/dark:	Measurement system is off - power sup-
25/75)	ply is connected (approx. 900µA cur-
	rent draw
Blinks (lit/dark: 50/50 )	System booting, due to met start condi-
	tion (e.g., Clamp 15 or WoC
Lit (steady)	Boot was successful, logger is operatio-
	nal. (Check the Log LED for the measu-
	rement mode.)
Long blinks (lit/dark:	System shutting down (takes approx.
75/25 )	10s), ends with the mode "short blinks"
, , _ , _ ,	





CL15 Status Display	
LED on/off	Voltage for logger start is present/not present (voltage above 3V)

000	
Standard assignment of	Transfer of configurations and measu-
PC technology	red data

Display/Ethernet Pin Assignment (identical to ARCOS dL and X-Over		
1	Supply -	
2	Supply -	
3	Supply +	
4	Supply +	
5	Data 1 (RX+, orange and white)	
6	Data 2 (RX-, orange)	
7	Data 3 (TX+, green and white)	
8	Data 4 (TX-, green)	

CAN Pin Assignment	
1	CAN 1 Low
2	CAN 2 Low
3	CAN 3 Low
4	CAN 4 Low
5	n.c.
6	CAN 1 High
7	CAN 2 High
8	CAN 3 High
9	CAN 4 High

A CAN bus with "standard" assignment (D-Sub socket with CAN Low Pin 2, CAN High Pin 7 and all other pins unassigned!) can also be directly connected to this plug, without an adapter/breakout box and received on the second CAN channel of the  $\mu$ CROS.

# 3.4 Upper Expansion Chassis Unit (USB)

This expansion chassis unit is mounted on top of the basic platform unit and houses slide-in modules with USB interfaces.

To avoid accidental use as a "lower chassis unit", its connector has been keyed, with differently positioned alignment pins. In addition, the grooves cut in the lid of the chassis unit (cf. 2.4-1), which serve as assembly guides for the modules, have a different design. The lid serves as the bottom for the next chassis unit. This means that modules for the "upper chassis unit" cannot be inserted in the "lower chassis unit", and vice versa.





The chassis units have been designed to house up to four slide-in modules per unit. The available space can be divided up between 1/4, 2/4 and 4/4 slide-in modules. The form of the slide-in modules depends on the interface type. The modules currently available for the upper chassis unit are:

- > WLAN
- > GPS
- > UMTS/GPRS
- > Power Switch
- > USB/Power Switch
- > USB hub
- > ETH 1G
- > USB HDD
- > Video
- > CANCase XL (ARCOS PC and ARCOS X-Over only)
- > VN1630 (ARCOS PC and ARCOS X-Over only

A so-called "backplane" connects the interfaces to the basic unit. The backplane loops both the data signals and the supply through the chassis unit, which makes the chassis units cascadable. Each chassis unit has its own power supply conditioning, its own power supply unit (DC/DC conversion), so to speak. The slide-in modules are identified by their individual IDs, so they function independently of their slot position or the assembly order of the chassis units.

The chassis unit stacks are screwed to the basic platform unit by means of four connecting tabs (two at the front and two at the rear).

In the final expansion chassis unit, the opening above the contacts can be covered with a screw-down lid.

# 3.5 Lower Expansion Chassis Unit (ETH)

The lower expansion chassis unit is mounted under the basic platform unit and houses slide-in modules with Ethernet interfaces. To avoid accidentally substituting it for an "upper chassis unit", its connector has been keyed, with differently positioned alignment pins. In addition, the grooves cut in the lid of the chassis unit, which serve as assembly guides for the interfaces, have a different design. The bottom serves as the lid for the next chassis unit (i.e. on the bottom of the adjoining unit). This means that modules for the "lower chassis unit" cannot be used in the "upper chassis unit", and vice versa.







The chassis unit has been designed to house up to two modules per unit. The available space can be divided up between 1/2 and 2/2 slide-in modules. he currently available interfaces are CAN, LIN, FlexRay, MOST and Analog/Digital I/O.

A modified Ethernet interface in the so-called "backplane" connects the interfaces to the basic unit. The backplane loops both the interface and the supply through the chassis unit, which makes the chassis units cascadable. Each chassis unit has its own power supply conditioning, its own power supply unit (DC/DC conversion), so to speak. In the final expansion chassis unit, the opening above the contacts can be covered with a screwdown lid.

The slide-in modules are each identified by an individual ID (product number/serial number), so they function independently of their slot position or the assembly order of the chassis units. When setting up the system, one should thus bear in mind that the node number for the bus channel is linked to the interface module and not the slot position. The assignment of each interface module to a node number is stored in the logger and configurable via the webinterface.

Any time an interface is replaced, please check the configuration of its node assignment (see 2.8.2 Initializing the Modules)!

The total number of chassis units that can be mounted under the basic platform is limited only by such peripheral parameters as the maximum current of the complete assembly, the overall data throughput or the assembly size.

# 3.6 Interface Module for the Lower Expansion Chassis Unit

The lower expansion chassis unit houses the modules with field bus channels. Currently available are slide-in modules for LIN, CAN, FlexRay, MOST and Analog/Digital I/O. Except for Analog/Digital I/O, all module types have quick-start functionality, i.e. signals on one or more channels start and stop the logger.

# 3.6.1 CAN

The models currently available are galvanically separate CAN slide-in modules – with two CAN channels (half-width), and four CAN channels (full-width) – and a not galvanically separate CAN slide-in with four CAN channels (half-width). This means that per expansion chassis unit up to eight CAN channels are available. These modules are equipped with Wake-on-CAN (WoC) and quick-start functionality.

In this context, Wake-on-CAN means that any CAN signal on one or more of the CAN channels can start the logger. You can even specify for the content of a specific message bit to be used for start-up. For details about starting and stopping with WoC, see and the following chapter.

Idle current draw needs to be minimized, but message loss should also be avoided. To optimize idle current draw with respect to these competing demands, two modes were introduced:

- > WoC: very little idle current, but the first messages are lost (max. 30 ms)
- > WoC with "No message lost": higher idle current, but no messages are lost.

### 3.6.1.1 Input Buffer

Logger booting time is currently approx. 20 seconds. During this time, any data in the CAN interface is buffered. Once booting procedure is completed, it is transferred to the logger.

The following table shows the buffer size, with the maximum number of buffered messages – for the complete slide-in module, regardless of whether it is a two-channel or fourchannel model. A CAN message requires exactly 20 Bytes.

Buffer sizes		
CAN 2/4 Version 1	16MB	838,860 messages
CAN 4 Version 2	16MB	838,860 messages

The buffer time for a particular buffer size depends on the bus load and CAN bit rate. It is easy to compute using the above information (a 500 kbit CAN bus handles about 3600 messages per second).

If, for example, we have

- > 50 bus load, 500 kbit rate -> 1800 messages/s and
- > 4 CAN channels

we can calculate the time t until the buffer is full:

$$t = \frac{838860 \text{ messages}}{4*1800 \text{ messages/s}} = 116.5 \text{ s}$$

(Note: In a two-channel expansion module, the buffer is distributed on only two nodes, so the buffer available per node is twice as large and, as a result, the maximum buffer time is twice as long.)

The current implementation uses FIFO memory. In the event of buffer overflow, you lose any data arriving while the memory is full.

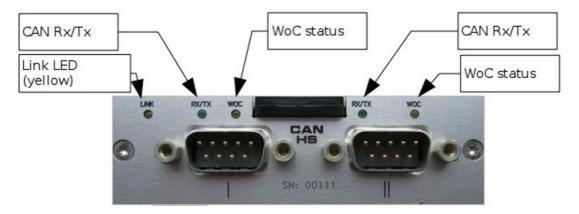
Overflow can occur if booting time is excessively long. This can occur if, at an unfavorable moment, the power supply drops, so the logger shuts off without shutdown. In certain cases, the operating system will then perform a disk consistency check, which can take a minute or longer. The logger will always boot, as the operating system is robust against sudden voltage drops. You must take this possible circumstance into consideration, though, when calculating the length of the booting phase.

# 3.6.1.2 Switching Output for External Hardware (not CAN interface v2)

On the one hand, an external voltage level can start the logger, as well as any external hardware such as CAN measurement modules (thermo, analog, ...). Conversely, CAN signals can start the logger (WoC). In that case, the logger must produce a control signal to initiate the power-up process in the external measurement hardware.

The switching voltage is provided by the logger to the nine-way D-Sub sockets of the CAN channels. The signal consists of a galvanically separate 5 V TTL voltage on pin 1 of the 9-pin D-Sub. The corresponding ground (galvanically separate from the system power supply) is on pin 6.

# 3.6.1.3 Assigning the connections



CAN interface - front plate of two-channel module (four-channel module is comparable)

CAN Interface LEDs	Comment
Link LED (yellow)	Data transfer from the interface to the logger
CAN Rx/Tx (green)	Data transfer on the CAN channel
WoC (yellow)	"Wake on CAN" status (for more on blink codes,
	see Table 2.6.1-3)

CAN channel LEDs

# 

WoC status LED (blink co- des)	Comment
Off	WoC not activated
Short, double	WoC activated and waiting for CAN signal (to
	wake the logger)
Lit (steady)(basic plat-	WoC with "No Message Loss" activated and wai-
form Log LED is off)	ting for CAN signal (to wake the logger)
Fast blinks	This CAN channel has woken the logger (logger is
	starting)
Lit (steady)	CAN interface is in operation and measuring

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#### WoC LED Blink codes for the CAN channel

Pin	CAN D-Sub Assignment
1	TTL signal for the switch module (galvanically isolated from supply)
2	CAN Low (galvanically isolated)
3	GND
6	GND for TTL switch voltage (galvanically isolated from power supply)
7	CAN High (galvanically decoupled)

#### CAN channel D-Sub plug assignment



# CAN interface - four-channel module front plate version 2

Pin	CAN LEMO Assignment
1	CAN High (not galvanically decoupled!)
2	CAN Low (not galvanically decoupled!)
3	n.c.

# CAN channel LEMO jack assignment

The functions of the LEDs and blink codes are identical to those of the D-Sub version.



# Four-channel module:

Dimensions (W x H x D): Weight:	168 mm x 25 mm x 119 mm approx. 260 g
Input voltage:	6 - 50 V DC
Operating temperature:	-40 °C to +85 °C
Connectors:	4 x 9-pin D-Sub male
Number of channels: Current draw:	four channels in standby, 0.145 mA (12V) in standby with WoC, 19.5 mA (12V) in standby with WoCnml, 106.5 mA (12V) in operation, 150 mA (12V)

# Two-channel module:

Dimensions (W x H x D):	84 mm x 25 mm x 119 mm
Weight:	approx. 146 g
Input voltage:	6 - 50 V DC
Operating temperature:	-40 °C to +85 °C
Connectors:	2 x 9-pin D-Sub male
Number of channels:	two channels
Current draw:	in standby, 0.155 mA (12V)
	in standby with WoC, 10.5 mA (12V)
	in standby with WoCnml, 70.5 mA (12V)

# Four-channel module version 2:

Dimensions (W $x$ H $x$ D):	84 mm x 25 mm x 119 mm
Weight:	approx. 150 g
Input voltage:	6 - 50 V DC
Operating temperature:	-40 °C to +85 °C
Connectors:	LEMO EGG.0B.303.CLL
	mating plug: LEMO FGG.0B.303.CLAD
Number of channels:	four channels
Current draw:	in standby, 0.130 mA (12V)
	in standby with WoC, 3.1 mA (12V)
	in standby with WoCnml, 39.6 mA (12V)
	in operation, 80 mA (12V)

# 3.6.2 LIN

The models currently available are a galvanically separate LIN slide-in module with two LIN channels (half-width), and a not galvanically separate LIN slide-in with four LIN channels (half-width). This means that per expansion chassis unit up to eight LIN channels are available. These modules are equipped with Wake on LIN (WoL) functionality.

in operation, 110 mA (12V)

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In this context, Wake on LIN means that any LIN signal on one or more of the LIN channels can start the logger. You can even specify that the content of a specific message bit be used to trigger start. (For details about starting and stopping with WoL, see Error: Reference source not found, Error: Reference source not found and the following chapter.)

The LIN modules operate in the logger only in "slave mode".

### 3.6.2.1 Input Buffer

Logger booting time is currently approx. 20 seconds. During this time, any data in the LIN interface is buffered. Once booting procedure is completed, the data is transferred to the logger. Buffer size is 16 MB per slide-in module.

# 3.6.2.2 Power Supply on the LIN Channel

Supply voltage is typically provided through the LIN wiring set. If this voltage is missing or is lower than 10V, there is an auxiliary power supply to the LIN interface. In other words, a LIN connector supplying only signal GND and LIN data can operate at the interface.

### 3.6.2.3 Setting the Baud Rate

The LIN interface has automatic baud rate recognition. This means the baud rate need not be set in the configuration.

# 3.6.2.4 Connection Assignment



#### LIN interface - two-channel module front plate

LIN Interface LEDs	Comment
Link LED (yellow)	Data transfer from the interface to the logger
LIN Rx/Tx (green)	Data transfer on the LIN channel
WoL (yellow)	"Wake on LIN" status (for more on blink codes, see
	Table 2.6.2-2)

#### LIN channel LED functions



# 

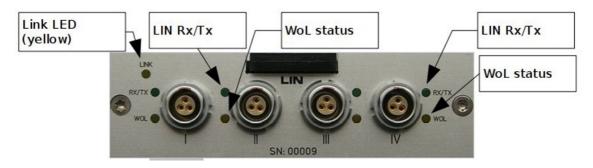
WoL status LED (blink co- des)	Comment
Off	WoL not activated
Short, double	WoL activated and waiting for LIN signal (to wake
	the logger)
Fast blinks	This LIN channel has woken the logger (logger is
	starting)
Lit (steady)	LIN interface is in operation and measuring

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#### LIN module WoL LED blink codes

Pin	LIN D-Sub Assignment
1	TTL switch voltage for switch module (galvanically isolated from sup-
	ply)
3	GND
6	GND for TTL switch voltage (galvanically isolated from power supply)
7	DATA-LIN (galvanically isolated from power supply)
9	VCC-LIN

#### LIN module D-Sub plug assignment



#### LIN interface - four-channel module front plate version 2

Pin	LIN LEMO Assignment
1	DATA-LIN (not galvanically decoupled!)
2	n.c.
3	n.c.

#### LEMO jack assignment for the LIN channel

The functions of the LEDs and blink codes are identical to those of the D-Sub version.

#### 3.6.2.5 Technichal Data

#### Two-channel module:

Dimensions (W x H x D): Weight: 84 mm x 25 mm x 119 mm approx. 145 g

Changes and errors excepted.

Input voltage:
Operating temperature:
Connectors:
Number of channels:
Current draw:

6 - 50 V DC -40 °C to +85 °C 2 x 9-pin D-Sub male two channels in standby, 0.16 mA (12V) in operation, 120 mA (12V)

### Four-channel module version 2:

Dimensions (W x H x D): Weight:	84 mm x 25 mm x 119 mm approx. 156 g
Input voltage:	6 - 50 V DC
Operating temperature:	-40 °C to +85 °C
Connectors:	LEMO EGG.0B.303.CLL mating plug: LEMO FGG.0B.303.CLAD
Number of channels: Current draw:	four channels in standby, 0.20 mA (12V) in standby with 4 x WoL, 50 mA (12V) in operation, 115 mA (12V)

### 3.6.3 FlexRay

Currently available are half-width FlexRay slide-in modules with two FlexRay channels, each configurable as an A or B channel. This means that per expansion chassis unit up to four FlexRay channels are available. These modules are equipped with Wake-on-FlexRay functionality (WoFR).

#### 3.6.3.1 Input Buffer

Logger booting time is currently approx. 20 seconds. During this time, any data in the FlexRay interface is buffered. Once booting procedure is completed, the data is transferred to the logger. Buffer size per slide-in module is 128 MB.

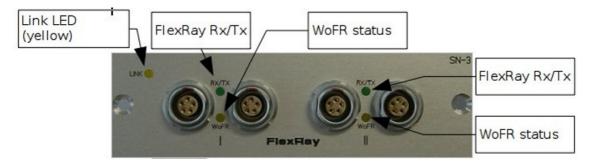
# 3.6.3.2 Timing Parameters

Due to the method used for signal acquisition on the bus, the FlexRay interface needs no additional parameters to define the exact timing on the bus. Therefore, they require no specification in the configuration, providing messages or signals need only be received and not sent (see also Chapter Error: Reference source not found Error: Reference source not found).

# 3.6.3.3 Connection Assignment







FlexRay interface - two channel module front plate

LED FlexRay Interface	Comment
Link LED (yellow)	Data transfer from the interface to the logger
FlexRay Rx/Tx (green)	Data transfer on the FlexRay channel
WoFR (yellow)	"Wake on FlexRay" status (for more on blink co-
	des, see Table 2.6.2-2)

#### Flexray module LED functions

WoFR status LED (blink codes)	Comment
Off	No WoFR activated
Short, double	WoFR activated and waiting for FlexRay signal (to wake the logger)
Fast blinks	This FlexRay channel has woken the logger (log- ger is starting)
Lit (steady)	FlexRay interface is in operation and measuring

#### FlexRay module WoFR LED blink codes

Pin	FlexRay LEMO Assignment
1	Reserve (shield)
2	BP in
3	BM in
4	BP out
5	BM out

FlexRay module LEMO jack assignment

Per FlexRay channel there are two five-pin Lemo sockets, whose PINs are connected straight through. This offers a variety of connection possibilities, from a simple branch line to looping right into the bus.

#### 3.6.3.4 Technical Data

Size (W $\times$ H $\times$ D):	84 mm x 25 mm x 119 mm
Weight:	approx. 165 g

Changes and errors excepted.

Input voltage: Operating temperature: Connectors:

Number of channels: Transceivers: Controllers: Memory: Current draw: 6 - 50 V DC -40 °C to +85 °C LEMO EGG.0B.305.CLN mating plug: LEMO FGG.0B.305.CLAD two (either A or B channel possible) 2 x TJA1080 2 x Fujitsu MB88121B 128 MB in standby, 0.26 mA (12V) in standby with WoFR, 5 mA (12V) in operation, 340 mA (12V)

# 3.6.4 Analog/Digital I/O

The currently available unit is a (half-width) Analog/Digital I/O (ADIO) slide-in module with eight analog channels, eight digital bit inputs and eight digital bit outputs.

# 3.6.4.1 Input Buffer

Logger booting time is currently approx. 20 seconds. During this time, any data in the ADIO interface is buffered. Once booting procedure is completed, the data is transferred to the logger. During booting, digital outputs are not addressed and remain in a defined start state (no bit set). Once the logger firmware is fully started and backlog execution has been started, the digital outputs are also activated. Buffer size is 8 MB per slide-in module.

# 3.6.4.2 Sampling Rate

Each channel of the ADIO interface can be independently parameterized with a sampling rate in the range of 0.1...1000.0 Hz. The digital outputs are activated when needed, i.e. upon value change, with a maximum rate of 100 Hz (for more information, see Chapters Error: Reference source not found, Error: Reference source not found and Error: Reference source not found).

# 3.6.4.3 Connection Assignment



**IPETRONIK** 



#### ADIO interface - front plate

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LET ADIO Interface	Comment
Link LED (yellow)	Data transfer from the interface to the logger

Pin	ADIO LEMO Analog Input Assignment
1	Analog input channel 1 + or 5 +
2	Analog input channel 1 - or 5 -
3	Analog input channel 2 + or 6 +
4	Analog input channel 2 - or 6 -
5	Analog input channel 3 + or 7 +
6	Analog input channel 3 - or 7 -
7	Analog input channel 4 + or 8 +
8	Analog input channel 4 - or 8 -
9	GND
10	GND

LEMO jack assignment at the analog input

For analog input, the ADIO provides two jacks, for the channels 1 - 4 and channels 5 - 8 respectively. Though these are differential inputs, it may be useful to connect the ADIO grounds (GND) with the ground of the voltage source to be measured, so as to create a common reference potential.

Pin	ADIO LEMO Digital Input Assignment
1	Digital input bit 1
2	Digital input bit 2
3	Digital input bit 3
4	Digital input bit 4
5	Digital input bit 5
6	Digital input bit 6
7	Digital input bit 7
8	Digital input bit 8
9	Digital GND
10	Digital GND

LEMO jack assignment for digital input

Always connect the digital inputs to a fixed reference ground. The switching threshold between high (=1) and low (=0) level is approx. 1.5 V DC.

Pin	ADIO LEMO Digital Output Assignment
1	Digital output bit 1
2	Digital output bit 2
3	Digital output bit 3
4	Digital output bit 4
5	Digital output bit 5
6	Digital output bit 6
7	Digital output bit 7
8	Digital output bit 8
9	Digital GND
10	Digital GND

CAETE(

LEMO jack assignment for digital output

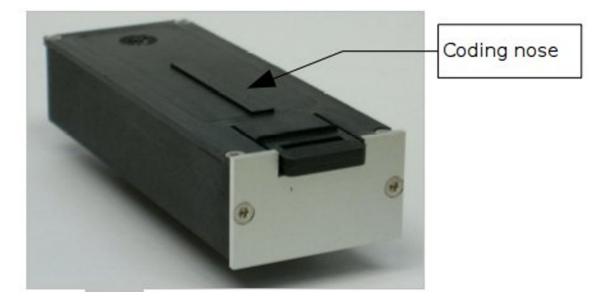
The digital outputs function as switches, for connecting the particular connection pin to ground. If a logical 0 is applied, they are open; they are closed if a logical 1 is applied. In combination with the appropriate external switches, it is thus possible to control external devices (e.g., relays, LEDs).

# 3.6.4.4 Technical Data

Dimensions (W x H x D): Weight: Input voltage: Operating temperature: Connectors:	84 mm x 25 mm x 119 mm approx. 180 g 6 - 50 V DC -40 °C to +85 °C Analog input: LEMO EEB.2B.310.CLN mating plug: LEMO FGB.2B.310.CLAD Digital input: LEMO EEG.2B.310.CLN mating plug: LEMO FGG.2B.310.CLAD Digital output: LEMO EEA.2B.310.CLN mating plug: LEMO FGA.2B.310.CLAD
Number of channels:	2 x four analog channels 8 digital bit inputs 8 digital bit outputs
Measuring range:	Analog input: ±60 V, 16-bit resolution (1.8 mV) Digital input: 060 V switching threshold at approx. 1.5 V input resistance: 1 MOhm Digital output switching voltage: 060 V Max. switching current: 250 mA
Memory: Current draw:	8 MB in standby, 0.13 mA (12V) in operation, 68 mA (12V)

# 3.7 Interface Modules for the Upper Expansion Chassis Unit

All the modules for the upper expansion chassis unit have a coding nose. This ensures that they are operated only in an upper expansion unit.



USB dummy module for the upper expansion chassis unit

# 3.7.1 WiFi

#### 3.7.1.1 Applications

The WiFi module is another channel (like a memory stick, for example) for transmitting recorded data from the logger to an external computer, such as a server station, or for importing new configurations. Data transfer that is started when the logger is shut down, for example, can be directed to the WiFi module.

The module is only activated when data transfer is started, and is inactive during measurement operation. This increases data security – a WiFi that is inactive cannot be misused for unauthorized data transmission. Moreover, this reduces total current draw of the measurement system.

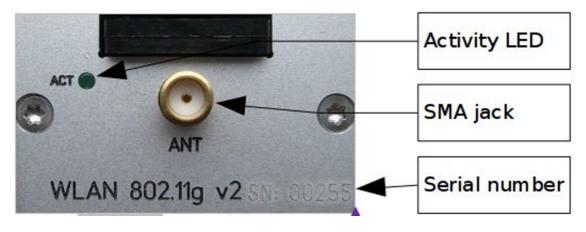
Conversely, it isn't possible to use the logger's WiFi port for continuous measurement-data transfer or for data display during measurement.

# 3.7.1.2 Module Placement





3.7 INTERFACE MODULES FOR THE UPPER EXPANS,



V2 WiFi module

The module is a quarter-unit wide and can be operated in any slot within a given chassis unit. Neither its position within a chassis unit nor the chassis level it occupies requires specification during configuration.

# 3.7.1.3 Configuration parameters

Each module has a fixed MAC address. During module activation, the IP address is either, depending on its configuration, dynamically assigned (DHCP server) or set from the logger.

	ARCOS WLAN Interface V2
	ARCOS WEAR Interface VE
P	N: 100654
	MAC Adress 00:0D:F0:55:01:C9 ]

# V2 WiFi module bottom

The MAC address is very often used by system administrators to protect networks against unauthorized use. When replacing modules, make sure the used module has authorized access to the required networks. For this purpose, the sticker on the bottom of the module has the MAC address printed under the product number (Illus. above).

In the case of the µCROS, you can obtain the MAC address from CAETEC (please specify the µCROS serial number). Due to lack of space, there is no sticker, so the address must be read by software from the module.

In the case of built-in modules, you can list MAC addresses according to the respective serial numbers printed on the front of the module.

With firmware Version 1.3 and higher, the option of transferring data via WLAN, DT\_WLAN, must be enabled in the logger. Without activation no data transfer is possible.

# 3.7.1.4 Technical Data

Dimensions (W x H x D)	ARCOS: 42mm x 25mm x 114mm
	µCROS: 25mm x 8mm x 80mm
Weight	ARCOS: approx. 63 g
	µCROS: approx. 14 g
Operating temperature	-40°C bis +85°C
Input voltage	ARCOS: 6 50 V DC
	µCROS: 6 36 V DC
WLAN	Standard 802.11g/n, 2.4 Ghz
	Maximale Rate 54 Mbit/s
	Sicherheitseinstellungen nach WPA-PSK und WPA-
	EAP
	Zugriff nur über Infrastruktur (Access-Point),
	Adhoc - Verbindung nicht möglich für ARCOS
	und µCROS gültig
Current draw	approx. 40 mA

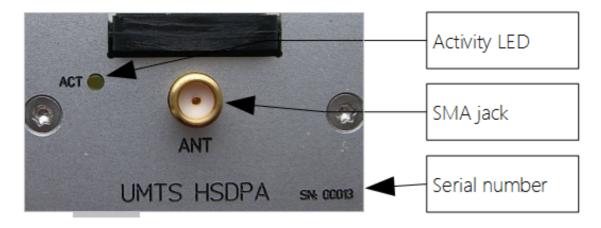
# 3.7.2 UMTS

# 3.7.2.1 Applications

The UMTS module is (like a memory stick or WLAN) another channel for transmitting recorded data from the logger to an external computer, such as a server station, or for importing new configurations. Data transfer that is started when the logger is shut down, for example, can be directed to the UMTS module.

The module is activated only once data transfer is started, and is inactive during measurement operation. This increases data security a mobile telephone connection that is inactive cannot be misused for unauthorized data transmission. Moreover, this reduces total current draw of the measurement system.

### 3.7.2.2 Module Placement



#### UMTS module

The module is a quarter-unit wide, and can be operated in any slot within the given chassis unit. Neither its position within a chassis unit nor the chassis level it occupies requires specification during configuration.

UMTS Interface ACT LED (yel- low)	Comment
Fast blinks	No connection to a network carrier.
Slow blinks	Connected to a network carrier.

Figure 1: UMTS interface LED functions

# 3.7.2.3 Configuration Parameters

Each module has a fixed IMEI number, with which the module accesses the particular mobile telephone network. During module activation, the IP address is dynamically assigned upon registration with the service provider.

ARCOS	UMTS HSDPA I	nterface	
PN: 100825 [ IMEI:	352636020095449		

Bottom view of UMTS module

The IMEI number uniquely identifies a mobile telephone subscriber and can be used by system administrators to protect networks against unauthorized use. When replacing modules, make sure the used module has authorized access to the required networks. For this purpose, the sticker on the bottom of the module has the IMEI number printed under the product number (Illustration above).

In the case of the  $\mu$ CROS, you can obtain the IMEI number from CAETEC (please specify the  $\mu$ CROS serial number). Due to lack of space, there is no sticker, so the address must be read from the module by software.

In the case of built-in modules, you can list IMEI numbers according to the respective serial numbers printed on the front of the module.

The option for transferring data via UMTS, DT\_PPP, must be enabled in the logger. Without activation no data transfer is possible.

# 3.7.2.4 SIM Card

Operation of the UMTS module requires a SIM card.

The SIM card must configured without PIN number request (the logger does not support PIN number input!) and be authorized for data connection.

To insert the SIM card, remove the ARCOS module from the logger (after unplugging the power supply from the logger!) and the lid by removing the four screws. Once you have inserted the SIM card into the card holder (with the card oriented correctly), close the module. Slide it into the chassis unit, plug in an UMTS antenna and the module is ready for operation.

To insert the SIM card in the  $\mu$ CROS, first open the module by removing the four screws on the front. On the bottom you will find the UMTS module with card holder. Once you have inserted the SIM card, carefully slide the  $\mu$ CROS back into the housing. As you slide it back, you may have to push the UMTS module down by pressing on the card holder to avoid damaging it. Plug in a UMTS antenna and the module is ready for operation.

# 3.7.2.5 Technical Data

Dimensions (W x H x D)	ARCOS: 42mm x 25mm x 114mm
	μCROS: 35mm x 10mm x 80mm
Weight	ARCOS: approx. 63 g
	µCROS: approx. 31 g
Operating temperature	-40°C bis +85°C
Input voltage	ARCOS: 6 50 V DC
	µCROS: 6 36 V DC
UMTS	HSDPA (Downlink 7.2 Mbps, Uplink 384 kbps)
	UMTS/HSDPA (WCDMA/FDD) 2100 MHz
	Quad-Band EGSM 850/900/1800/1900
	GPRS multi-slot class 12
	EDGE multi-slot class 12
Antenna	SMA jack in the module, fo connecting a stan-
	dard GSM/UMTS antenna wit SMA plug. Thios is
	required for operation.
Current draw	approx. 40 mA

# 3.7.3 GPS/Galileo

# 3.7.3.1 Applications

With an update rate of 4 Hz, the GPS/Galileo module provides global position data, which can be recorded as additional signals, parallel to the CAN data.

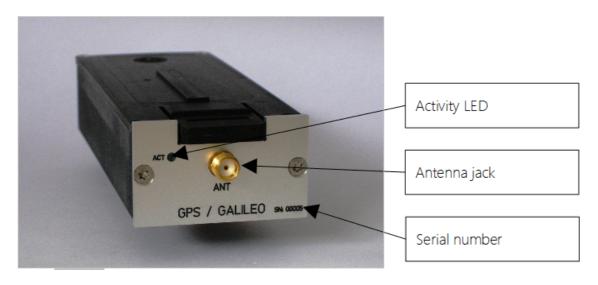
The receiver can process signals from the US GPS system or, alternatively, once the appropriate firmware has been downloaded to the module, the signals from the future European system Galileo .

The last received satellite data is stored in the module in persistent form, which saves startup time, providing the satellites are still available.

Currently, the time information in the GPS signal is not used for time control.

This module is only supported by logger firmware version 1.0 and higher.

### 3.7.3.2 Module Placement



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GPS/Galileo module

The module is a quarter-unit wide and can be operated in any slot within the given chassis unit. Neither its position within a chassis unit nor the chassis level it occupies requires specification during configuration.

GPS Interface ACT LED (yel- low)	Comment
Blinks	Blinks upon GPS fix, i.e. once a valid position has been determined. Simultaneously data output begins.

Figure 2: GPS interface LED functions

# 3.7.3.3 Configuration parameters

The following values can currently be recorded as signals:

- number of received satellites
- longitude (°)
- latitude (°)
- current velocity (km/h)
- compass (heading) (°), N=> 0°
- elevation above sea level (m)
- status (no connection (=0), connection (=1), Egnos (=2))
- GPS date

Changes and errors excepted.



- GPS time and
- quality of precision (the raw value, directly acquired from the GPS signa, is converted to measurement uncertainty (in m), with a probability of 95%)

The values status and number of received satellites are transmitted by the module as soon as it is recognized by the logger. All other values are sent after the first GPS fix, i.e. once a valid position has been determined. Until then they have the value NaN (Not a Number).

# 3.7.3.4 Technical Data

Dimensions (W x H x D)	ARCOS: 42mm x 25mm x 114mm
	µCROS: 25mm x 8mm x 80mm
Weight	ARCOS: approx. 65 g
	µCROS: approx. 18 g
Operating temperature	-40°C bis +85°C
Input voltage	ARCOS: 6 50 V DC
	µCROS: 6 36 V DC
GPS	Requires an active antenna, with phantom power
	supply (approx. 3 to 3.3 V)
	SMA jack
	maximum rate, 4 Hz
	sensitivity, -148 dBm
	Start-up time, approx. 34 seconds (with good sa-
	tellite visibility)
	precision, 2.5 CEP
Current draw	approx. 45 mA

# 3.8 Mounting the Slide-In Modules

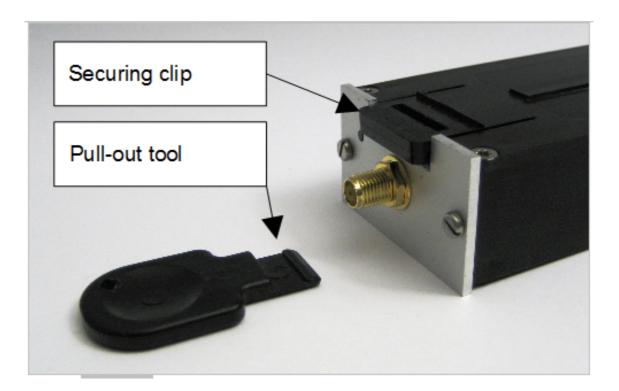
# 3.8.1 Mechanical Installation

The slide-in modules for both chassis units (upper, as well as lower) are not screwed, but only clipped into place. A plastic clip at the front secures the slide-in module. This clip can be released either with the pull-out tool, as shown in the illustration below, or manually, by pressing it down. The slide-in module is then simply pulled out.

The modules should only be removed or inserted after disconnecting the power. This is necessary, on the one hand, to protect the modules electrically, but also because of the initialization procedures performed once the logger is started.

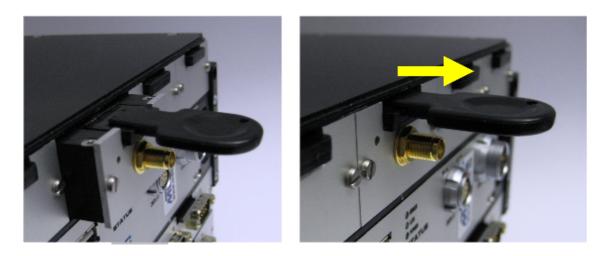


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Securing clip on slide-in module, with pull-out tool.

Insert the pull-out tool, with the hook pointed downward, into the gap between the clip and the chassis unit housing. Once it clicks into place, pull it out, along with the slide-in module (see illustration below).



With the tool inserted, the module can be slid out.



### 3.8.2 Initializing the modules

# 3.8.2.1 Upper Expansion Chassis Unit

The slide-in modules of the upper expansion chassis unit require no manual connection establishment. These modules (GPS, WLAN, etc.) are automatically initialized when the logger is started. However, they do not appear on the Web interface.

### 3.8.2.2 Lower Expansion Chassis Unit

A variety of different LIN, CAN, FlexRay and Analog/Digital I/O interfaces can be combined here. The modules of a given type must be assigned channel numbers so that the logger can unambiguously assign a channel jack to the signal configurations. The numbering of each module type must be unambiguous; e.g., the number of each CAN channel is unique, and each LIN channel has a unique number with respect to other LIN channels. It is permitted though to have a LIN module numbered one, while a CAN module has the number one, as well. Numbering need not be consecutive (though it is recommended!).

This number must also be assigned after each replacement or addition of an interface, using the individual serial number of the specific interface.

The assignment of a node number to an interface is done through the Web interface included in the logger firmware, and which is used for all interface types (see Manual Web Interface).

# 3.8.2.3 Adjusting for Changes in Installed Interfaces

Once the Web interface is started, all the interfaces are displayed that either were already recorded in the logger or are found as new. The Actions/Delete function can be used to delete all the interfaces reported to be offline.

Upon system start, the logger searches for all the interfaces that have been assigned an offset value. If any module is no longer installed in the logger, this will extend booting time, since the system continues searching for the particular module until a timeout marks it as offline. It is therefore recommended that you delete non-installed interfaces from the list.

In order for the nodes to be consecutively numbered, the offset must now be set in each interface. Within an interface, the nodes are numbered from the left to the right. If, for example, in a four-channel interface node, the numbers 5 to 8 are to be created, an offset of 4 must be set. After specifying the offset, it must be written to each separate module by clicking Send.

To identify a specific interface within the chassis unit stack, you can use the respective line in the list to activate the blink function. This causes all the activity LEDs of the specific interface to blink for approx. five seconds.

All settings are initially temporary and can be reversed using Restore logger settings . Only by clicking Write settings to logger are the settings permanently stored in the logger.



A node number is assigned to each interface as a component not to its position within a chassis unit! If the interface is re-plugged within the chassis units (e.g., from level 1 to level 3), it takes its node number with it.

If interfaces are replaced, the logger must be rebooted. This guarantees that the configuration settings are also set in the interface (WoX, No-Message-Loss, etc). Otherwise old settings might be used.

# 3.9 Display

The display is the input station for entering values in the logger, as well as the output station for displaying logger values and messages. Technically, measurement operation is always possible without a display. The display is hot-pluggable, meaning it can be connected or unplugged at any time during operation without loss of measured data.

If the display is unplugged and the configuration requires driver input, the system uses the configured default settings.

The display enables the logger operator to monitor measurement values and logger status, to select a Track and mark its end, as well as to set event markers in the log file (Trigger from display).

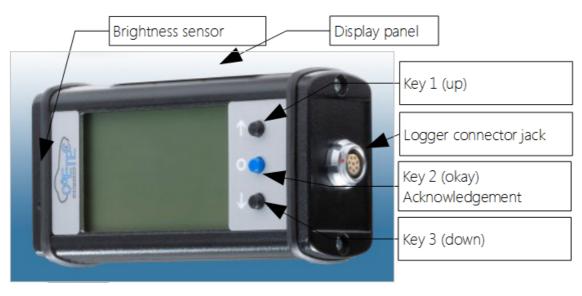
In addition, alarms and messages are output to the display, warning the driver about critical conditions of the test object.

These messages are displayed on a 4-line screen, with 20 characters per line, while the three keys control display content and acknowledge messages and alarms. The USB interface integrated in the display is at present nonfunctional.

To enable flexible display installation (choice of connections on the left or the right), display content can be rotated 180°. An integrated sensor adapts display brightness to ambient light, contrast is adjusted manually (the set value is automatically adjusted for temperature). The required parameters are set using an additional display dialog.



# 3.9.1 About the Connections and Keys



Display design

# 3.9.2 General Connection and Key Assignment

Operating the device involves no input of numbers or values. The display instead offers a selection (which, depending on the configuration, can comprise only a single entry). Keys 1 and 3 are for changing the selection. Once you have finished selection, you simply acknowledge by pressing okay, i.e. the middle (blue) Key 2.

Standard pressing duration for the okay key is approx. one second. This avoids hasty, unintentional acknowledgment. After a one-second delay, a brief confirmation tone sounds.

Key Assignment	
l (< l s)	Up
1 (> 1 s)	Fast up (accelerates the longer it is held).
2 (< 1 s)	Starts/Stops the list scan.
2 (> 1 s)	Switches the screen page, acknowledges input.
2 (> 3 s)	Sets a trigger mark in the log file.
3 (< 1 s)	Down
3 (> 1 s)	Fast down (accelerates the longer it is held).
1&2&3 (> 1 s)	Switches to the setting dialog.

Figure 3: Display key functions





Display Plug Pin Assignment	
1	Supply -
2	Supply -
3	Supply +
4	Supply +
5	Data 1 (RX+, orange and white)
6	Data 2 (RX , orange)
7	Data 3 (TX+, green and white)
8	Data 4 (TX , green)

Figure 4: Assignment of the Fischer display connection plug

# 3.9.3 Display During Start

As soon as the logger is started with a connected display, or when the display is plugged in during logger operation, the display and the logger start synchronization. For its duration, the start screen appears on the display, presenting the CAETEC logo above the text Waiting for logger.



Display with start screen

Aside from the text, three dots appear in sequence, providing information about the status of the connection being established. The following table explains the meaning of the dots.





Number	Current action
0 dots	Basic functions are initialized. The display is in operation but without external connections.
1 dot	The display has been assigned its network address by the logger; i.e. it is physically connected to the logger.
2 dots	The display has found the logger and begun com- munication.
3 dots	The display has imported the statistical data from the logger needed for operation (the number of channels, channel names, etc.)

Table 1: Meaning of the dots on the start screen.

Finally the screen switches to dynamic measurement-data display mode, if no track has been previously defined (cf. Chapter "System Start with Track Selection"  $\rightarrow$ 3.9.4.1). Once the logger is ready for measurement (with booting completed, yellow LOG LED lit or blinking), synchronization is generally completed within seconds.



If the display stops at three-dot status, this can indicate that no signals have been configured for output in which case, you must check and modify the configuration.



# 3.9.4 Operation

The following description of logger operation assumes a totally started logger, with connection established to the display (start screen has vanished).

### 3.9.4.1 System start without track selection

In this logger mode, the display switches directly to View measured data ( $\rightarrow$ 3.9.4.4). The user need not make any entry or selection. (Measurement is performed without track assignment, and file names are appended with a time stamp.) In all other respects, the display behaves the same as when the system is started with track selection, once that selection has been completed.

# 3.9.4.2 System start with track selection

When the system is started with track selection, you have two options:

- to select a new track, because either a new configuration with track selection is being applied for the first time or the last measurement was completed with End Track , or
- 2. to continue measurement with a track that was not yet completed.

### Case 1: Selecting a new track



Track selection screen (example)

The illustration above shows an example of the display screen for track selection. To start with, the first lines display the vehicle number (the path prefix taken from the configuration file), the version number of the configuration (cfg\_identity), together with the date and time. Next, the small black triangles prompt the driver to use the up/down keys to select the track from a list (stored in the logger). If there is no response, a steady tone sounds until the driver selects the track.

The next screen page (cf. Illustration below) shows the selected track. If a mistake has been made, the arrow keys can be used to change the selection. (Change from Have a good trip to Change, then acknowledge with okay thus returning to Selection.) If the selection is fine, acknowledge with okay (blue key). Brief warning tones, two seconds

Changes and errors excepted.



apart, prompt the operator to acknowledge. If the user fails to acknowledge the selection within 10 seconds, it is automatically acknowledged.



Dialog screen for confirming track selection.)

In summary:

- Press the up / down key to select the track, then end with okay (Key 2, duration > 1s).
- Confirm the selection with okay (Key 2, duration > 1s) (Drive safely). If necessary, use the up / down key to open Change and correct your selection.

If the display is plugged in after the system was started and no track has been assigned, the track is now selected. In other words, after plug-in, the same cycle takes place as occurs at system start with a plugged-in display. (On the other hand, if the display was unplugged during operation and then plugged back in i.e. after a track had already been assigned track selection is naturally not repeated.)



# Case 2: Continuing a track

The illustration below shows the screen for continuing a track or measurement. This dialog appears whenever the logger was shut down without ending a track. This can be useful, for example, when resuming track measurement after a break.



Dialog screen for continuing a track.)

Confirming this dialog with okay starts measured-value display (normal mode). If no entry is made within ten seconds, the logger automatically continues, with yes .

Should you at this point decide to change the track after all, simply switch to modify by pressing either of the arrow keys. Once the function modify is confirmed with okay, the display returns to the track selection dialog. The selection of a new track ends the current measurement and closes its data set, to begin a new one (standard procedure does not include data transfer. This is only started, if depending on the configuration, the measurement was ended by stopping the vehicle, for example, by means of a clamp 15 voltage drop).

During track selection, the logger continues to record measured data. Neither track selection itself nor the involved dialog interferes with data recording.



#### 3.9.4.3 Shutting down the system

System shutdown is initiated through Start/Stop signals at the logger. (The conditions depend on the configuration cf. Chapter Configuration). In other words, one cannot directly stop the logger from the display. However, certain shutdown circumstances require input from the operator, which is described here.

It may be necessary, depending on the configuration, to enter End Track or specify the data transfer destination. The illustration below shows the dialog that may display at shut-down.



End Track input dialog at shutdown.)

The default value for the End Track dialogue is no . If the operator fails to respond within approx. ten seconds, the logger shuts down without ending the track.

By using the arrow keys, the operator can switch from the default value no to yes and end with okay. If the operator selects no, the logger is shut down without further query. A yes reply closes the current data set. If the configuration is set accordingly, data transfer is then executed.

There are two alternatives for saving the data:

- transfer without operator input via a preset path; for example, always via WLAN, or
- transfer with operator input, i.e. selection of the transfer method.

If selection is the configured option, the user is first prompted to specify the target. The illustration below shows the involved dialog.



Changes and errors excepted.



### Selecting the data transfer target.)

In the example shown in Illus. 2.10.4-5, the display proposes USB as the target. Depending on what was activated in configuration, the operator can use the arrow keys to select from the following targets:

- WLAN
- USB
- PPP
- — (No target, therefore no transfer.)

Once WLAN, PPP or USB has been selected (and acknowledged with okay), transfer begins. The logger displays, during the transfer process, each step as it is executed subsequent screen pages indicate that the data set is being closed, packed (zipping) and transmitted. Depending on the quality of the connection, transfer via WLAN can take a while. The progress bar shows the transfer progress (in percentage), allowing you to estimate the total duration of the transfer.

If malfunction occurs during transfer, a screen page displays an error message (see Appendix). Then, after a ten-second timeout, the logger shuts down and switches off. As part of the data transfer process, the configuration and logger firmware are also updated. This involves the messages GetUpdate, Checking and Processing only briefly mentioned here, but described in full detail later.

For operation in track mode, please bear in mind that without an End of Track no data transfer takes place.

During data transfer, it is not possible to begin a new measurement. 1.3Depending on the configuration, a measurement can continue in parallel with data transfer, or a new one can be started.

# 3.9.4.4 Viewing measured data (Normal Mode)

After system start, the data is automatically displayed in normal mode. Normal mode means that the data channels are displayed consecutively, at five second intervals, in the order defined in the measurement configuration (Illustration below identified in the display by the word Live, along with a double arrow in the upper left corner).

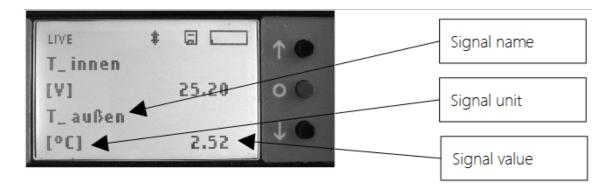
A single screen page displays up to two channels, with two lines per channel. The first line of each channel displays the channel name, followed by the unit and the current value in the second line.

In the event of a (configurable) signal timeout, the display shows horizontal lines (-.-) instead of a value. In the event of signal value overrun (e.g., division by 0 in computation, or an incorrectly scaled CAN signal), the text Infinity is displayed instead of a signal value.



By briefly pressing (arrow) Key 1 or 3, you can stop automatic scroll and change the screen manually. A longer press of this key starts a quick scroll through the measured data, keeping it pressed accelerates the stroll. The manually selected reading remains on display for a configurable duration (default value = 2 h), after which the system reverts to automatic scroll.

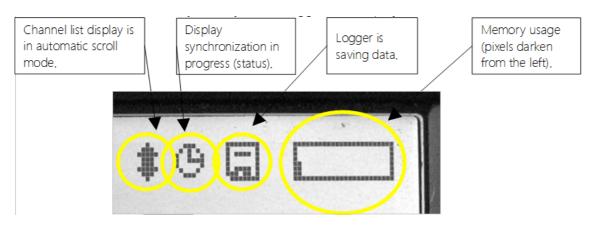
To activate automatic scroll sooner, all it takes is a brief press (<1 s, no tone) on Key 2 (blue). When automatic scroll is active, the symbol  $\uparrow$  appears at the upper edge of the display.



Normal display screen)



Four symbols in the upper right corner of the screen indicate memory card usage and memory activity of the logger, the display status and scroll mode.



Displayed logger status messages.)

The display status symbol (clock) indicates that, due to specific circumstances (e.g., following message display or a booting phase), the displayed measurement values are not totally synchronous with the current measured data and are being refreshed. Once this is completed, usually within seconds, the clock vanishes.

# 3.9.4.5 Displaying the Minimum/Maximum Values

Aside from displaying the current measurement values (normal display mode), you can also switch to viewing minimum/maximum values. In normal mode, you simply press the okay key (blue) until you hear a tone (approx. 1 second). This method is also used to switch from Min/Max display back to normal display mode.

The illustration below shows the Min/Max display screen, identified by the text MINMAX in the upper left corner of the display).



Min/Max display screen)

In two lines for each channel, the screen displays its name, unit and a pair of values. The value left of the separator / denotes the minimum, the value to the right is the maximum of the current track. For very long numeric representations, such as 12345.6/78901.2, the

Changes and errors excepted.



display is automatically shifted horizontally (horizontal scroll), so all the digits are visible.

As in normal mode, in Min/Max display mode it is possible to scroll either automatically or manually.

The minimums and maximums are valid for the duration of a track. If a single track spans multiple shifts/driver changes and pauses, the Min/Max value is valid across multiple logger starts.

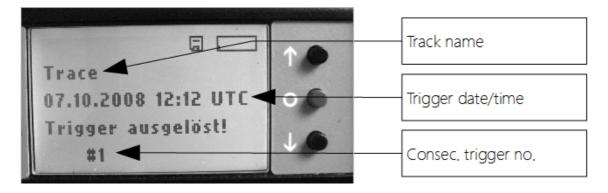
## 3.9.4.6 Setting Display Triggers

If anything unusual occurs during measurement, if events occur that need to be logged, you can mark the event via the display, by setting a trigger .

It is activated, during normal display or Min/Max display, by continuing to press the okay key beyond the first signal tone, until the screen shown in the Illustration below appears and a double tone sounds (after approx. 3 s).

In addition to the track name, the screen displays the date, time (UTC-standard!) and the track-specific consecutive number under which the trigger has been set. After approx. five seconds, the display automatically switches from the trigger screen back to the previous screen.

The time, date and number uniquely identify the trigger. Other information specifying what happened at the time of the trigger can be added later (e.g., in a driver s report).



Display screen after activating a trigger.

Through its name 'trig\_display', this trigger can be configured, for example, to start methods or data transfer. You should bear in mind though, that the display trigger is only a trigger pulse with a duration of two seconds, as opposed to the parameterized triggers.

The trigger is recorded in the log file of the measurement.

Example of an entry in the log file:



... 2008-10-01 13:54:25; TRIGGER; Display; 1 ...

## 3.9.4.7 Displaying Settings Dialogs

The setting dialogs set parameters in the display or show status information (e.g., software versions, contrast settings, etc.):

Display Setting Dialog	Function
Language1 <sup>1.20</sup>	Sets the dialog language.
Illumination opt.	Sets the max. brightness of background illumina-
	tion (control range)
Contrast	Sets the contrast.
CPU load	Displays the usage of the CPU.
Memory usage	Displays the used space on the memory card.
Rotate display	Rotates the display screen 180°.
Restart logger	Ends the current measurement and restarts the
	firmware without booting the logger.
Softw. versions	Displays the software versions of the display,
	dL (logger firmware) and pC (power control-
	ler/front).
Expanded menu <sup>1.20</sup>	Sets the signal tone (on/off).
Use default settings	Resets display brightness, contrast and rotation to
	the factory defaults.
Close menu	Ends the setting dialog.

Figure 5: Setting dialogs for configuring via display.

The dialogs marked <sup>1.20</sup> are only available with display firmware version 1.20 and higher.

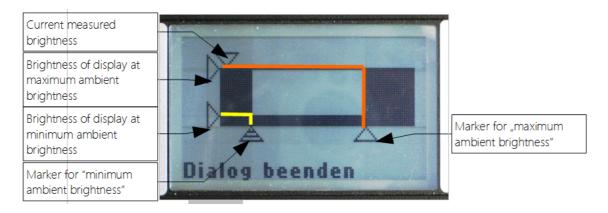
To start the display mode for the setting dialogs, simultaneously press all three keys. To end, select the dialog item Close menu. Keys 1 and 3 shift input from one field to another (the first character is inverted as a cursor). Longer pressing of Key 2 starts and ends the setting dialog and switches the screen back to the previous menu item.



## Setting the Illumination Options

The display is equipped with a brightness sensor that responds to ambient brightness. You can use the dialog Illumination opt. to set the brightness of the background illumination with regard to the surroundings.

This dialog offers the setting options shown in the figure below:



Setting dialog for the illumination options.

The unshaded surface within the markers defines the active range, within which the brightness of the background illumination is regulated according to the sensor value.

The triangle at the upper edge shows the current value measured by the sensor. In darkness, it moves toward the left, with increasing brightness toward the right.

The colored lines highlight the pairs of triangles defining the brightness of the display with respect to the ambient brightness (2-point representation). The yellow pair defines the point of least brightness, the orange pair defines the point of highest brightness of the background illumination.

Use the left triangle under the graph to set the level of ambient brightness below which the display should not get darker. The corresponding triangle at the left edge defines how bright the display should then be.

Use the right triangle under the graph to set the level of ambient brightness above which the display should not get brighter. The corresponding triangle at the left edge defines how bright the display should then be.

The setting markers can be shifted, using the arrow keys. The markers set the border ranges for illumination control.

- With the display arrow keys, select the particular setting marker (this is then displayed as hatched). Acknowledge selection by pressing Okay for one second (marker is then displayed as solid).
- Use the arrow keys to shift the activated marker.

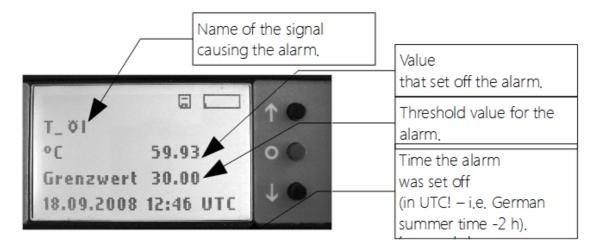
Changes and errors excepted.



- The marker shift must also be acknowledged by pressing Okay for one second. Then proceed to the next marker.
- Exit the dialog by marking the text Exit dialog and then pressing Okay for one second.

## 3.9.4.8 Alarm Management for Limit Violation

If a signal deviates from a valid range into an alarm range, a warning tone sounds, while the screen in the illustration below is displayed.



Display screen for a signal alarm (example).

The first item displayed is the name of the signal that set off the alarm. Next you see the value of the signal that set off the alarm, and which threshold (= limit) was set for the alarm, followed by the time when the alarm occurred.

The warning tone sounds until the message is acknowledged by briefly pressing the Okay key. Another press on Okay > 1 second returns the display to normal mode, unless another alarm has occurred, in which case the next alarm is displayed. Alarms are collected and then, one after the other, are output to the display.

In the event of repeated alarms set off by a signal, after the fifth acknowledgment (counting all violations of upper and lower thresholds) you are given the option of permanent acknowledgment indicated by the displayed prompt Alarm off (cf. Illustration below).



Changes and errors excepted.







#### "Alarm off" prompt, displayed after the fifth alarm (example).

Once this dialog is acknowledged by pressing Okay (Key 2) for longer than three seconds, there is a single signal tone, followed after approx. three seconds by a double tone. Alarms for this signal are subsequently suppressed for the duration of the current measurement (track). No further limit violations are reported for this signal until the measurement is ended or a new track is selected.

Whenever a signal is outside the valid range from the beginning, from logger start-up, instead of producing a warning for the signal, the system writes a log file entry. Whenever a signal remains in the alarm range, warnings are set off at ten-minute intervals.

Violations of alarm limits are recorded in the log file. Here are a few examples of pertinent log file entries:

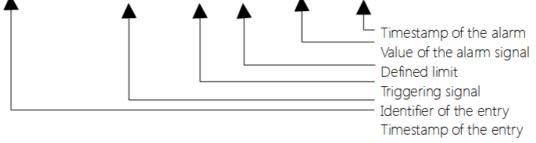
Entry for a signal running out of the valid range:

Entry for a signal running out of the valid range:

2007-12-13 14:30:18; OUT OF LIMIT; T\_OIL; 30.000000; 30.146844, 1, 2007-12-13 14:30:18

Entry for a signal entering the valid range:

2007-12-13 14:30:20; INSIDE LIMIT; T\_OIL; 30.000000; 29.956109; 2007-12-13 14:30:20



Entry, with "Alarm off":

2008-06-06 07:40:11; LIMIT WARNING; OFF; T\_OIL



### 3.9.4.9 Handling Messages

Messages are texts that can be freely defined within the configuration. They are displayed once a signal trigger occurs. This means that messages can be used in any situation where a trigger can be defined for a signal.

The example in the Illustration below shows a message that appears when a temperature exceeds the value of 50°C.



Message with the free text "Temperature above  $50^{\circ}$ C".

The screen displays (line by line, from the top) the name of the configuration (pathprefix), the message text itself, and the date and time when the message has occurred.

The message remains on the screen until it is acknowledged by pressing Okay (= Key 2, with signal tone confirmation).

Like alarms, messages are collected in the background. In the event that additional alarms or messages occur during message display, they are displayed one after the other. Once a displayed message is acknowledged, the next one appears.

Just like with alarm messages, it is possible to permanently acknowledge free-text messages.

If so configured, each message can also be recorded in the log file.

Log file entries (excerpt example):

(1) 2008-08-25 08:30:48; START METHOD; Message 2; 2008-08-25 08:30:48
(2) 2008-08-25 08:30:48; NOTIFICATION; Memory 90% full
(3) 2008-08-25 08:30:49; STOP METHOD; Message 2; 2008-08-25 08:30:49
(4) 2008-08-25 08:30:55; NOTIFICATION WARNING; OFF; Message 2
...

Meaning:

- (1) Message 2 was triggered.
- (2) The text for Message 2 was displayed.
- (3) Message was acknowledged.
- (4) Message was switched off for the duration of the track.



# **IPTRONIK**

## 3.9.5 Technical Data

Dimensions (W x H x D): Weight: Operating temperature: Input voltage: Maximum line length: Maximum pressure on key: Current draw: 115 mm x 60 mm x 33 mm approx. 210 g -20 °C to +70 °C 6 - 50 V DC approx. 10 m 30 N (3 kg) for 3 seconds

approx. 100 mA 12 V



# 4 Configuration

# 4.1 General Information

## 4.1.1 Basic Principles

The logger is configured through an ASCII file. This file contains all the parameters for the logger. If LAPI-capable measurement modules are used for the CAN channels, the configuration file can also include the LAPI. The settings enable the logger to configure any LAPI measurement modules connected to the CAN bus.

It is equally possible, though to conventionally configure the measurement modules, without LAPI, thus treating them as conventional CAN users. In this case, only the CAN parameters for the module signals are declared in the logger configuration, and the logger performs no further configuration of the measurement modules.

This means it is possible to configure the modules in advance, separately from the logger, and then to give the logger a configuration file dealing only with data recording.

The only section of the ASCII file where conventional configuration differs from LAPI configuration is that containing the module configuration. The remainder is identical.

The logger can only configure the CAN measurement modules via LAPI if a driver exists for each module type, and the measurement module must be LAPI-capable (cf. the LAPI specifications).

The configuration file, regardless of whether it includes a LAPI section, is imported by the logger during the next data transfer. The file is then analyzed and stored in the logger. Any newly imported configuration is used upon the next system restart, and is already active after shutdown.

The configurations are not usually created manually, but by a so-called configurator, such as the one provided with the logger, PHÖNIX . (This tool includes no LAPI configuration though.)

Various logger configurators are currently in development, so the configuration description presented here is based on the current logger functionality. The configuration involved with CEUS is described in a separate document.

# i

All names and designations, such as units, tracks, comments, etc. should always be set in in single quotation marks, to avoid problems with special characters and blanks.

This manual distinguishes configuration parameters typographically by setting them in the typeface courier.

Do not include empty entries! If an entry is not required, you should delete the entire line, or comment it out by inserting the character # at the beginning of the line.



## 4.1.2 Configuration blocks

The logger configuration comprises groups of functions, each dealing with a coherent topic.

Group	Content
Generall options	global parameters
	comments
	track lists
Generall settings	CAN/LIN/FlexRay node settings data
	source definitions (CCP/XCP, KWP)
	Data transfer definitions (network and
	server), data set generation, file header
	and system state
Data sources	CAN/LIN/FlexRay/XCP/CCP/ADIO and
	GPS signals
	Computed signals (formulas)
	Internal signals (logger state)
Protocol	Special protocol services: KWP
Trigger	Starting/stopping methods
Scripts	Enhanced programming with scripts
Methods	time logs
	classing
	display output
	min./max. values
	traces (raw data recording)
	notifications
	gateway

Figure 6: The sections of a configuration

Within the configuration file, each group has its own section. The sections are marked by key terms. The sections are structured with a hierarchy similar to that of XML. It is not possible to randomly shift the blocks around within this structure.

For a detailed explanation of this structure, see the separate documentation<sup>1</sup>.

The entries are combined in blocks beginning with a key word, set in angular brackets. Preceded by a slash, the given word also marks the end of the block, which must always be explicitly stated. All words must be lowercase (!!).

Example of how such a block is written:

```
<key word>
parameter1=...
parameter2=...
parameter3=...
...
</key word>
```

<sup>1</sup>Description of the Configuration File for CAETEC datalogger ARCOS dL, µCROS, CAETEC GmbH



Blanks between parameters, equals signs and the assignment must be avoided, otherwise the line will not be completely read. Any specification of names and designations (signal names, names of methods, paths, comments, etc) should be set in single quotes () to avoid problems with such special characters as umlauts, hyphens and the like (a blank is considered a special character).

Example: name='Oil temperature'

## 4.1.3 Standard logger run behavior

The following paragraphs describe the procedure of a typical, simple logger run, to illustrate the standard behavior of the logger. The logger run extends from start to stop of the logger, including data transfer. In side notes, we shall point out possible variations in this standard behavior.

The logger is permanently connected to the supply voltage (V+ and GND) and is started with Clamp 15 (Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden). During the logger booting phase, the configured bus interface modules temporarily buffer any incoming bus messages. These are time-stamped the moment they arrive at the interface.

Once booting is completed and a track has been selected on the display screen (Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden and Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden), the running measurement values are displayed. However, the logger processes all the buffered data first (Backlog indicated by a clock symbol at the top of the display), before proceeding, without interruption, to live display (Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden).

As soon as data processing begins, the logger automatically starts a permanent recording in .atfx format (Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden). The record contains, at equal time intervals, the values of certain bus signals defined in the configuration (Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden, Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden, Fehler: Referenz nicht gefunden Fehler: den Fehler: Referenz nicht gefunden, Fehler: Referenz nicht gefundenff. Analog/Digital I/O), GPS values (Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden), as well as such internal values as logger runtime, bus load and error frame rate (Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden).

Pressing the display trigger key sets a display trigger (2.10.4.6 Setting Display Triggers), displaying it with its timestamp and trigger number, Simultaneously the associated internal trigger event 'trig\_display' would be initiated.

This can e.g. be used to trigger a data storage of a trace (raw bus data, Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden). The trace data is stored with pre and post triggers in e.g. Vector ASCII format, the data file name is automatically appended with the date and time of the trigger (Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden). The trigger event is recorded in the log file and in the trace file. Switching off Clamp 15 triggers the end of the logger run. Once Clamp 15 is switched off (Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden), the display immediately prompts whether the track is to be ended. If this is confirmed with yes, the current data set containing all the measurement files is closed. This is followed by a dialog prompt to specify the target medium for the data (Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden). After ten seconds, the default transfer path USB is selected. To establish connection, the logger searches for a USB stick prepared for data transfer, while the closed data set is compressed and finally transmitted (4 Data Transfer). Successful transfer is verified by computing a check sum on the storage medium and directly comparing it with the check sum made prior to transfer. Only then is the transmitted data deleted from the logger and memory space released for new measurements.

While the measured data is being transferred, the logger checks the USB stick for a new configuration file (4.4 Importing the Configuration to the Logger) or a firmware update file (5.3 Firmware Updates). If found, the new configuration is immediately activated, the update performed. Only then is the logger shut down and switched off.

The logger is now ready, possibly with a new configuration and/or updated firmware, for a new measurement.



## 4.1.4 Starting/Stopping the logger

As of 2015.02.0, 1.5.4 and 1.4.6: Only RX-messages keep the logger awake. This prevents that inappropriate setting of triggerconditions for messages on a WoX-channel keep the logger from sleeping. Caution: Errorframes (e.g. on CAN) will still keep the logger awake. Sending on a not scheduled Bus can also cause that the logger cannot go to sleep!

Once the logger is connected to the power supply, it can be started either by:

- hardware signal voltage (Clamp 15), or
- message on a bus, WoX, e.g., Wake on CAN (= WoC).

As soon as Clamp 15 occurs, the logger immediately (delay < 0.5 s) begins recording. During the booting phase, the logger firmware is not yet able to process values, so the messages are first buffered in the interfaces and then processed once booting is completed.

The option of starting with Clamp 15 is always available, regardless of whether bus channels are configured as WoX.

This option exists parallel to start by bus message (e.g., Wake on CAN = WoC). This behavior also supports emergency start-up ensuring there s always a way to safely start the logger (e.g., due to a configuration error, such as Start on a CAN message that never occurs).

If WoX is configured, the logger starts (just like with Clamp 15), as soon as a message (or the message/data defined in the configuration) is received on the activated channel.

Once the firmware is totally loaded, the buffered data (backlog) is processed. This is executed with full system performance (quicker than real time) and is usually finished within seconds. From this point on, the data is processed in real time under these system conditions the delay is at least three to approx. 20 minutes, depending on the data rate in the interfaces.

In the event that all the wake conditions are eliminated during a measurement, the system initiates a logger stop. In this context, it is irrelevant whether a wake condition was active at logger start-up or was activated later. In the case of channels with WoX, the requirement is that there be no received messages (or the defined message/data) on the particular channel for the bus timeout period (see Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden), i.e. for at least 10 seconds. This condition must be met on all the channels for which WoX is configured.

Once the configured post-runtime (Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden) has expired, the current data set is closed and data transfer is started (<sup>1.3</sup>providing this has been configured). Once data transfer has been completed, the logger shuts down.

<sup>1.3</sup>If the involved display dialog is still on the screen or data transfer is still in progress, and a wake condition is reactivated, this immediately starts a new measurement, initially in

the background. Once all the dialogs/the data transfer is finished, the screen returns to displaying a current measurement.

If all the start conditions are eliminated while the logger is still booting, then once the firmware is started, the data buffered up to this point (including any defined post-runtime) is processed and the logger is stopped (just as in a regular measurement). Since the state of Clamp 15 is not monitored until the firmware is running, the earliest point at which the logger can be stopped by an inactive Clamp 15 is when the firmware starts.

## 4.1.5 Persistence

en How long the value of defined bus signals and internal variables remains stored in the logger can vary. In a number of cases, standard behavior can be influenced by parameter persistence. The value is accordingly available for a longer or shorter period even without an update or re-computation.

The following table lists the standard behavior. The value is preserved until the given event occurs. For the various signals the start value of all values/variables is NaN (Not a Number); for trigger counters and classing methods it is 0.

Group	Content
Bus signals	none
Computed signals	none
Internal signals	none, unchangeable
GPS signals	none
Analog/Digital signals	none, unchangeable
Trigger (trigger counter)	end of data set
Display trigger (trigger	logger start
counter)	
Classing	end of data set

Figure 7: Standard persistence behavior



#### The persistence options are:

none	The value is preserved for the logger run. Even upon data transfer, the value is not reset, as long as the logger is not switched off or rebooted. Once the logger is switched off or restarted, or a new data set is begun, the values are initialized with the start value.
end of data set	The value is preserved until the end of the data set. Once the data set is closed (e.g., by End Track, a trigger or shutting down the logger), the value is reset and the new data set is begun with the reset value.
data transfer	The value is preserved until a data transfer is successfully comple- ted. If data transfer is being performed in parallel with a running measurement, then the value is reset as soon as data transfer is successfully completed. To avoid parallel access to the variable, the current measurement is briefly paused and then continued with the reset values (there is no data loss, only a brief increase in measurement delay).
config	The value is preserved until a new configuration file is installed. Once the logger restarts due to activation of a new configura- tion, the value is reset and the new data set is begun with the reset value.
ever	The value is preserved forever; it is only updated but not reset. To reset it, you must import a special update packet, which then resets all the persistences.

## 4.1.6 Bus channels/nodes

Due to the modular design of the logger, it can be run with a variable number of interface modules.

To make sure the various signals are unambiguously assigned to their respective channels (also known as nodes) in the interface module, you must assign each channel a number.

This step is a prerequisite for further configuration. All other node settings can then be made through the configuration file.

The assignment of a node number to the connection number in the interface so-called initialization must be performed upon installation of each interface module, with the aid of the (logger-integrated) Web interface. The procedure is described in the Chapter "Initializing the Modules" ( $\rightarrow$ 3.8.2).

The following text describes the various node parameters. Within the <settings> </settings> section of the configuration file, the node settings are first grouped according to the key word of the connection type <can>, , , or <flexray>. Then each node is bracketed by <canch> (stands for can channel), , , or <flexraych> (do not forget to close the bracket with the corresponding </...>!). This section is to specified individually for each node/channel being configured.



## 4.1.7 CAN channels

Due to its modular design, the logger can be equipped with a variable number of CAN interface modules.

Channel numbers are assigned to the CAN modules as described above, cf. chapter "Bus Channels/Nodes" ( $\rightarrow$ 4.1.6) and chapter "Initializing the Modules" ( $\rightarrow$ 3.8.2).

The following parameters for CAN channels are grouped within the configuration file, bracketed by the key words <canch> and </canch> (stands for CAN channel ).

## 4.1.8 LIN channels

Due to its modular design, the logger can be equipped with a variable number of LIN interface modules.

Channel numbers are assigned to the LIN modules as described above, cf. chapter "Bus Channels/Nodes" ( $\rightarrow$ 4.1.6) and chapter "Initializing the Modules" ( $\rightarrow$ 3.8.2).

The following parameters for LIN channels are grouped within the configuration file, bracketed by the key words <linch> and </linch> (stands for LIN channel ).

## 4.1.9 FlexRay channels<sup>1.3</sup>

Due to its modular design, the logger can be equipped with a variable number of FlexRay interface modules.

Channel numbers are assigned to the FlexRay modules as described above, cf. chapter "Bus Channels/Nodes" ( $\rightarrow$ 4.1.6) and chapter "Initializing the Modules" ( $\rightarrow$ 3.8.2).

The following parameters for FlexRay channels are grouped within the configuration file, bracketed by the key words <flexraych> and </flexraych> (stands for FlexRay channel ).



# 5 Data transfer

# 5.1 Basic information

Data transfer includes not only the transfer of measurement results from the logger to a storage medium, but also the transfer of a new configuration to the logger.

Since both data types are file-based, the same transfer channels are used for both types, even though they involve slightly different mechanisms and procedures.

One principle is that all data can be transmitted either over the WLAN or UMTS module in the upper chassis unit or via any USB interface (e.g., in the basic platform).

<sup>1.3</sup> The specific time for transfer via these interfaces is defined in the configuration (see Chapter Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden). If not further specified, it is always performed at the end of a measurement, when the logger is shut down. If configured accordingly, transfer can also be performed in parallel with a running measurement. Whenever, during the transfer process, a new configuration file is loaded, any running measurement is automatically ended, the logger is restarted and the new configuration activated.

<sup>1.3</sup> If the frequency of data transfer needs to be restricted, then this restriction can be defined for each individual transfer path either generally, by setting the parameter max\_occurrence, or only for measured data transfer, by means of the parameter max\_datatransfer. These restrictions can be overridden by individual transfer events. For details, see the description of the relevant parameters in Chapter Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden.

When data is transferred, only already closed data sets are transmitted. Depending on the configuration, this can also include the current data set, providing it is closed at this point for transfer (for more information, see Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden.

There is also the option of accessing the logger via Ethernet, by plugging an adapter cable into the display jack of the basic platform. However, this access requires detailed knowledge of the file structure, as well as login to the logger. This path should rather be reserved as a fallback solution for extraordinary circumstances.

For more information about operation, along with photographs of the screen output, see Chapter "Display" ( $\rightarrow$ 3.9).



# 5.2 General Transfer Procedure

The transfer steps are nearly identical for all transfer paths, with only small differences due to the requirements of the different transfer mediums.

When transfer is started (e.g., upon logger shutdown), if so configured, the display prompts selection of a transfer path.

Once the destination, i.e. a transfer path, has been selected, the logger attempts to establish connection. If this is successful, the logger searches the target for a new logger configuration. If found, it is first downloaded.

Next, the logger compresses the data sets located within the logger s internal main directory (<root>\home\datalog), in a directory whose name was formed out of the configured PathPrefix, the date of the measurement start, plus the track name (if there is no track name selected, xxx is appended as track name, if no track names are defined, then this part is omitted). Finally, a check sum is computed for the created file. Depending on the quantity of data, this can take several minutes. To prevent this process from exceeding the default timeouts, the parameters zipping and md5sum can be adjusted accordingly (see Fehler: Referenz nicht gefunden Fehler: Referenz nicht gefunden). Once packing is finished, the original measurement files are deleted.

At this point, the zip and log files are transmitted. If there is either insufficient memory or a loss of connection, the logger deletes only those zipped measurement files that were completely transmitted. The next time connection is established, the logger retries to transmit the data.

Once all the data sets have been completely transferred, the logger checks whether a firmware update packet is available for download and, if one is found, downloads it.

The transfer and its result (successful, or abort with error code) is recorded in the log file of the currently active data set, or else in the next one (the transmitted data sets being closed and thus unable to record any further log data).

In the case of transfers started at logger shutdown, once transfer is completed, the logger shuts down and switches off. In the process, any new configuration is already activated, and any new update is performed. So the next time the logger is started, it operates with the settings of the new configuration and/or updated firmware.

<sup>1.3</sup> When transfer is started during active measurement and the logger finds a new configuration, once transfer is completed, the logger automatically restarts, activating the new configuration.

This three-step order new configuration first, then data sets, then firmware update ideally ensures three things: that the logger always operates with the latest configuration, and measured data is transferred without delay; and, finally, that firmware is updated only when the transfer path is sufficiently stable.



# 5.3 Data transfer via USB

For data transfer from the logger you can use USB storage media, either so-called memory sticks or external USB hard drives.

However, target media are restricted to those containing a key that enables the logger to identify them. This is designed to prevent unauthorized read-out from the logger by random media. Moreover, the medium must be formatted with the file system FAT or FAT32.

At the USB port, memory sticks are the most common medium, so for simplicity sake the following text refers to a USB stick.

## 5.3.1 Preparation

To structure data storage, the logger configuration allows the specification of separate directories for configurations (cfgdir) and measured data (datadir). It is also necessary to ensure that a particular logger receive only the configuration designed for that logger. Therefore the logger looks for the configuration in a directory bearing the name of the front number of the logger, created as a subdirectory of the configuration directory.

The USB stick for data exchange with the logger must therefore be prepared as follows:

- The file datalog.key is copied into the root directory of the USB stick.
- Once the directory <cfgdir>\<front number of the logger>\is created in the root directory of the stick,
- if a new configuration is to also be transmitted, the file datalog.cfg is copied into the above directory.
- Finally, the directory <datadir> is created as configured.

#### Example

As specified in the logger configuration: The data directory is datadir=/test data. The configuration directory is cfgdir=/testkonfig, Front number of the logger = 42, The stick is to be recognized at the PC under the drive letter E: .

Zu erstellende Verzeichnisse: E:\test data\ E:\testkonfig\42\

Copy the file datalog.cfg (created for logger 42 !!!) into the directory E:\testkonfig\42\ kopieren.

## 5.3.2 Transfer procedure

Thus prepared, the stick is inserted into any logger USB interface (e.g., in the basic platform). This can take place at any time during operation as long as the logger is not booting or shutting down or even before the logger is switched on.

Changes and errors excepted.



Before proceeding, be sure to allow the logger enough time to recognize the USB stick (just as is required under Windows). This generally takes only a few seconds (< 10 s) (also indicated by a brief flicker of the activity LED at the stick).

If so configured, once transfer is started, USB is selected as the transfer destination. If a valid stick is recognized, the closed data sets are compressed by the logger, and a check sum is computed.

Finally the zip and log files are moved(!) to the stick i.e. once copying is finished, the logger directory for the measured data is empty.

If there is insufficient memory on the stick, transfer is interrupted, with an error message. Any files not completely transmitted remain on the logger.

If transfer was started upon logger shutdown, once the logger has switched off, the stick can be removed without risk.

<sup>1.3</sup> If transfer was started during an active measurement, the stick can be removed once the latter is completed, which is clearly indicated, either by the display, which returns to the normal screen; or by the LED at the stick, which goes from blinking to steady. If during the transfer process, a new configuration is found, the stick should not be removed until the logger has completely restarted and the new measurement is running.



# 5.4 Data transfer via WLAN/UMTS

For transfer via WLAN or UMTS, the basic mechanisms or steps are the same as for transfer via USB. Only the transfer medium is different.

## 5.4.1 Preparation

The data server where data is to be stored must have an operating SSH server, as described in Chapter Fehler: Referenz nicht gefunden. This server must also be able to compute md5 check sums.

Analog to the configuration of a USB stick, the directories for configurations (cfgdir) and measured data (datadir) specified in the logger configuration must be created on the server, as well as the subdirectory with the name of the front number. The datalog.cfg is then copied into the latter.

Since secure access is already provided by the used access log (SSH/SCP), there is no need for a datalog.key file on the server.

## 5.4.2 Transfer procedure

At the configured time (standard is upon logger shutdown), the logger tries to establish connection to the server.

Once connection has been successfully established and the logger has checked whether a new configuration is available, the closed data sets are packed and then transmitted. Once a data set is transferred, a check sum for the transmitted file (md5) is generated on the server and compared with the one on the logger. Only if these check sums match, confirming successful transfer, are the data on the logger deleted.

If the server runs out of memory or the connection is interrupted, data transfer ends and the check sums do no match. In this case, the data on the logger are not deleted.

Once the data sets are transferred, the logger checks to see if there is a new firmware update, and if it is found it is downloaded.

The transfer and its result (successful, or abort with an error code) is recorded in the log file.

Depending on the circumstances triggering data transfer, the logger then either shuts down and switches off, <sup>1.3</sup> continues measurement, or restarts in order to activate a new configuration.

# 5.5 Importing the configuration to the logger

A configuration is imported as part of measured data transfer, either via USB, WLAN or UMTS. At the beginning of data transfer the logger checks whether there is a new configuration available. If a new one is found, it is transmitted and imported by the logger. At the next start, the logger operates with this new configuration.

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The location where the logger searches for a configuration is defined in the configuration settings of the current configuration. If required, a selection dialog can be displayed prior to transfer of the configuration.

In special cases, a special display adapter cable can be plugged in instead of the display, thus creating a direct Ethernet connection for manually transmitting a configuration.

Whether the logger has read a configuration file is indicated by the file name datalog.cfg. If the file name found in the configuration directory is unchanged following transfer, then the new file has not been imported (wrong directory or wrong name). On the other hand, if the file is accepted, then the extension .cfg is appended with the import date.

Example: datalog.cfg\_20080114\_181327 read on 14.01.2008 at 18:13:27h

This not only prevents accidentally re-importing an old configuration, but also records in the logger the exact time of transfer.



# 5.6 Data transfer via LAN

KAPITEL MUSS LAUT STEFAN PROUSA NEU AUFGESETZT WERDEN. TERMIN MIT STEFAN PROSA MACHEN UND KAPITEL NACHREICHEN!!! SIEHE AUCH ODT KOMMENTAR

# 5.7 Filestructure of measurement data stored on the logger

The base directory for the file structure is the logger directory where the datalog.cfg file is stored: <root>\home\datalog.

Once a measurement is completed, the data is moved from the data buffer (cache) into a new data directory relative to the base directory datalog. The name of this data directory is made up of the prefix (see: dataLog configuration) followed by the date, time and track name.

This directory is where the logger stores the CFG file used for the measurement, as well as the ATFX file containing the description (header) of the stored data files, and the start/stop list (\*.SSL) and the minimum/maximum list (\*.MML). The actual measured data is located in the data subdirectory. A separate file is created for each method. The name is the name of the method from the configuration. The corresponding log file is stored parallel to the directory.

<sup>1.3</sup> This standard structure can be altered with the appropriate settings in the configuration. If no subdirectory data is used, all the files from a measurement are located directly in the data directory.



# 6 Service

# 6.1 Power outage

In the event of a power interruption during a running measurement, the logger-operating system is designed to ensure that the logger always properly restarts.

Since the data is buffered prior to being permanently stored in the file system, buffer loss due to power outage has the following consequences:

- Classing results are stored at 60-second intervals, i.e. up to 60 seconds of classing results can be lost.
- Time logs are directly stored. The operating system uses only a small writing buffer for this purpose. Any recording losses are within the seconds range.
- The ATFX header file is not written, since the measurement was not completed. This is done later, once the logger is restarted and the measurement properly ended.

In the event that a logger becomes inoperable, due to an accident during operation, for example, CAETEC can attempt to reconstruct the ATFX header, providing the card is still usable.

## 6.2 Fallback-behaviour

For emergencies the logger has a fallback configuration. This is fixed on the manufacturer side and does not include bus signals or logging methods. It is activated if the logger has not been correctly shutdown at the first 2 minutes of the last run. This can be caused by a faulty configuration that crashes the firmware, by a hardware defect or by the user who wants to put the system in a secure state (by disconnecting from the power supply), e.g. To enter a new configuration.

A modified configuration can be imported via USB. No user input is necessary. However, the changed configuration must be located on the USB stick in the subdirectory / fall-backcfg / <frontnumber>. This transmission path is independent of the configured data transmission. No measurement data are transmitted to the stick.

As of Version 1.3.0 the logger will automatically restart after running for 30 seconds in fallback-configuration. A modified configuration can applied via USB. No user input is necessary. The modified configuration has to be located on the USB-Stick in the subdirectory */fallbackcfg/<Serialnumber>*. This transfer method is independent from the configured data transfer. No measurement data will be transfered to the USB-Stick.

## 6.3 Firmware updates

The basic firmware update procedure is the same as for importing a new CFG file into the logger. The update can be performed via WLAN, UMTS or USB. The import of an update packet can coincide with that of a new configuration (.cfg).



With logger firmware version 1.0.0 and higher, the higher version can generally be imported without dealing with intermediate versions. To update lower versions, please contact CAETEC Support.

The name of the file containing the firmware update must be dlupdate.dlua; with firmware version 1.3.0 and above, only the attachment .dlua is mandatory, while the preceding name can be freely selected (e.g., dL\_1.3.1.dlua).

With this mechanism, downgrading from a high version number to a lower one is generally not possible.

If an update fails, the logger continues with the last valid firmware status. An update may also include updates for the display and the various bus interfaces. If these are not connected at the time of logger update, their update is performed at the next shutdown with connected display/interfaces.

The following preparations must be made:

- The current configuration must permit an End Track (either by display selection or by default).
- The datalog.key must be located in the root directory of the USB medium.
- A new firmware version must be copied into the directory where the logger also accepts CFG files.
- The valid configuration should be running (updating from an error situation should be avoided).

Update procedure:

- Switch on the logger and let it boot until it is in measurement operation.
- For update via USB: Connect the USB medium and wait until it is accepted (until the activity LED first lights up takes approx. 10 seconds.)
- Start data transfer (e.g., by shutting down the logger, depending on the configuration).
- During the data transfer process, the logger checks for a firmware update file. If a valid one is found, update begins. This is indicated in the display by the words in progress. If the display is also updated, then the background illumination is extinguished for the duration of the procedure. The procedure can take up to one to two minutes; the typical duration is < 30 s. Once the update process is completed, the logger restarts.

## Check

- After the update flash, the firmware version can be checked either via the display or the Web interface.
- After the flash, the extension of the firmware file is appended with the timestamp of the update.

## 6.4 Error codes, problems and suggested remedies

Error codes, signified by the combination letter - number , help identify the error:

i=initializiation

Letter:

t=transfer

Number:

Consecutive number with a specific meaning described in the following tables. (The numbers do not always have the same meaning for WLAN, USB and PPP).

Error number	Description
i-1	Either a file on the logger cannot be
	opened for transfer or an SSH-error
	occurred (e.g. timeout)
i-2	WLAN hardware not recognized
i-3	Target-directory for file could not be cre-
	ated
i-4	No WLAN connection possible
i-5	Internal error
i-6	Internal error
i-7	Internal error
i-8	Error in dynamic allocation of IP address
i-9	Error in setting the configured static IP
	address
i-18	Datatransfer initialisation failed with
	DHCP-error
i-53	Target-directory for MD5 could not be
	created

## 6.4.1 Error codes - WLAN

Figure 8: WLAN initialization errors.



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Error number	Description
i-11	Internal error
i-12	Error in TCP Connect (Note: Do not use
	subnet 192.168.1.xxx or 203.0.113.xxx)
i-13	Error in initializing an SSH session
i-14	Error in opening an SSH session
i-15	SSH server provides no usable authenti-
	cation method
i-16	SSH server authentication attempt fai-
	led (e.g., incorrect password)

Figure 9: WLAN SSH connection errors.

Error number	Description
t-11	Error in opening the internal source file
t-12	Error in creating the target file on the
	SSH server (no SCP log support on ser-
	ver, path does not exist, storage me-
	dium full,)
t-21	Error during transfer of target file to SSH
	server (storage medium full full,)

Figure 10: WLAN data transfer errors

## 6.4.2 Error codes - USB

Error number	Descriptio	on	
i-1	USB	storage	medium
	(stick/disk	<th>und</th>	und
i-2	USB stora	ge medium not c	iuthorized

Figure 11: USB initialization errors

Error number	Description
t-11	Error in opening the internal source file
t-12	Error creating the target file on the USB stick (path does not exist, data storage medium full, )
t-21	Error transferring the target file to the USB stick (data storage medium full, )

Figure 12: USB data transfer errors



## 6.4.3 Error codes - PPP

Error number	Description
i-3	Error in section <ppp> <peer> of the cfg</peer></ppp>
i-4	Modem not found
i-9	Connection failed

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Figure 13: PPP initialization errors

Error number	Description
i-11	Internal error
i-12	Error in TCP Connect (Note: Do not use subnet 192.168.1.xxx or 203.0.113.xxx)
i-13	Error in initializing an SSH session
i-14	Error in opening an SSH session
i-15	SSH server provides no usable authenti- cation method
i-16	SSH server authentication attempt fai- led (e.g., incorrect password)
i-18	SSH-Timeout (e.g. no connection or no prepaid credit available)

Figure 14: PPP SSH connection errors.

Error number	Description
t-11	Error in opening the internal source file
t-12	Error in creating the target file on the SSH server (no SCP log support on ser- ver, path does not exist, storage me- dium full,)
t-21	Error during transfer of target file to SSH server (storage medium full full,)
t-98	MD5 checksum failed 5x

Figure 15: PPP data transfer errors



## 6.4.4 Error codes XCP LAPI

Error number	Description
Errors (hexadecimal) upon initialization have the (right-most) bit	
with index 0 as the LSB, and the indexes linearly ascending (to	
the left) to the MSB. Error code is written to the log file, behind	
the string "Parameterization failed with error code".	
Bit 0 is set	SET_MTA or DOWNLOAD of data failed
Bit 1 is set	USER_CMD (active) failed
Bit 2 is set	USER_CMD (deactivated) failed
Bit 3 is set	CONNECT failed
Bit 4 is set	DISCONNECT failed

Figure 16: XCP LAPI parameterization errors.

## 6.4.5 Problems and suggested remedies

Problem	Possible remedy
Logger starts unex- pectedly.	The input wire for start on preset voltage (Clamp 15) has a very high impedance. Ambient disturbance can start the log- ger. Proper wiring of the potential on the pin is recommended.
Signals on the CAN channel, but green LED is not lit.	Wrong baud rate of CAN signals. Check setting.
No signals in the display, only the start screen, with three dots.	No signals configured for output to dis- play. Check configuration for errors (upper/lower-casing or omissions) Old display firmware (lower than 1.05) used with new logger firmware (1.3.x and higher). Unplug and re-plug dis- play, update firmware.

Figure 17: Problems with suggested remedies